

Cortex-A5™ MPCore™

Revision: r0p1

Technical Reference Manual



Cortex-A5 MPCore

Technical Reference Manual

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Release Information

The following changes have been made to this book.

Change history

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Preface

This preface introduces the *Cortex-A5 MPCore Technical Reference Manual*. It contains the following sections:

- *About this book* on page xv
- *Feedback* on page xix.

About this book

This book is for the Cortex-A5 MPCore processor. A Cortex-A5 MPCore includes between one and four Cortex-A5 processors.

Product revision status

The *rnpn* identifier indicates the revision status of the product described in this book, where:

- rn** Identifies the major revision of the product.
- pn** Identifies the minor revision or modification status of the product.

Intended audience

This book is written for hardware and software engineers implementing Cortex-A5 MPCore system designs. It provides information that enables designers to integrate the MPCore processor into a target system.

Using this book

This book is organized into the following chapters:

Chapter 1 *Introduction*

Read this for an introduction to the processor and descriptions of the major functional blocks.

Chapter 2 *Functional Description*

Read this for a description of the functionality of the processor.

Chapter 3 *Programmers Model*

Read this for a description of the registers and programming details.

Chapter 4 *System Control*

Read this for a description of the system registers and programming details.

Chapter 5 *Non-debug Use of CP14*

Read this for a description of the CP14 coprocessor and its non-debug uses.

Chapter 6 *Memory Management Unit*

Read this for a description of the *Memory Management Unit* (MMU) and the address translation process.

Chapter 7 *Level 1 Memory System*

Read this for a description of the *Level 1* (L1) memory system, including caches, *Translation Lookaside Buffers* (TLB), and store buffer.

Chapter 8 *Level 2 Memory Interface*

Read this for a description of the *Level 2* (L2) memory interface and the AXI interface attributes.

Chapter 9 *Snoop Control Unit*

Read this for a description of the *Snoop Control Unit* (SCU).

Chapter 10 *Interrupt Controller*

Read this for a description of the Interrupt Controller.

Chapter 11 Debug

Read this for a description of the Cortex-A5 MPCore support for debug.

Chapter 12 Performance Monitoring Unit

Read this for a description of the Cortex-A5 MPCore *Performance Monitoring Unit* (PMU) and associated events.

Appendix A Signal Descriptions

Read this for a description of the signals.

Appendix B Revisions

Read this for a description of technical changes in this document.

Glossary Read this for definitions of terms used in this book.

Conventions

Conventions that this book can use are described in:

- *Typographical*
- *Timing diagrams*
- *Signals* on page xvii.

Typographical

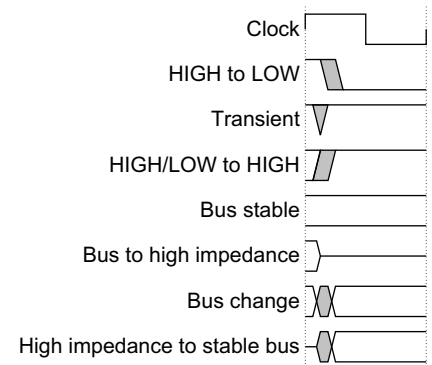
The typographical conventions are:

<i>italic</i>	Highlights important notes, introduces special terminology, denotes internal cross-references, and citations.
bold	Highlights interface elements, such as menu names. Denotes signal names. Also used for terms in descriptive lists, where appropriate.
monospace	Denotes text that you can enter at the keyboard, such as commands, file and program names, and source code.
<u>monospace</u>	Denotes a permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.
<i>monospace italic</i>	Denotes arguments to monospace text where the argument is to be replaced by a specific value.
monospace bold	Denotes language keywords when used outside example code.
< and >	Enclose replaceable terms for assembler syntax where they appear in code or code fragments. For example: MRC p15, 0 <Rd>, <CRn>, <CRm>, <Opcode_2>

Timing diagrams

The figure named *Key to timing diagram conventions* on page xvii explains the components used in timing diagrams. Variations, when they occur, have clear labels. You must not assume any timing information that is not explicit in the diagrams.

Shaded bus and signal areas are undefined, so the bus or signal can assume any value within the shaded area at that time. The actual level is unimportant and does not affect normal operation.



Key to timing diagram conventions

Signals

The signal conventions are:

Signal level The level of an asserted signal depends on whether the signal is active-HIGH or active-LOW. Asserted means:

- HIGH for active-HIGH signals
- LOW for active-LOW signals.

Lower-case n At the start or end of a signal name denotes an active-LOW signal.

Additional reading

This section lists publications by ARM and by third parties.

See Infocenter, <http://infocenter.arm.com>, for access to ARM documentation.

ARM publications

This book contains information that is specific to this product. See the following documents for other relevant information:

- *Cortex-A5 Supplementary Datasheet* (ARM DDI 0448)
- *Cortex-A5 Floating-Point Unit (FPU) Technical Reference Manual* (ARM DDI 0449)
- *Cortex-A5 NEON Media Processing Engine Technical Reference Manual* (ARM DDI 0450)
- *Cortex-A5 MPCore Configuration and Sign-Off Guide* (ARM DII 0243)
- *Cortex-A5 MPCore Integration Manual* (ARM DIT 0015)
- *Cortex-A5 Technical Reference Manual* (ARM DDI 0433)
- *ARM Architecture Reference Manual, ARMv7-A and ARMv7-R edition* (ARM DDI 0406)
- *ARM Architecture Reference Manual Performance Monitors v2 Supplement* (ARM DDI 0457)
- *CoreSight ETM™-A5 Technical Reference Manual* (ARM DDI 0435)
- *CoreSight ETM-A5 Configuration and Sign-Off Guide* (ARM DII 0212)
- *CoreSight ETM-A5 Integration Manual* (ARM DIT 0002)

- *CoreSight Design Kit for Cortex-A5 Integration Manual* (ARM DIT 0003)
- *CoreSight Embedded Trace Macrocell v3.5 Architecture Specification* (ARM IHI 0014)
- *PrimeCell Level 2 Cache Controller (PL310) Technical Reference Manual* (ARM DDI 0246)
- *AMBA® AXI Protocol v1.0 Specification* (ARM IHI 0022)
- *ARM Generic Interrupt Controller Architecture Specification* (ARM IHI 0048)
- *RealView ICE User Guide* (ARM DUI 0155)
- *Intelligent Energy Controller Technical Overview* (ARM DTO 0005)
- *CoreSight Architecture Specification* (ARM IHI 0029)
- *CoreSight Technology System Design Guide* (ARM DGI 0012)
- *Cortex-A5 MPCore Release Note* (MP008-DC-06003)
- *Cortex-A5 Floating-Point Unit (FPU) Release Note* (AT551-DC-06001)
- *Cortex-A5 NEON Media Processing Engine Release Note* (AT552-DC-06001).

Other publications

This section lists relevant documents published by third parties:

- *ANSI/IEEE Std 754-2008, IEEE Standard for Binary Floating-Point Arithmetic.*
- *IEEE Std. 1500-2005, IEEE Standard Testability Method for Embedded Core-based Integrated Circuits.*

Feedback

ARM welcomes feedback on this product and its documentation.

Feedback on this product

If you have any comments or suggestions about this product, contact your supplier and give:

- The product name.
- The product revision or version.
- An explanation with as much information as you can provide. Include symptoms and diagnostic procedures if appropriate.

Feedback on content

If you have comments on content then send an e-mail to errata@arm.com. Give:

- the title
- the number, ARM DDI 0434B
- the page numbers to which your comments apply
- a concise explanation of your comments.

ARM also welcomes general suggestions for additions and improvements.

Chapter 1

Introduction

This chapter introduces the processor and its features. It contains the following sections:

- *About the Cortex-A5 MPCore processor* on page 1-2
- *Variants* on page 1-4
- *Compliance* on page 1-5
- *Features* on page 1-6
- *Interfaces* on page 1-7
- *Configurable options* on page 1-8
- *Test features* on page 1-9
- *Product documentation, design flow, and architecture* on page 1-10
- *Product revisions* on page 1-13.

1.1 About the Cortex-A5 MPCore processor

The Cortex-A5 MPCore processor is a high-performance, low-power, ARM macrocell with an L1 cache subsystem that provides full virtual memory capabilities. Up to four individual cores can be linked in a cache-coherent cluster, under the control of a *Snoop Control Unit* (SCU), that maintains L1 data cache coherency for memory marked as shared. The Cortex-A5 MPCore processor implements the ARMv7 architecture and runs 32-bit ARM instructions, 16-bit and 32-bit Thumb instructions, and 8-bit Java™ bytecodes in Jazelle state.

The Cortex-A5 MPCore processor consists of:

- up to four Cortex-A5 cores
- an SCU responsible for maintaining coherency among L1 data caches
- an *Interrupt Controller* (IC) with support for legacy ARM interrupts
- a private timer and a private watchdog per processor
- a global timer
- one or two AXI high-speed *Advanced Microprocessor Bus Architecture* (AMBA) L2 interfaces.
- an *Acceleration Coherency Port* (ACP), an optional AXI 64-bit slave port that can be connected to a noncached peripheral such as a DMA engine.

It is possible to implement only one Cortex-A5 processor in a Cortex-A5 MPCore processor design. In this configuration, the SCU is still provided. The ACP, and the additional master port, are also available in this configuration.

1.1.1 Floating-Point Unit

The *Floating-Point Unit* (FPU) supports the ARMv7 VFPv4-D16 architecture without Advanced SIMD extensions (NEON). It is tightly integrated to the Cortex-A5 processor pipeline. It provides trapless execution and is optimized for scalar operation. It can generate an Undefined instruction exception on vector instructions that enables the programmer to emulate vector capability in software.

The design can include the FPU only, in which case the *Media Processing Engine* (MPE) is not included.

See the *Cortex-A5 Floating-Point Unit Technical Reference Manual*.

1.1.2 Media Processing Engine

The MPE implements ARM NEON technology, a media and signal processing architecture that adds instructions targeted at audio, video, 3-D graphics, image, and speech processing. Advanced SIMD instructions are available in both ARM and Thumb states.

If the design includes the MPE, the FPU is included.

See the *Cortex-A5 NEON Media Processing Engine Technical Reference Manual*.

1.1.3 System design components

This section describes the peripheral components used in Cortex-A5 MPCore designs:

- *Generic Interrupt Controller* on page 1-3
- *PrimeCell Level 2 Cache Controller (PL310)* on page 1-3.

Generic Interrupt Controller

The Cortex-A5 MPCore Interrupt Controller and the PrimeCell Generic Interrupt Controller (PL390) share the same programmers model. There are implementation-specific differences.

PrimeCell Level 2 Cache Controller (PL310)

The addition of an on-chip secondary cache, also referred to as a Level 2 or L2 cache, is a recognized method of improving the performance of ARM-based systems when significant memory traffic is generated by the processor. The PrimeCell Level 2 Cache Controller reduces the number of external memory accesses and has been optimized for use with the Cortex-A5 MPCore processor.

1.2 Variants

The Cortex-A5 processor is available as an MPCore multiprocessor, as described in this manual, or a uniprocessor, as described in the *Cortex-A5 Technical Reference Manual*.

1.3 Compliance

The Cortex-A5 MPCore processor implements the ARMv7-A architecture and includes the following features:

- Thumb[®]-2 technology for overall code density comparable with Thumb and performance comparable with ARM instructions. See the *ARM Architecture Reference Manual* for details of both the ARM and Thumb instruction sets.
- *Thumb Execution Environment* (ThumbEE) architecture to enable execution environment acceleration. See the *ARM Architecture Reference Manual* for details of the ThumbEE instruction set.
- TrustZone[®] technology for enhanced security. See *Security Extensions overview* on page 3-10. See the *ARM Architecture Reference Manual* for details on how TrustZone works in the architecture.
- NEON[®] technology to accelerate the performance of multimedia applications such as 3-D graphics and image processing. See the *ARM Architecture Reference Manual* for details of the NEON technology.
See the *Cortex-A5 NEON Media Processing Engine Technical Reference Manual* for implementation-specific information.
- *Vector Floating-Point v4* (VFPv4) architecture for floating-point computation that is compliant with the IEEE 754 standard. See the *ARM Architecture Reference Manual* for details of the VFPv4 subarchitecture.
See the *Cortex-A5 Floating-Point Unit Technical Reference Manual* for implementation-specific information.
- The processor implements the ARMv7 Debug architecture that includes support for TrustZone and CoreSight. The Cortex-A5 MPCore processor implements both Baseline CP14 and Extended CP14 debug access. To get full access to the processor debug capability, you can access the debug register map through the APB slave port. See Chapter 11 *Debug* for more information.

1.4 Features

The Cortex-A5 MPCore processor features are:

- in-order pipeline with dynamic branch prediction
- ARM, Thumb, and ThumbEE instruction set support
- TrustZone security extensions
- Harvard level 1 memory system with a *Memory Management Unit* (MMU)
- 64-bit AXI master interface with one or two buses
- ARM v7 debug architecture
- trace support through an *Embedded Trace Macrocell* (ETM) interface
- *Intelligent Energy Manager* (IEM) support with
 - asynchronous AXI wrappers
 - three voltage domains
- optional VFPv4-D16 FPU with trapless execution
- optional *Media Processing Engine* (MPE) with NEON technology
- optional Jazelle hardware acceleration.

1.5 Interfaces

The Cortex-A5 MPCore processor has the following external interfaces:

- AMBA AXI interfaces
- APB CoreSight interface
- ETM interface
- *Design for Test (DFT) interface.*

See the following for more information on these interfaces:

- *AMBA AXI Protocol Specification*
- *CoreSight Architecture Specification*
- *CoreSight Embedded Trace Macrocell v3.5 Architecture Specification.*

1.6 Configurable options

Table 1-1 shows the Cortex-A5 MPCore RTL configurable options.

Table 1-1 Configurable options for the Cortex-A5 MPCore

Feature	Range of options	Default value
Processor-level configuration options:^a		
Instruction cache size	4KB, 8KB, 16KB, 32KB, or 64KB	Implementation dependent
Data cache size	4KB, 8KB, 16KB, 32KB, or 64KB	Implementation dependent
Floating Point Unit or Media Processing Engine (NEON)	None, VFPv4-D16, or VFPv4 and NEON	Not included
Jazelle Architecture Extension	Full or trivial	Trivial
Global configuration options:		
SCU AMBA AXI secondary master interface	Included or not	Included
SCU AMBA AXI ACP slave interface	Included or not	Included
SCU GIC interrupt sources	0-224 in steps of 32	32

a. These options can be configured independently for each core in the Cortex-A5 MPCore.

1.7 Test features

The Cortex-A5 MPCore processor is delivered as fully-synthesizable RTL and is a fully-static design. Scan-chains and test wrappers for production test can be inserted into the design by the synthesis tools during implementation. See the relevant reference methodology documentation for more information.

Production test of the processor cache and TLB RAMs can be performed through a dedicated MBIST interface. See the *Cortex-A5 MPCore Integration Manual* for more information about this interface, and how to control it.

1.8 Product documentation, design flow, and architecture

This section describes the Cortex-A5 MPCore books, how they relate to the design flow, and the relevant architectural standards and protocols.

See *Additional reading* on page xvii for more information about the books described in this section.

1.8.1 Documentation

The Cortex-A5 MPCore documentation is as follows:

Technical Reference Manual

The *Technical Reference Manual* (TRM) describes the functionality and the effects of functional options on the behavior of the Cortex-A5 MPCore processor. It is required at all stages of the design flow. Some behavior described in the TRM might not be relevant because of the way that the Cortex-A5 MPCore processor is implemented and integrated.

If you are programming the Cortex-A5 MPCore processor then contact:

- the implementer to determine the build configuration of the implementation
- the integrator to determine the pin configuration of the SoC that you are using.

Configuration and Sign-Off Guide

The *Configuration and Sign-Off Guide* (CSG) describes:

- the available build configuration options and related issues in selecting them
- how to configure the *Register Transfer Level* (RTL) description with the build configuration options
- the processes to sign off the configured design.

The ARM product deliverables include reference scripts and information about using them to implement your design. Reference methodology documentation from your EDA tools vendor complements the CSG.

The CSG is a confidential book that is only available to licensees.

Integration Manual

The *Integration Manual* (IM) describes how to integrate the Cortex-A5 MPCore processor into a SoC. It includes a description of the pins that the integrator must tie off to configure the macrocell for the required integration. Some of the integration is affected by the configuration options used when implementing the Cortex-A5 MPCore processor.

The IM is a confidential book that is only available to licensees.

1.8.2 Design flow

The processor is delivered as synthesizable RTL. Before it can be used in a product, it must go through the following process:

1. Implementation. The implementer configures and synthesizes the RTL to produce a hard macrocell. If appropriate, this includes integrating the RAMs into the design.
2. Integration. The integrator connects the implemented design into a SoC. This includes connecting it to a memory system and peripherals.

3. Programming. The system programmer develops the software required to configure and initialize the processor, and tests the required application software.

Each stage of the process:

- can be performed by a different party
- can include options that affect the behavior and features at the next stage:

Build configuration

The implementer chooses the options that affect how the RTL source files are pre-processed. They usually include or exclude logic that can affect the area or maximum frequency of the resulting macrocell.

Configuration inputs

The integrator configures some features of the processor by tying inputs to specific values. These configurations affect the start-up behavior before any software configuration is made. They can also limit the options available to the software.

Software configuration

The programmer configures the processor by programming particular values into software-visible registers. This affects the behavior of the processor.

Note

This manual refers to implementation-defined features that are applicable to build configuration options. References to a feature that is included mean that the appropriate build and pin configuration options have been selected, while references to an enabled feature mean one that has also been configured by software.

1.8.3 Architecture and protocol information

The Cortex-A5 MPCore processor complies with, or implements, the specifications described in:

- *ARM architecture*
- *Interrupt controller architecture*
- *Trace macrocell*
- *Advanced Microcontroller Bus Architecture* on page 1-12.

This TRM complements architecture reference manuals, architecture specifications, protocol specifications, and relevant external standards. It does not duplicate information from these sources.

ARM architecture

The Cortex-A5 MPCore processor implements the ARMv7-A architecture profile. See *ARM Architecture Reference Manual, ARMv7-A and ARMv7-R edition*.

Interrupt controller architecture

The Cortex-A5 MPCore processor implements Architecture version 1.0 of the ARM Generic Interrupt Controller architecture profile. See *ARM Generic Interrupt Controller Architecture Specification*.

Trace macrocell

The Cortex-A5 MPCore processor implements ETM architecture version 3.5. See *CoreSight Embedded Trace Macrocell v3.5 Architecture Specification*.

Advanced Microcontroller Bus Architecture

The Cortex-A5 MPCore processor complies with the AMBA 3 protocol. See *AMBA AXI Protocol v1.0 Specification* and *AMBA 3 APB Protocol Specification*.

1.9 Product revisions

This section describes the differences in functionality between product revisions:

r0p0 First release.

r0p0-r0p1 SCU dynamic clock gating added.

Chapter 2

Functional Description

This chapter describes the functionality of the Cortex-A5 MPCore processor. It contains the following sections:

- *About the functions* on page 2-2
- *Interfaces* on page 2-9
- *Clocking and resets* on page 2-11
- *Power management* on page 2-13
- *Multiprocessor bring-up* on page 2-19.

2.1 About the functions

Figure 2-1 shows an example block diagram of a Cortex-A5 MPCore implementation with four Cortex-A5 CPU cores.

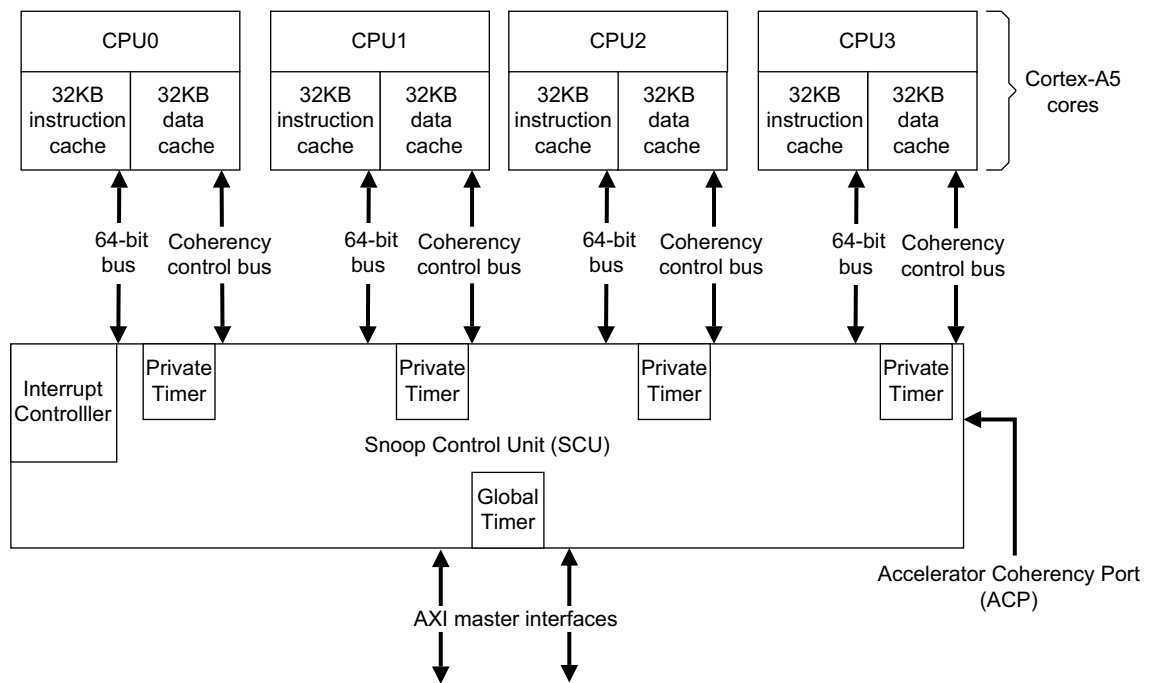


Figure 2-1 Example Cortex-A5 MPCore configuration

By default, at reset all the cores in the processor are configured in *Asymmetric MultiProcessing* (AMP) mode. All normal memory marked as shared is treated as non-cacheable independent of its cache attributes.

Individual cores can be switched from AMP to *Symmetric MultiProcessing* (SMP) mode, where shared cacheable D-side data is coherently maintained across all participating cores by:

- setting the appropriate bit in the *Auxiliary Control Register* on page 4-42
- writing to the *SCU Control Register* on page 9-7 to turn the SCU on
- setting to Normal power mode in the *SCU CPU Power Status Register* on page 9-9.

The current MPCore configuration for the processor is reflected in the memory-mapped *SCU Configuration Register* on page 9-8 and in the external signal **SMPnAMP[3:0]**. Each bit indicates whether the appropriate core is currently configured as SMP or AMP.

Figure 2-2 on page 2-3 shows a top-level functional diagram of one of the Cortex-A5 cores in a Cortex-A5MPCore processor.

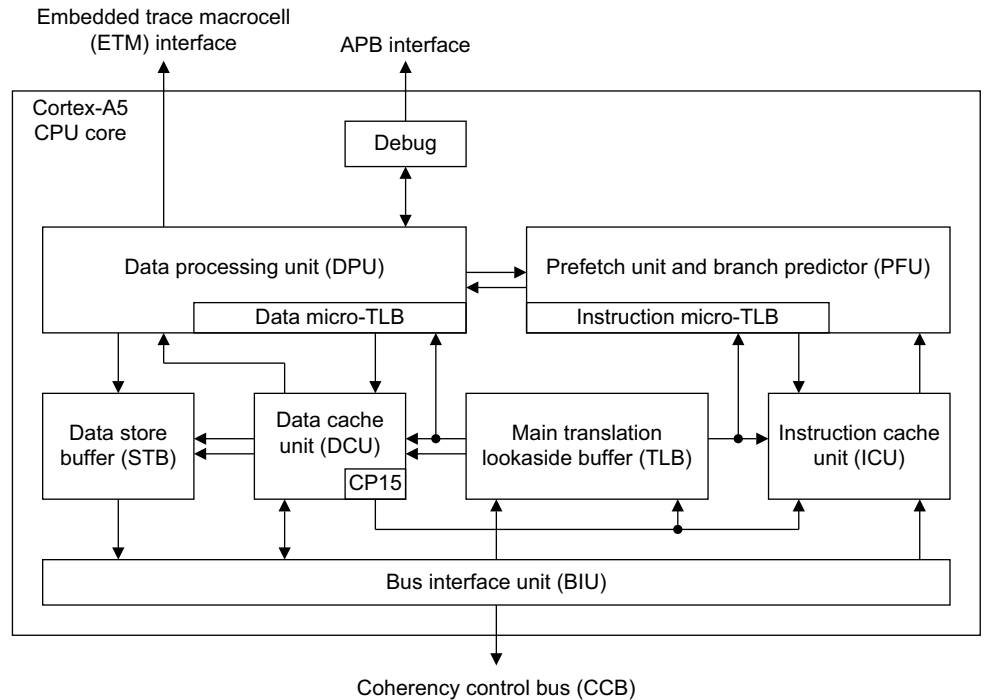


Figure 2-2 Cortex-A5 CPU core top-level diagram

The following sections describe the blocks and their functions:

- *Data Processing Unit*
- *System control coprocessor*
- *Instruction side memory system* on page 2-4
- *Data side memory system* on page 2-4
- *L1 memory system* on page 2-6
- *Media Processing Engine* on page 2-6
- *Floating-Point Unit* on page 2-7
- *Snoop Control Unit* on page 2-7
- *Debug* on page 2-7
- *Performance monitoring* on page 2-7
- *Virtualization extensions* on page 2-8.

2.1.1 Data Processing Unit

The *Data Processing Unit* (DPU) holds most of the program-visible state of the processor, such as general-purpose registers, status registers and control registers. It decodes and executes instructions, operating on data held in the registers in accordance with the ARM Architecture. Instructions are fed to the DPU from the *Prefetch Unit* (PFU). The DPU performs instructions that require data to be transferred to or from the memory system by interfacing to the *Data Cache Unit* (DCU), which manages all load and store operations. See Chapter 3 *Programmers Model* for more information.

2.1.2 System control coprocessor

The system control coprocessor, CP15, provides configuration and control of the memory system and its associated functionality.

See Chapter 4 *System Control* for more information.

2.1.3 Instruction side memory system

The instruction side memory system is described in:

- *Instruction Cache Unit*
- *Prefetch Unit*.

Instruction Cache Unit

The *Instruction Cache Unit* (ICU) contains the Instruction Cache controller and its associated linefill buffer. The Cortex-A5 MPCore ICache is two-way set associative and uses *Virtually Indexed Physically Tagged* (VIPT) cache-lines holding up to eight ARM or up to sixteen Thumb instructions.

Prefetch Unit

The *Prefetch Unit* (PFU) obtains instructions from the instruction cache or from external memory and predicts the outcome of branches in the instruction stream, then passes the instructions to the DPU for processing. In any given cycle, up to a maximum of four instructions can be fetched and two can be passed to the DPU.

Branch Target Address Cache

The PFU also contains a small four-entry deep *Branch Target Address Cache* (BTAC) used to predict the target address of certain indirect branches. The BTAC implementation is architecturally transparent, so it does not have to be flushed on a context switch.

Branch prediction

The branch predictor is a global type that uses history registers and a 256-entry pattern history table.

Return stack

The PFU includes a 4-entry return stack to accelerate returns from procedure calls. For each procedure call, the return address is pushed onto a hardware stack. When a procedure return is recognized, the address held in the return stack is popped, and the PFU uses it as the predicted return address. The return stack is architecturally transparent, so it does not have to be flushed on a context switch.

2.1.4 Data side memory system

The data side memory system is described in:

- *Data Cache Unit*
- *Store Buffer* on page 2-6
- *Bus Interface Unit and SCU interface* on page 2-6.

Data Cache Unit

The *Data Cache Unit* (DCU) consists of the following sub-blocks:

- The *Level 1* (L1) data cache controller, which generates the control signals for the associated embedded tag, data, and dirty memory (RAMs) and arbitrates between the different sources requesting access to the memory resources. The data cache is 4-way set associative and uses a *Physically Indexed Physically Tagged* (PIPT) scheme for lookup which enables unambiguous address management in the system.
- The load/store pipeline which interfaces with the DPU and main TLB.

- The system coprocessor (CP15) controller which performs cache maintenance operations directly on the data cache and indirectly on the instruction cache through an interface with the ICU.
- The *Coherency Control Bus* (CCB) interface which receives requests from the *Snoop Control Unit* (SCU), and accesses the data cache to fulfil them.

The DCU contains a combined local and global exclusive monitor. This monitor can be set to the exclusive state only by a LDREX instruction executing on the local processor, and can be cleared to the open access state by a STREX instruction on the local processor or a store to the same shared cache line on another processor, or by the cache line being evicted for other reasons.

The Cortex-A5 MPCore uses the MOESI protocol to maintain data coherency between multiple cores. MOESI describes the state that a shareable line in a level-1 D-cache can be in:

M	Modified. The line is only in this cache and is dirty.
O	Owned. The line is possibly in more than one cache and is dirty.
E	Exclusive. The line is only in this cache and is clean.
S	Shared. The line is possibly in more than one cache and is clean.
I	Invalid. The line is not in this cache.

The DCU stores the MOESI state of the cache line in the Tag and Dirty RAMs.

Data cache operation is described in:

- *Read allocate mode*
- *Data cache invalidate on reset.*

Read allocate mode

The Cortex-A5 MPCore data cache only supports a write-back policy. It normally allocates a cache line on either a read miss or a write miss. However, there are some situations where allocating on writes is undesirable, such as executing the C standard library memset() function to clear a large block of memory to a known value. Writing large blocks of data like this can pollute the cache with unnecessary data. It can also waste power and performance if a linefill must be performed only to discard the linefill data because the entire line was subsequently written by the memset().

To prevent this, the *Bus Interface Unit* (BIU) includes logic to detect when a full cache line has been written by the core before the linefill has completed. If this situation is detected on three consecutive linefills, it switches into read allocate mode. When in read allocate mode, loads behave as normal and can still cause linefills, and writes still lookup in the cache but, if they miss, they write out to L2 rather than starting a linefill.

The BIU continues in read allocate mode until it detects either a cacheable write burst to L2 that is not a full cache line, or there is a load to the same line as is currently being written to L2.

Data cache invalidate on reset

The ARMv7 *Virtual Memory System Architecture* (VMSA) does not support a CP15 operation to invalidate the entire data cache. If this function is required in software, it must be constructed by iterating over the cache geometry and executing a series of individual CP15 invalidate by set/way instructions.

In normal usage the only time the entire data cache has to be invalidated is on reset. The Cortex-A5 MPCore processor provides this functionality by default. If it is not required on reset, for example when leaving dormant mode, the invalidate operation can be disabled by asserting and holding the appropriate external **L1RSTDISABLE** signal for a core when the corresponding reset signal is deasserted.

In parallel to the data cache invalidate, the DCU also sends an invalidate-all request to the ICU and the TLB, unless **LIRSTDISABLE** is asserted.

Store Buffer

The *Store Buffer* (STB) holds store operations when they have left the load/store pipeline and have been committed by the DPU. From the STB, a store can request access to the cache RAMs in the DCU, request the BIU to initiate linefills, or request the BIU to write the data out on the external write channel. External data writes are through the SCU.

The STB can merge several store transactions into a single transaction if they are to the same 64-bit aligned address. The STB is also used to queue up CP15 maintenance operations before they are broadcast to other cores in the processor.

Bus Interface Unit and SCU interface

The *Bus Interface Unit* (BIU) contains the SCU interface and various buffers to decouple the interface from the cache and STB. The BIU interface and the SCU always operate at the core frequency. Additional clocking modes are available through the SCU AMBA master interfaces.

There is a write buffer that is used to hold data from cache evictions or non-cacheable write bursts before they are written out on the SCU interface.

2.1.5 L1 memory system

The processor L1 memory system includes the following features:

- separate instruction and data caches
- export of memory attributes for L2 memory system.

The caches have the following features:

- Support for independent configuration of the instruction and data cache sizes between 4KB and 64KB.
- Pseudo-random cache replacement policy.
- Ability to disable each cache independently.
- Streaming of sequential data from LDM and LDRD operations, and sequential instruction fetches.
- Critical word first filling of the cache on a cache miss.
- Implementation of all the cache RAM blocks and the associated tag and valid RAM blocks using standard ASIC RAM compilers.

See Chapter 7 *Level 1 Memory System* for more information.

2.1.6 Media Processing Engine

The optional *Media Processing Engine* (MPE) implements ARM NEON technology, a media and signal processing architecture that adds instructions targeted at audio, video, 3-D graphics, image, and speech processing. Advanced SIMD instructions are available in both ARM and Thumb states.

See the *Cortex-A5 NEON Media Processing Engine Technical Reference Manual* for more information.

2.1.7 Floating-Point Unit

The optional *Floating-Point Unit* (FPU) implements the ARMv7 VFPv4-D16 architecture and includes the VFP register file and status registers. It performs floating-point operations on the data held in the VFP register file.

See the *Cortex-A5 Floating-Point Unit Technical Reference Manual* for more information.

2.1.8 Snoop Control Unit

The *Snoop Control Unit* (SCU) connects one to four Cortex-A5 cores to the memory system through the AXI interfaces. The SCU maintains data cache coherency between the Cortex-A5 cores and arbitrates L2 requests from the CPU cores and the ACP. The SCU programmers model also includes support for data security using the TrustZone memory model.

See Chapter 9 *Snoop Control Unit* for more information.

———— **Note** —————

The Cortex-A5 SCU does not support hardware management of coherency of the instruction cache.

The SCU provides the following L2 AXI interfaces:

- One or two 64-bit AXI master ports. When configured to use two master ports, the SCU can be given an address range which redirects all memory transactions within this range to the second master port. All other transactions are routed to the first master port. The filtering mode enable bit and the address range selection is provided in the SCU control registers. Alternatively, when filtering is disabled, the ports are used in a round-robin fashion.
- An optional 64-bit AXI slave port, the *Accelerator Coherency Port* (ACP), which can be connected to a DMA engine or a non-cached coherent master.

The **ARCACHE** and **AWCACHE** signals on the AXI address channels provide the memory type and outer cacheability attributes. It is sometimes necessary to connect an L2 cache that uses the inner cacheability attributes. In the Cortex-A5 MPCore processor, this information is provided on the **ARUSER** and **AWUSER** signals, as described in *AXI user bits* on page 8-4.

The **AWUSER** signal also includes additional bits to support an L2 cache in exclusive mode, as described in *AXI user bits* on page 8-4. These encodings are suitable for connecting to the PrimeCell Level 2 Cache Controller.

See Chapter 8 *Level 2 Memory Interface* for more information.

2.1.9 Debug

The Cortex-A5 MPCore processor has a CoreSight compliant *Advanced Peripheral Bus version 3* (APBv3) debug interface. This permits system access to debug resources, for example, the setting of watchpoints and breakpoints. The processor provides extensive support for real-time debug and performance profiling.

See Chapter 11 *Debug* for more information.

2.1.10 Performance monitoring

The Cortex-A5 MPCore processor provides performance counters and event monitors that can be configured to gather statistics on the operation of the processor and the memory system. See Chapter 12 *Performance Monitoring Unit*.

2.1.11 Virtualization extensions

The Cortex-A5 MPCore processor includes a number of ARMv7 extensions to improve the efficiency of para-virtualization. These extensions are implemented using existing fields in the *Secure Configuration Register* on page 4-46 (SCR) and a pair of new registers, the *Virtualization Control Register* on page 4-51 (VCR) and the *Virtualization Interrupt Register* on page 4-66 (VIR). The status of pending physical or virtual interrupts is reflected in the *Interrupt Status Register* on page 4-65 (ISR). The virtualization extensions in the Cortex-A5 MPCore processor are compatible with those available in Cortex-A9.

2.2 Interfaces

The Cortex-A5 MPCore processor has the following external interfaces:

- AMBA AXI interfaces
- APB CoreSight Debug interface
- DFT interface
- ETM interface.

See the *AMBA AXI Protocol Specification*, the *CoreSight Architecture Specification*, and the *CoreSight Embedded Trace Macrocell v3.5 Architecture Specification* for more information on these interfaces.

2.2.1 ETM interface

The *Embedded Trace Macrocell* (ETM) interface enables you to connect an external ETM unit to the processor for real-time code and data tracing of the core in an embedded system.

The ETM interface collects various processor signals and drives these signals from the processor. The interface runs at the full speed of the processor. The ETM interface connects directly to the external CoreSight ETM -A5 without any additional glue logic. Figure 2-3 shows the ETM interface signals.

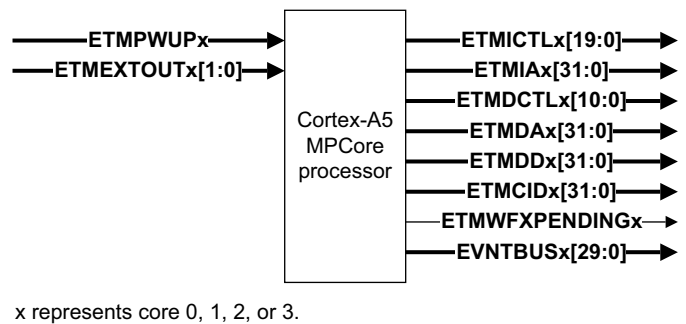


Figure 2-3 ETM interface signals

See *Trace interface signals* on page A-17 for more information.

Each core in the Cortex MPCore processor exports its own ETM interface and the processor can include a dedicated ETM unit for each individual core if required. The data is collected and filtered using a Trace Funnel as shown in Figure 2-4 on page 2-10. The ETM v3.5 architecture includes an extension to support time-stamping of data. This enables the individual trace-streams from each core to be identified and cross-referenced to help in the debugging of multi-threaded software.

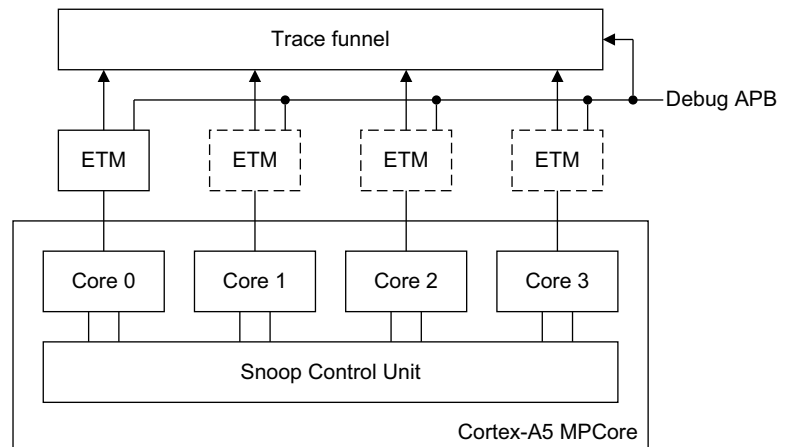


Figure 2-4 Trace architecture

You can disable the ETM interface to save power when not required. See the *CoreSight ETM-A5 Technical Reference Manual* for more information on the ETM interface, including the event bus, **EVNTBUS**.

2.3 Clocking and resets

The following sections describe clocking and resets:

- *Clocking*
- *Resets* on page 2-12.

2.3.1 Clocking

The Cortex-A5 MPCore processor has the following functional clock inputs:

CLKIN This is the main clock of the Cortex-A5 MPCore processor. All Cortex-A5 cores in the Cortex-A5 MPCore processor and the SCU are clocked with a distributed version of **CLKIN**. The CPU only synchronizes the external input signals **nCPURESET**, **nSCURESET**, **nPERIPHRESET**, **nWDRESET**, **nIRQ**, and **nFIQ**. All other external signals must be synchronous with reference to **CLKIN**.

PERIPHCLK

The Interrupt Controller, global timer, private timers, and watchdog are clocked with **PERIPHCLK**.

PERIPHCLK must be synchronous with **CLKIN**, and the **PERIPHCLK** clock period, N , must be configured as a multiple of the **CLKIN** clock period. This multiple N must be equal to, or greater than two.

PERIPHCLKEN

This is the clock enable signal for the Interrupt Controller and timers. The **PERIPHCLKEN** signal is generated at **CLKIN** clock speed. **PERIPHCLKEN** HIGH on a **CLKIN** rising edge indicates that there is a corresponding **PERIPHCLK** rising edge.

Figure 2-5 shows an example of clocking the peripherals using these enable signals at a 3:1 ratio.

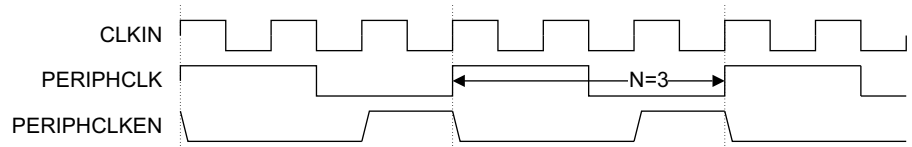


Figure 2-5 Clocking example on Cortex-A5 MPCore peripherals

AXI interface clocking

The SCU AMBA AXI interface supports integer ratios of the **CLKIN** frequency (1:1, 2:1, 3:1, ...). These ratios are configured through external clock enable signals. In all cases AXI transfers remain synchronous. The AXI master interfaces include the following clock enable signals:

- **ACLKENM0** for the primary AXI master interface.
- **ACLKENM1** for the optional secondary AXI master interface.

Figure 2-6 on page 2-12 shows an example where the AXI primary master interface is clocked at a 3:1 ratio using the enable signal.

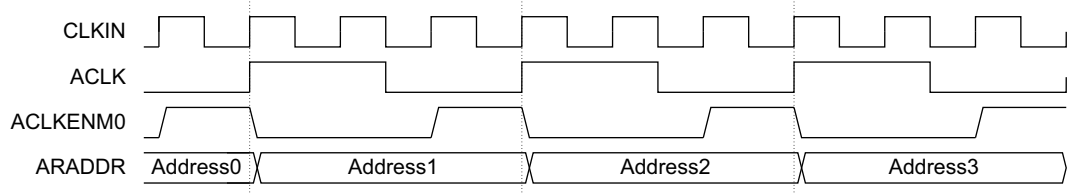


Figure 2-6 AXI master port clocking at a ratio of 3:1 using ACLKENM0

The optional AXI slave interface, the *Accelerator Coherency Port (ACP)*, also supports integer AXI bus frequency ratios using the clock enable signal **ACLKENS** in the same way as the master AXI ports.

Debug interface clocking

The processor includes an AMBA APB interface used to access the debug and performance monitoring registers. Internally this interface is driven from **CLKIN**. A separate enable signal, **PCLKENDBG**, is provided to enable the external AMBA bus to be driven at a lower frequency, which must be an integer ratio of **CLKIN**. If the debug infrastructure in the system is required to be fully asynchronous to the processor clock, you can use a synchronizing component supplied as part of the standard product deliverables to connect the external AMBA APB bus to the processor.

2.3.2 Resets

The Cortex-A5 MPCore processor has multiple reset domains with the following reset input signals:

- nCPURESET[3:0]** These are the primary reset signals which initialize the majority of the processor except for the debug logic.
- nDBGRESET[3:0]** These signals reset only the debug logic in the processor.
- nWDRESET[3:0]** These signals are used to individually reset each watchdog unit reset status flag. These resets must be asserted for power-on reset, but not if a reset assertion is caused by a watchdog reset request with the **WDRESETREQ** signal.

These reset signals are 4-bit signals, where each bit represents one core in the processor. The following reset input signals are single-bit:

- nPERIPHRESET** This signal initializes the Interrupt Controller and the timer-watchdog units.
- nSCURESET** This signal initializes the majority of the logic in the SCU.

All of these are active LOW signals that reset logic in the processor.

2.4 Power management

The Cortex-A5 MPCore processor uses gated clocks and gates to disable inputs to unused functional blocks. Only the logic in use to perform an operation consumes any dynamic power.

The following sections describe power management:

- *Individual Cortex-A5 core power management*
- *Power domains* on page 2-15
- *Communication to the Power Management Controller* on page 2-17
- *IEM support* on page 2-18.

2.4.1 Individual Cortex-A5 core power management

The individual Cortex-A5 cores in the Cortex-A5 MPCore processor support four main levels of power management:

Run mode This is the normal mode of operation where all of the processor functionality is available. Everything, including core logic and embedded RAM arrays, is clocked and powered up.

Standby mode

This mode disables most of the clocks of the core, while keeping it powered up. This reduces the power drawn to the static leakage current, plus a small clock power overhead required to enable the processor to wake up from Standby mode. The transition from Standby mode to Run mode is caused by one of the following:

- the arrival of an interrupt, either masked or unmasked
- the arrival of an event, if standby mode was initiated by a *Wait for Event* (WFE) instruction
- a debug request, when either debug is enabled or disabled
- a reset.

Note

When a core in Standby mode receives a data cache coherency request or a CP15 maintenance operation from another core in the processor through the SCU, the clock on its L1 memory system is restored temporarily so that the request can be handled. This mechanism prevents the requirement for a core about to enter Standby mode from having to flush its L1 data cache, by ensuring that its coherent data remains accessible by other cores in the processor.

The debug request can be generated externally using the appropriate bit of the **EDBGRQ** signal on the Cortex-A5 MPCore processor, or from a Debug Halt instruction issued to the core through the debug APB.

Entry into Standby mode is performed by executing the *Wait For Interrupt* (WFI) instruction. To ensure that the entry into the standby mode does not affect the memory system, the WFI instruction automatically performs a *Data Synchronization Barrier* (DSB) operation. This ensures that all explicit memory accesses occur in program order before the WFI instruction has completed.

After the processor clocks are stopped, the corresponding bit of the external **STANDBYWFI** signal is asserted to indicate that the core is in Standby mode.

The core can also enter Standby mode using the WFE instruction. In this case, the processor indicates the change of state with the external **STANDBYWFE** signal. When Standby Mode is entered using WFE, the core can be woken up by another core in the processor issuing a *Send Event* (SEV) instruction, or by raising the external **EVENTI** signal on the processor.

Dormant mode

This mode is designed to enable the core to be powered down, while leaving the TLB, instruction, and data cache powered up and maintaining their state. When the core is in Dormant mode it can only be returned to Run mode by asserting a reset.

The mode change is initiated in the same way as Standby mode using a WFI instruction. When reset is asserted, the exception handler is responsible for recovering the state from storage and resuming execution of the program.

Dormant mode has an advantage over a full shutdown in that the state can be restored in a significantly shorter time with only a relatively small extra power requirement.

Before entering Dormant mode, the state of the chosen core in the Cortex-A5 MPCore processor, excluding the contents of the RAMs that remain powered up in dormant mode, must be saved to external memory. These state saving operations must ensure that the following occur:

- All ARM registers, including CPSR and SPSR registers are saved.
- All system registers are saved.
- All debug-related state must be saved.
- The core must correctly set the CPU Status Register in the SCU so that it enters Dormant Mode. See *SCU CPU Power Status Register* on page 9-9.
- A Data Synchronization Barrier instruction is executed to ensure that all state saving has completed.
- The core then executes a WFI instruction and raises **STANDBYWFI**, to indicate that it is ready to enter dormant mode. See *Communication to the Power Management Controller* on page 2-17 for more information.
- Before removing the power, the appropriate reset signal to the Cortex-A5 MPCore processor must be asserted by the external power control mechanism.

The external power controller triggers the transition from Dormant state to Run state. The external power controller must assert the appropriate reset to the processor until the power is restored. After power is restored, the core leaves reset and can determine that the saved state must be restored.

Shutdown mode

This mode is similar to Dormant mode, but all the power domains in the processor are shut down and all state is lost. To restore program execution after entering this mode:

- all program state must be saved and the L1 data cache cleaned
- interrupts must be disabled
- all external requests must be completed by issuing a DSB memory barrier instruction.

The processor can be restored to Run mode from reset in the same way as from Dormant mode with the exception handler restoring all the saved state.

Data cache coherency is maintained in Run and Standby modes. To enter Dormant or Shutdown mode without losing data coherency in the processor:

- clean all shared data from the L1 cache
- execute a DSB instruction
- switch the processor from *Symmetric MultiProcessing (SMP)* mode to *Asymmetric MultiProcessing (AMP)* mode

- raise a power mode change request.

———— **Note** ————

You must power up the processor before performing a reset.

Processor debug and power saving modes

The Cortex-A5 MPCore processor does not include a separate clock or power domain for the AMBA APB bus. Because of this, debug requests cannot be handled by the processor when it is in Shutdown or Dormant mode. If this functionality is required in the system, you must configure the power control infrastructure to power-up and clock the core when a debug request is issued, either by sampling the APB **PSEL** signal or using a separate mechanism.

The Cortex-A5 MPCore processor supports a number of different power domains as described in *Power domains*. The top level debug infrastructure, including the single APB interface, forms part of the power and clocking domain which includes the SCU. A debug request can be addressed to a core which is currently in Shutdown or Dormant mode when other cores are active. In this case, the APB bus responds with a slave error on **PSLVERRDBG** unless additional power controller functionality is added to power up the specific core automatically.

Debug requests can be handled normally in Standby mode, because the APB bus clock is gated at the same level as the interrupt logic and is always active in this mode.

Additional optional dynamic clock gating is provided by both the SCU and the interrupt controller to minimize the power used by the processor when all of the CPU cores are in low power state and there are no outstanding requests on the ACP interface. This clock gating functionality is disabled by default and can be enabled by software by writing to the appropriate fields in the SCU Control Register. See *SCU Control Register* on page 9-7 for more information.

2.4.2 Power domains

The Cortex-A5 MPCore processor supports two power domains in each of the individual cores:

- V_{Core} , which includes the CPU logic cells and optional ETM
- V_{Ram} , which includes the embedded memory used for the instruction and data caches and the main TLB.

In addition, the SCU provides two more power domains:

- One for the SCU control logic and peripherals, such as the interrupt controller and timer/watchdog units, V_{SCU} .
- A separate domain containing the duplicate Cache Tag RAMs.

The separate SCU power domains can remain active even when all the cores are powered down. This enables the Cortex-A5 MPCore processor to accept requests on the ACP AXI slave port when no instruction execution is taking place in the processor.

Figure 2-7 on page 2-16 shows these domains embedded in a typical *System-on-Chip* (SoC) power domain, V_{Soc} .

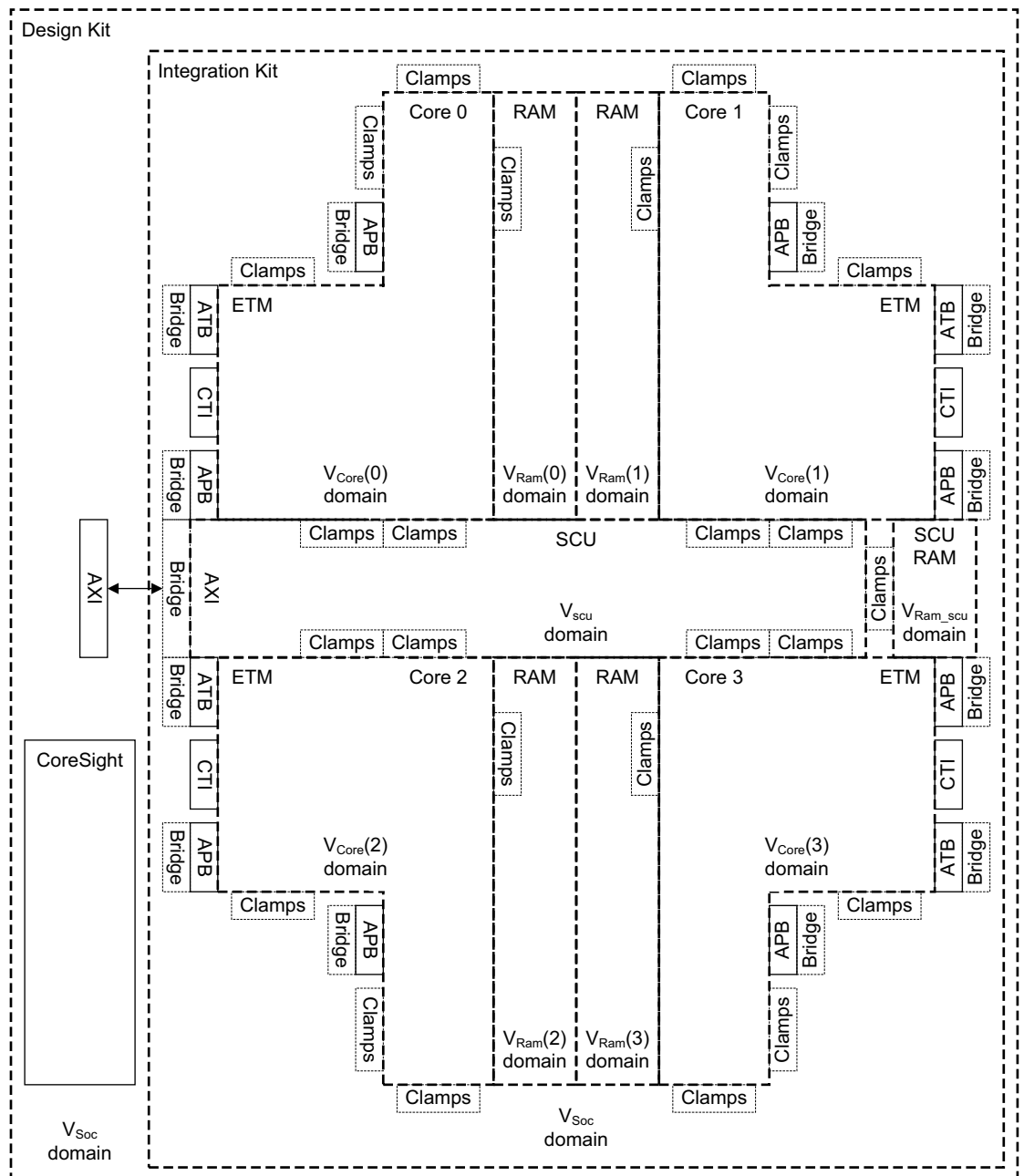


Figure 2-7 Power domains

Each of the V_{Core} domains uses a single clock which is architecturally gated at the top level of the core to minimize dynamic power consumption without removing power completely from the core. The V_{Ram} domains can include logic to clamp the input signals from V_{Core} , enabling the RAM state to be retained when the power is removed from the V_{Core} domain in Dormant mode.

At the SOC integration level, the processor logic in V_{Core} and V_{Scu} can be isolated and powered down completely through the instantiation of clamps and bridges on all of the external interfaces inside the V_{Soc} domain. Special bridge components supporting both asynchronous operation

and power control interfaces for the AMBA AXI and APB ports on the processor and the ATB Trace port on the ETM are supplied in the integration kit provided in the standard processor deliverables. Table 2-1 shows the supported power configurations.

Table 2-1 Supported power configurations

V_{Soc}	V_{SCU}	V_{Core}	V_{Ram}	Comments
On	Off	Off	Off	Processor isolated from SOC domain.
On	On	Off	Off	All cores in shutdown mode, ACP active.
On	On	Off	On	Dormant mode. RAM powered, clock off.
On	On	On	On	Run mode.

2.4.3 Communication to the Power Management Controller

Communication between the Cortex-A5 MPCore processor and the system Power Management Controller can be performed using a number of signals on the external interface.

The required power mode can be selected for each of the individual processor power domains by writing to the memory-mapped SCU CPU Power Status Register as described in *SCU CPU Power Status Register* on page 9-9. The appropriate register field is transferred to the corresponding output signal **PWRCTLO{n}[1:0]** when core $0 < n < 3$ is ready to enter a lower power mode. This is also signified by the **STANDBYWFI{n}** or **STANDBYWFE{n}** signals.

When the SCU CPU Power Status Register indicates that a core in the processor is in Dormant or Shutdown mode, or about to enter one of these modes, the core does not receive any coherency requests, including forwarded CP15 maintenance operations, from the SCU. If a CP15 maintenance operation is executed by a core in the processor after the SCU CPU Power Status Register is set to indicate it is about to enter Dormant or Shutdown mode, it is unpredictable whether the operation is forwarded to other cores in the processor.

Table 2-2 shows the encoding of these output power control signals.

Table 2-2 Cortex-A5 MPCore power control signal encoding

PWRCTLO{n}[1:0]	Desired power mode
b0x	Core n must remain powered on for Standby mode
b10	Core n can enter Dormant mode
b11	Core n can enter Shutdown mode

These control signals can then be used by the power controller logic to constrain the actual power mode selected in the system. The default value for the desired power mode for each processor can be selected using the external input signals **PWRCTLI{n}[1:0]** encoded in the same format. The values on these signals are transferred to the SCU CPU Power Status Register when the Cortex-A5 MPCore processor is reset.

The Cortex-A5 MPCore processor includes the following input clamp signals to enable individual domains to be isolated before the power is turned off:

CPURAMCLAMP[3:0]

Enable clamps on individual core RAM blocks. These clamps must be enabled in Dormant mode to maintain the state of the instruction cache, data cache, and TLB in the core when the power is removed.

PERIPHCLAMP[3:0]

Enable clamps which isolate an individual core from the SCU, interrupt controller, and peripherals in the Cortex-A5 MPCore processor. These clamps must be enabled before the power is removed from a core in Shutdown or Dormant mode.

SCURAMCLAMP

Enable clamps on SCU RAM blocks. These are duplicate cache tags.

———— **Note** ————

These signals are only applicable if the processor has been implemented with power clamps.

2.4.4 IEM support

The Cortex-A5 MPCore processor supports the implementation of ARM *Intelligent Energy Management* (IEM) at the system level using the following features:

- At the SCU and processor level, RAM voltage for caches, TLB RAM and SCU tags can differ from logic voltage.
- The standard deliverables include IEM-ready asynchronous bridge components for all the AMBA AXI and APB interfaces on the processor. The ETM deliverables also include an ATB trace interface bridge component.

2.5 Multiprocessor bring-up

This section describes the steps required to bring-up the Cortex-A5 MPCore processor ready for *Symmetric MultiProcessing* (SMP). In the description:

- All operations within a step on a single core in the processor can occur in any order.
- All operations on one step on a single core in the processor must occur before any operations in a subsequent step occur on that core. All operations on a non-lead core must not occur before the equivalent step number on the lead core. No other ordering applies.

For the lead core in the processor:

1. Invalidate the data cache.
2. Invalidate the SCU duplicate tags for all processors.
3. Invalidate the PL310 L2 cache controller if present in the system.
4. Enable the SCU.
5. Enable the data cache
6. Enable the PL310 L2 cache controller if present in the system.
7. Set SMP mode with ACTLR.SMP.

For non-lead cores in the processor:

1. Invalidate the data cache.
2. Enable the data cache.
3. Set SMP with ACTLR.SMP.

Chapter 3

Programmers Model

This chapter describes the processor registers and provides information about programming the processor. It contains the following sections:

- *About the programmers model* on page 3-2
- *Jazelle extension* on page 3-3
- *NEON technology* on page 3-4
- *Processor operating states* on page 3-5
- *Data types* on page 3-7
- *Memory formats* on page 3-8
- *Addresses in the Cortex-A5 MPCore processor* on page 3-9
- *Security Extensions overview* on page 3-10.

3.1 About the programmers model

The Cortex-A5 MPCore processor implements the ARM v7-A architecture profile. This includes:

- the 32-bit ARM instruction set
- the Thumb instruction set, a variable-length instruction set, that has both 16-bit and 32-bit instructions
- execution of 8-bit Java bytecodes
- the ThumbEE instruction set
- the security extensions, TrustZone
- the VFPv4 Floating point architecture and Advanced SIMD extensions, NEON.

See the *ARM Architecture Reference Manual* for more information on the ARMv7-A architecture.

3.2 Jazelle extension

The Cortex-A5 MPCore processor optionally provides hardware support for the Jazelle extension. The processor accelerates the execution of most Java bytecodes. Some bytecodes are executed by software routines.

See *CPI4 Jazelle register summary* on page 5-3.

3.3 NEON technology

NEON technology is a media and signal processing architecture that adds instructions targeted primarily at audio, video, 3-D graphics, image, and speech processing.

NEON technology includes both Advanced SIMD (*single-instruction multiple data*) instructions and ARM VFPv4 instructions. These instructions are all available in both ARM and Thumb states.

See the *ARM Architecture Reference Manual* for details of the NEON technology.

See the *Cortex-A5 NEON Media Processing Engine Technical Reference Manual* for implementation-specific information.

3.4 Processor operating states

The processor has the following instruction set states controlled by the T bit and J bit in the CPSR.

- ARM state** The processor executes 32-bit, word-aligned ARM instructions.
- Thumb state** The processor executes 16-bit and 32-bit, halfword-aligned Thumb instructions.
- ThumbEE state** The processor executes a variant of the Thumb instruction set designed as a target for dynamically generated code. This is code compiled on the device either shortly before or during execution from a portable bytecode or other intermediate or native representation.
- Jazelle state** The processor executes variable length, byte-aligned Java bytecodes.

The J bit and the T bit determine the instruction set used by the processor. Table 3-1 shows the encoding of these bits.

Table 3-1 CPSR J and T bit encoding

J	T	Instruction set state
0	0	ARM
0	1	Thumb
1	0	Jazelle
1	1	ThumbEE

———— **Note** —————

Changing between ARM and Thumb states does not affect the processor mode or the register contents. See the *ARM Architecture Reference Manual* for information on entering and exiting ThumbEE state.

3.4.1 Switching state

You can change the instruction set state of the processor between:

- ARM state and Thumb state using the BX and BLX instructions.
- Thumb state and ThumbEE state using the ENTERX and LEAVEX instructions.
- ARM and Jazelle state using the BXJ instruction.
- Thumb and Jazelle state using the BXJ instruction.

See the *ARM Architecture Reference Manual* for more information about changing instruction set state.

The processor handles exceptions in ARM state or in Thumb state, determined by the SCR.TE bit. See *System Control Register* on page 4-39.

On taking an exception, the processor stores the *Current Processor Status Register* (CPSR) to the *Saved Processor Status Register* (SPSR). On exiting the exception handler, the processor transfers the SPSR value back to the CPSR, returning the processor to the original instruction set state if necessary.

3.4.2 Interworking ARM and Thumb code sequences

You can freely mix ARM and Thumb code sequences. You can use BLX instructions to call ARM subroutines from Thumb. You can also use BLX instructions to call Thumb subroutines from ARM.

3.5 Data types

The Cortex-A5 MPCore processor supports the following data types:

Byte 8 bits
Halfword 16 bits
Word 32 bits
Doubleword 64 bits.

Note

- When any of these types are described as unsigned, the N-bit data value represents a non-negative integer in the range 0 to $+2^N-1$, using normal binary format.
 - When any of these types are described as signed, the N-bit data value represents an integer in the range -2^{N-1} to $+2^{N-1}-1$, using two's complement format.
-

For best performance you must align these in memory as follows:

- byte quantities can be placed on any byte boundary
- halfword quantities must align with 2-byte boundaries
- word quantities must align with 4-byte boundaries
- doubleword quantities must align with 8-byte boundaries.

The processor supports unaligned accesses.

Note

You can only use LDRD, LDM, VLDM, STRD, STM, or VSTM instructions to access word-aligned quantities.

The processor supports mixed-endian accesses. See *Memory formats* on page 3-8.

3.6 Memory formats

The Cortex-A5 MPCore processor views memory as a linear collection of bytes numbered in ascending order from zero. For example, bytes 0-3 hold the first stored word, and bytes 4-7 hold the second stored word. The processor can store words in memory in either big-endian format or little-endian format.

Instructions are always treated as little-endian. See the *ARM Architecture Reference Manual* for more information about the supported endianness options.

3.7 Addresses in the Cortex-A5 MPCore processor

The Cortex-A5 MPCore processor operates using *virtual addresses* (VAs). The *Memory Management Unit* (MMU) translates these VAs into the *physical addresses* (PAs) used to access the memory system. Translation tables hold the mappings between VAs and PAs.

See the *ARM Architecture Reference Manual* for more information.

When the Cortex-A5 MPCore processor is executing in Non-secure state, the processor performs translation table look-ups using the Non-secure versions of the Translation Table Base Registers. In this situation, any VA can only translate into a Non-secure PA. When it is in Secure state, the Cortex-A5 MPCore processor performs translation table look-ups using the Secure versions of the Translation Table Base Registers. In this situation, the security state of any VA is determined by the NS bit of the translation table descriptors for that address.

This is an example of the address manipulation that occurs when the Cortex-A5 MPCore processor requests an instruction.

1. The Cortex-A5 processor issues the VA of the instruction as Secure or Non-secure VA accesses according to the state the processor is in.
2. The instruction cache is indexed by the bits of the VA. The MMU performs the translation table look-up in parallel with the cache access. If the processor is in the Secure state it uses the Secure translation tables, otherwise it uses the Non-secure translation tables.
3. If the protection check carried out by the MMU on the VA does not abort and the PA tag is in the instruction cache, the instruction data is returned to the processor.
4. If there is a cache miss, the MMU passes the PA to the AXI bus interface to perform an external access. The external access is always Non-secure when the core is in the Non-secure state. In the Secure state, the external access is Secure or Non-secure according to the NS attribute value in the selected translation table entry. In Secure state, both L1 and L2 translation table walk accesses are marked as Secure, even if the first level descriptor is marked as NS.

3.8 Security Extensions overview

The purpose of the Security Extensions is to enable the construction of a secure software environment. This section describes the following:

- *System boot sequence*
- *Security Extensions write access disable.*

See the *ARM Architecture Reference Manual* for details of the security extensions.

3.8.1 System boot sequence

———— Caution ————

The Security Extensions enable the construction of an isolated software environment for more secure execution, depending on a suitable system design around the processor. The technology does not protect the processor from hardware attacks, and you must make sure that the hardware containing the reset handling code is appropriately secure.

The processor always boots in the privileged Supervisor mode in the Secure state, with the NS bit set to 0. See *Secure Configuration Register* on page 4-46. This means that code that does not attempt to use the Security Extensions always runs in the Secure state. If the software uses both Secure and Non-secure states, the less trusted software, such as a complex operating system and application code running under that operating system, executes in Non-secure state, and the most trusted software executes in the Secure state. The following sequence is expected to be typical use of the Security Extensions:

1. Exit from reset in Secure state.
2. Configure the security state of memory and peripherals. Some memory and peripherals are accessible only to the software running in Secure state.
3. Initialize the secure operating system. The required operations depend on the operating system, and include initialization of caches, MMU, exception vectors, and stacks.
4. Initialize Secure Monitor software to handle exceptions that switch execution between the Secure and Non-secure operating systems.
5. Optionally lock aspects of the secure state environment against further configuration. See *System control and configuration* on page 4-3.
6. Pass control through the Secure Monitor software to the non-secure OS with an SMC instruction.
7. Enable the Non-secure operating system to initialize. The required operations depend on the operating system, and typically include initialization of caches, MMU, exception vectors, and stacks.

The overall security of the secure software depends on the system design, and on the secure software itself.

3.8.2 Security Extensions write access disable

The processor signal **CP15SDISABLE** disables write access to certain registers in the system control coprocessor. Each bit of the signal controls one of the cores in the processor. Attempts to write to these registers in a core when the corresponding bit of **CP15SDISABLE** is HIGH result in an Undefined instruction exception. Reads from the registers are still permitted. For more information about the registers affected by this signal, see *System control and configuration* on page 4-3.

Chapter 4

System Control

This chapter describes the purpose of the system control coprocessor, its structure, operation, and how to use it. It contains the following sections:

- *About system control* on page 4-2
- *Register summary* on page 4-14
- *Register descriptions* on page 4-22.

4.1 About system control

The system control coprocessor, CP15, controls and provides status information for the functions implemented in the processor. The main functions of the system control coprocessor are:

- overall system control and configuration
- MMU configuration and management
- cache configuration and management
- system performance monitoring.

Note

See Chapter 11 *Debug* for a description of the debug registers accessed through CP14.

In ARMv7-A the following registers have instruction set equivalents:

- Instruction Synchronization Barrier
- Data Synchronization Barrier
- Data Memory Barrier
- Wait for Interrupt.

This section gives an overall view of the system control coprocessor. See *System control functional groups* for details of the registers in the system control coprocessor.

The following sections describe system control:

- *System control functional groups*
- *System control and configuration* on page 4-3
- *MMU control and configuration* on page 4-4
- *Cache control and configuration* on page 4-4
- *Cache Operations Registers* on page 4-4
- *System performance monitor registers* on page 4-7
- *System feature registers* on page 4-7
- *c0, Instruction set attributes registers* on page 4-8
- *c7, VA to PA operations* on page 4-8
- *c8, TLB maintenance operations* on page 4-9
- *c10, Memory region remap* on page 4-11
- *c13, Software Thread ID Registers* on page 4-11
- *c15, TLB access and attributes* on page 4-12.

4.1.1 System control functional groups

The system control coprocessor provides a set of registers that you can write to and read from. The functional groups for the registers are:

- *System control and configuration* on page 4-3
- *MMU control and configuration* on page 4-4
- *Cache control and configuration* on page 4-4
- *System performance monitor registers* on page 4-7.

The system control coprocessor also controls the operation of the security extensions:

- some of the registers are only accessible in the Secure state
- some of the registers are banked, with separate copies for the Secure and Non-secure states
- some of the registers are common to Secure and Non-secure states.

Note

In Monitor mode, the Cortex-A5 MPCore processor is in Secure state. The processor treats all accesses as secure and the system control coprocessor behaves as if it operates in the Secure state regardless of the value of the NS bit, see *Secure Configuration Register* on page 4-46. In Monitor mode the NS bit defines the copies of the banked registers in the system control coprocessor that the processor can access:

NS = 0 Access to Secure state system registers.

NS = 1 Access to Non-secure state system registers.

Registers that are only accessible in the Secure state are always accessible in Monitor mode, regardless of the value of the NS bit.

4.1.2 System control and configuration

The system control and configuration registers provide overall management of:

- security extensions behavior
- memory functionality
- interrupt behavior
- exception handling
- program flow prediction
- coprocessor access rights for control of NEON and FPU access rights.

The system control and configuration registers also provide the processor ID. Some of the functionality depends on how you set external signals at reset.

System control and configuration behaves in three ways:

- as a set of flags or enables for specific functionality
- as a set of numbers, values that indicate system functionality
- as a set of addresses for processes in memory.

TrustZone write access disable

You can use the input signal, **CP15SSDISABLE**, to disable write access to some of the Secure registers. See Table 4-1 on page 4-4.

You can also use the **CP15SSDISABLE** signal to disable subsequent access to system control processor registers after the secure boot code runs. This protects the configuration set up by the Secure boot code.

A change to the **CP15SSDISABLE** signal takes effect on the instructions decoded by the corresponding core in the processor as quickly as possible. Software must perform an ISB after a change to this signal has occurred to ensure that its effects are recognized on following instructions. To ensure that this signal is effective:

- control of the **CP15SSDISABLE** signal must remain within the SoC that implements the macrocell
- the **CP15SSDISABLE** signal must be driven LOW by the SoC hardware at reset.

When **CP15SSDISABLE** is asserted HIGH for the registers that Table 4-1 on page 4-4 lists, any attempt to write to the secure version of a banked register, or any nonbanked register, results in an Undefined instruction exception.

Table 4-1 shows the system registers affected by **CP15SDISABLE**.

Table 4-1 System registers affected by CP15SDISABLE

Register	Description	Instruction
SCTLR	<i>System Control Register</i> on page 4-39	MCR p15, 0, <Rd>, c1, c0, 0
ACTLR	<i>Auxiliary Control Register</i> on page 4-42	MCR p15, 0, <Rd>, c1, c0, 1
TTBR0	<i>Translation Table Base Register 0</i> on page 4-52	MCR p15, 0, <Rd>, c2, c0, 0
TTBCR	<i>Translation Table Base Control Register</i> on page 4-55	MCR p15, 0, <Rd>, c2, c0, 2
DACR	<i>Domain Access Control Register</i> on page 4-56	MCR p15, 0, <Rd>, c3, c0, 0
PRRR	<i>c10, Memory region remap</i> on page 4-11	MCR p15, 0, <Rd>, c10, c2, 0
NMRR		MCR p15, 0, <Rd>, c10, c2, 1
VBAR	<i>Vector Base Address Register</i> on page 4-64	MCR p15, 0, <Rd>, c12, c0, 0
MVBAR	<i>Monitor Vector Base Address Register</i> on page 4-65	MCR p15, 0, <Rd>, c12, c0, 1

4.1.3 MMU control and configuration

The MMU control and configuration registers:

- generate physical address locations from the virtual addresses that the processor generates
- control program access to memory
- configure translation table memory type attributes
- provide information about MMU faults and external aborts
- control TLB maintenance operations that can invalidate either the entire TLB or selected entries
- hold thread and process IDs.

4.1.4 Cache control and configuration

The cache control and configuration registers:

- provide information on the size and architecture of the instruction and data caches
- control cache maintenance operations that include clean and invalidate caches, drain and flush buffers, and address translation.

4.1.5 Cache Operations Registers

Cache operations registers manage the associated cache levels. The maintenance operations are in the following management groups:

- Set/Way:
 - clean
 - invalidate
 - clean and invalidate.
- VA:
 - clean

- invalidate
- clean and invalidate.

In addition, the maintenance operations use the following definitions:

Point of coherency (PoC)

The PoC is the point at which all agents that can access memory are guaranteed to see the same copy of a memory location

Point of unification (PoU)

The PoU is the point by which the instruction and data caches and the translation table walks of the processor are guaranteed to see the same copy of a memory location.

For the Cortex-A5 MPCore processor the PoC and the PoU is at the L2 interfaces.

———— Note —————

- Reading from these registers, except for reads from the PA Register, causes an Undefined instruction exception.
- All accesses to these registers can only be executed in a privileged mode of operation, except Data Synchronization Barrier, Instruction Synchronization Barrier, and Data Memory Barrier. These can be executed in User mode. Attempting to execute a privileged instruction in User mode results in an Undefined instruction exception.
- For information on the behavior of the invalidate, clean, and prefetch operations in the Secure and Non-secure states, see the *ARM Architecture Reference Manual*.

Table 4-2 shows the cache operation functions and the associated data and instruction formats for CP15 c7.

Table 4-2 Cache operation functions

Description	Mnemonic	Data	Instruction
Invalidate entire instruction cache Inner Shareable.	ICIALUIS	SBZ	MCR p15, 0, <Rd>, c7, c1, 0
Invalidate entire branch predictor array Inner Shareable.	BPIALLIS	SBZ	MCR p15, 0, <Rd>, c7, c1, 6
Invalidate all instruction caches to PoU. Also flushes branch target cache.	ICIALLU	SBZ	MCR p15, 0, <Rd>, c7, c5, 0
Invalidate instruction cache by VA to PoU.	ICIMVAU	VA	MCR p15, 0, <Rd>, c7, c5, 1
Invalidate entire branch predictor array.	BPIALL	SBZ	MCR p15, 0, <Rd>, c7, c5, 6
Invalidate VA from branch predictor array.	BPIMVA	SBZ	MCR p15, 0, <Rd>, c7, c5, 7
Invalidate data cache line by VA to PoC.	DCIMVAC	VA	MCR p15, 0, <Rd>, c7, c6, 1
Invalidate data cache line by Set/Way.	DCISW	Set/Way	MCR p15, 0, <Rd>, c7, c6, 2
Clean data cache line to PoC by VA.	DCCMVAC	VA	MCR p15, 0, <Rd>, c7, c10, 1
Clean data cache line by Set/Way.	DCCSW	Set/Way	MCR p15, 0, <Rd>, c7, c10, 2
Clean data or unified cache line by VA to PoU.	DCCMVAU	VA	MCR p15, 0, <Rd>, c7, c11, 1
Clean and invalidate data cache line by VA to PoC.	DCCIMVAC	VA	MCR p15, 0, <Rd>, c7, c14, 1
Clean and invalidate data cache line by Set/Way.	DCCISW	Set/Way	MCR p15, 0, <Rd>, c7, c14, 2

The invalidate entire operations apply to all cache locations.

The operations that act on a single cache line identify the line using the contents of Rd as the address, passed in the MCR instruction. The data is interpreted using:

- *Set/way format*
- *VA format* on page 4-7.

Set/way format

Figure 4-1 shows the Set/Way format you can use to specify a line in the cache that must be accessed.

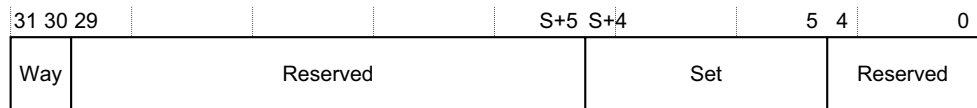


Figure 4-1 Set/Way bit assignments

Table 4-3 shows the bit assignments for Set/Way operations using CP15 c7, and their meanings.

Table 4-3 Set/Way bit assignments

Bits	Name	Description
[31:30]	Way	Way in set being accessed
[29:S+5]	Reserved	SBZ or UNP
[S+4:5]	Set	Set being accessed
[4:0]	Reserved	SBZ or UNP

The value of S in Table 4-3 depends on the cache size. Table 4-4 shows the relationship of cache sizes and the S parameter value.

Table 4-4 Cache size and S parameter dependency

Cache size	S parameter value
4KB	5
8KB	6
16KB	7
32KB	8
64KB	9

The value of S is derived from the following equation:

$$S = \log_2 \left(\frac{\text{Cache size in bytes}}{\text{Associativity} \times \text{line length in bytes}} \right)$$

See *Cache Size Selection Register* on page 4-39 for details of instruction and data cache size.

Example 4-1 on page 4-7 shows the use of the command Clean Data Cache.

Example 4-1 Clean Data Cache

```

;code is specific to Cortex-A5 processors with 32KB caches
MOV R0, #0:SHL:5
way_loop
MOV R1, #0:SHL:30
line_loop
ORR R2,R1,R0
MCR p15,0,R2,c7,c10,2
ADD R1,R1,#1:SHL:30
CMP R1,#0
BNE line_loop
ADD R0,R0,#1:SHL:5
CMP R0,#1:SHL:13
BNE way_loop

```

VA format

The VA format is useful for flushing a particular address or range of addresses in the caches. Figure 4-2 shows the VA bit assignments for c7 functions:

- Invalidate Instruction Cache Line
- Invalidate Data Cache Line
- Clean Data Cache Line
- Clean and Invalidate Data Cache Line.

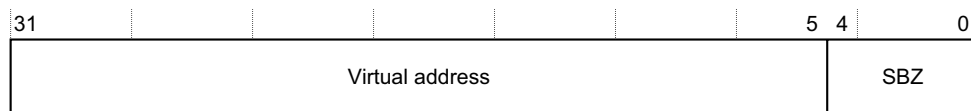


Figure 4-2 CP15 Register c7 VA bit assignments

Bits [4:0] are ignored.

The Invalidate entire instruction cache operation takes several cycles to complete and the instruction is not interruptible.

User access to CP15 c7 operations

A small number of CP15 c7 operations can be executed by code while in User mode. Attempting to execute a privileged operation in User mode using CP15 c7 results in an Undefined instruction exception.

4.1.6 System performance monitor registers

The performance monitor registers control the monitoring operation and count events.

System performance monitoring counts system events, such as cache misses, TLB misses, pipeline stalls, and other related features to enable system developers to profile the performance of their systems. See Chapter 12 *Performance Monitoring Unit* for more information on system performance monitoring.

4.1.7 System feature registers

The system feature registers specify:

- Processor features

- Debug features
- Memory model features.

You can access these registers with the following CP15 instruction:

MRC p15, 0, <Rd>, c0, c1, {0-7} ; reads feature version registers

Depending on the Opcode_2 value, the accessed register is:

- Opcode_2 = 0 for ID_PFR0, Processor Feature Register 0
- Opcode_2 = 1 for ID_PFR1, Processor Feature Register 1
- Opcode_2 = 2 for ID_DFR0, Debug Feature Register 0
- Opcode_2 = 3 Reserved
- Opcode_2 = 4 for ID_MMFR0, Memory Model Feature Register 0
- Opcode_2 = 5 for ID_MMFR1, Memory Model Feature Register 1
- Opcode_2 = 6 for ID_MMFR2, Memory Model Feature Register 2
- Opcode_2 = 7 for ID_MMFR3, Memory Model Feature Register 3.

The Reserved Opcode_2 value, Opcode_2=3, reads as zero.

4.1.8 c0, Instruction set attributes registers

The Instruction set attributes registers are:

- *Instruction Set Attributes Register 0* on page 4-31
- *Instruction Set Attributes Register 1* on page 4-32
- *Instruction Set Attributes Register 2* on page 4-33
- *Instruction Set Attributes Register 3* on page 4-34
- *Instruction Set Attributes Register 4* on page 4-35.

These registers are read-only registers and are accessed with the following CP15 instructions:

MRC p15, 0, <Rd>, c0, c2, {0-7} ; reads feature version registers

Depending on the Opcode_2 value, the accessed register is:

- Opcode_2 = 0 for ID_ISAR0, ISA feature Register 0
- Opcode_2 = 1 for ID_ISAR1, ISA Feature Register 1
- Opcode_2 = 2 for ID_ISAR2, ISA Feature Register 2
- Opcode_2 = 3 for ID_ISAR3, ISA Feature Register 3
- Opcode_2 = 4 for ID_ISAR4, ISA Feature Register 4
- Opcode_2 = 5 Reserved
- Opcode_2 = 6 Reserved
- Opcode_2 = 7 Reserved.

4.1.9 c7, VA to PA operations

Writes to the VA to PA Translation Registers translate the virtual address provided by a general-purpose register (<Rd> Field) and store the corresponding physical address in the PA Register. Figure 4-3 shows the register bit assignments.



Figure 4-3 VA to PA register bit assignments

The VA to PA translation can only be performed in privileged mode and uses the current ASID, in the Context ID Register, to perform the comparison in the TLB.

The VA to PA Translation Register is accessed by writing to CP15 c7 register with the <CRm> field set to c8 and the Opcode_2 field being used to select the kind of permission check that is performed during the translation.

With the processor in Non-secure state the operations are:

MCR p15,0,<Rd>,c7,c8,0; VA to PA translation with privileged read permission check
 MCR p15,0,<Rd>,c7,c8,1; VA to PA translation with privileged write permission check
 MCR p15,0,<Rd>,c7,c8,2; VA to PA translation with user read permission check
 MCR p15,0,<Rd>,c7,c8,3; VA to PA translation with user write permission check.

With the processor in Secure state the operations are:

MCR p15,0,<Rd>,c7,c8,4; VA to PA translation with privileged read permission check
 MCR p15,0,<Rd>,c7,c8,5; VA to PA translation with privileged write permission check
 MCR p15,0,<Rd>,c7,c8,6; VA to PA translation with user read permission check
 MCR p15,0,<Rd>,c7,c8,7; VA to PA translation with user write permission check.

4.1.10 c8, TLB maintenance operations

The TLB Operations Register characteristics are:

Purpose	Manages the TLB: <ul style="list-style-type: none"> invalidates all the entries in the TLB invalidates all TLB entries for an area of memory before the OS remaps it invalidates all TLB entries that match an ASID value.
Usage constraints	Only accessible in privileged mode.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-9 on page 4-15.

Table 4-5 shows the defined TLB operations. Select the function to be performed using the Opcode_2 and CRm fields in the MCR instruction used to write CP15 c8.

The Inner Shareable TLB operations, with CRm set to 3, operate on the local core which executed the instruction and are also broadcast to the other cores in the Cortex-A5 MPCore processor. The ARMv7 architecture also defines TLB maintenance operations for instructions with CRm set to c5 and c6. These behave exactly the same as the instructions with CRm set to c7. Writing other Opcode_2 or CRm values is Unpredictable.

Reading from CP15 c8 is Undefined.

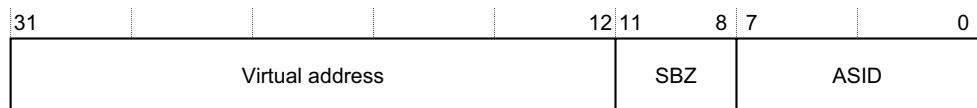
Table 4-5 TLB Operations Register instructions

Description	Mnemonic	Data	Instruction
Invalidate entire Unified TLB Inner Shareable	TLBIALLIS	SBZ	MCR p15, 0, <Rd>, c8, c3, 0
Invalidate Unified TLB entry by VA Inner Shareable	TLBIMVAIS	VA/ASID	MCR p15, 0, <Rd>, c8, c3, 1
Invalidate Unified TLB entry by ASID match Inner Shareable	TLBIASIDIS	ASID	MCR p15, 0, <Rd>, c8, c3, 2
Invalidate Unified TLB entry by VA all ASID Inner Shareable	TLBIMVAAIS	VA	MCR p15, 0, <Rd>, c8, c3, 3
Invalidate entire Unified TLB	TLBIALL	Ignored	MCR p15, 0, <Rd>, c8, c7, 0

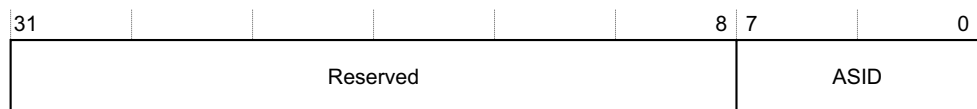
Table 4-5 TLB Operations Register instructions (continued)

Description	Mnemonic	Data	Instruction
Invalidate Unified TLB by VA	TLBIMVA	VA/ASID	MCR p15, 0, <Rd>, c8, c7, 1
Invalidate TLB entries by ASID Match	TLBIASID	ASID	MCR p15, 0, <Rd>, c8, c7, 2
Invalidate TLB entries by VA All ASID	TLBIMVAA	VA	MCR p15, 0, <Rd>, c8, c7, 3

Figure 4-4 shows the bit assignments of the TLB operations that use the Virtual Address as an argument. For Invalidate TLB entry by VA all ASID, the value of the ASID field is ignored.

**Figure 4-4 TLB Operations Register Virtual Address bit assignments**

The Invalidate TLB Entries on ASID Match function requires an ASID as an argument. Figure 4-5 shows the bit assignments.

**Figure 4-5 TLB Operations Register ASID bit assignments**

Functions that update the contents of the TLB occur in program order. Therefore, an explicit data access prior to the TLB function uses the old TLB contents, and an explicit data access after the TLB function uses the new TLB contents. For instruction accesses, TLB updates are guaranteed to have taken effect before the next pipeline flush. This includes ISB operations and exception return sequences.

Invalidate TLB entry by VA

This operation invalidates a single TLB entry which matches both the Virtual Address and ASID provided as arguments. With global entries in the TLB, the supplied ASID value is not checked.

Invalidate TLB entries by ASID match

This is a single operation that invalidates all TLB entries that match the provided ASID value. This function does not invalidate entries marked as global. In the Cortex-A5 MPCore processor, this operation takes several cycles to complete and the instruction is not interruptible.

Invalidate TLB entries by VA all ASID

You can use this Invalidate TLB Entries operation to invalidate an area of memory before remapping. You must perform an Invalidate TLB entries by VA all ASID in each area to be remapped as either section, small page, or large page. This function invalidates TLB entries that match the provided VA regardless of the ASID. The entries can be global or non-global.

4.1.11 c10, Memory region remap

The remap capability falls into two levels, the primary remap, enables the primary memory type (Normal, Device, or Strongly-ordered) to be remapped. For Device and Normal memory, the effect of the S bit can be independently remapped. To provide maximum flexibility, this level of remapping enables regions that were originally not Normal memory to be remapped independently. The remapping is applied to all sources of TLB requests.

After this primary remapping is performed any region that is mapped as Normal memory can have the inner and outer cacheable attributes determined by the *Normal Memory Remap Register* (NMRR).

The memory region remap registers are accessed by:

```
MCR/MRC p15, 0, Rd, c10, c2, 0;access primary memory region remap register
MCR/MRC p15, 0, Rd, c10, c2, 1;access normal memory region remap register
```

These registers are used to remap memory region types. This remapping is enabled when the TRE bit of the *System Control Register* (SCTLR) is set. The remapping takes place on the page table values, and overrides the settings specified in the page tables. The remapping does not take place when the MMU is turned off.

Table 4-6 and Table 4-7 show the encoding used for each memory type.

Table 4-6 shows the primary remapping encodings.

Table 4-6 Primary remapping encodings

Region	Encoding
Strongly-ordered	00
Shared Device	01
Normal Memory	10
Unpredictable	11

Table 4-7 shows the normal remapping encodings.

Table 4-7 Inner or outer region type encodings

Inner or Outer Region	Encoding
Non-cacheable	00
Write-Back, Write-Allocate	01
Write-Through, no Write-Allocate	10
Write-Back, no Write-Allocate	11

4.1.12 c13, Software Thread ID Registers

The Software Thread ID Register characteristics are:

Purpose Provide locations to store the IDs of software threads and processes for OS management purposes. These registers have no effect on processor behavior.

- Usage constraints** There are three 32-bit read and write registers:
- User read and write Thread and Process ID Register, TPIDRURW. Read and write in User and privileged modes.
 - User Read Only Thread and Process ID Register, TPIDRURO. Read only in User mode, read and write in privileged modes.
 - Privileged Only Thread and Process ID Register, TPIDRPRW. Read and write in privileged modes only.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-20 on page 4-20.

You can access the thread registers by reading or writing to CP15 c13 with the Opcode_2 field set to 2, 3, or 4:

MRC p15, 0, <Rd>, c13, c0, 2/3/4; Read Thread ID registers

MCR p15, 0, <Rd>, c13, c0, 2/3/4; Write Thread ID registers

Figure 4-6 shows the Thread ID registers bit assignments.

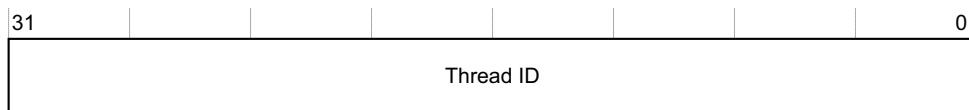


Figure 4-6 Thread ID register bit assignments

Thread ID registers have different access rights depending on Opcode_2 field value:

- Opcode_2 = 2: This register is both user and privileged RW accessible.
- Opcode_2 = 3: This register is user read-only and privileged RW accessible.
- Opcode_2 = 4: This register is privileged RW accessible only.

4.1.13 c15, TLB access and attributes

The *TLB Hitmap Register* (TLBHR) characteristics are:

Purpose Saves and restores the state of the page type hitmap held by the unified TLB.

Usage constraints Only accessible in Secure privileged mode.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-21 on page 4-21.

Table 4-8 shows the TLBHR data format.

Table 4-8 TLBHR data format

Bits	Description
[31:4]	RAZ/WI
[3]	Set if 16MB supersections are present in the TLB
[2]	Set if 1MB sections are present in the TLB
[1]	Set if 16KB pages are present in the TLB
[0]	Set if 4KB pages are present in the TLB

To access the TLBHR, use:

MRC p15, 5, <Rd>, c15, c0, 0; Read TLB Hitmap Register
MCR p15, 5, <Rd>, c15, c0, 0; Write TLB Hitmap Register

4.2 Register summary

This section contains summary tables of the register allocation and reset values of the system control coprocessor where:

- CRn is the register number within CP15
- Op1 is the Opcode_1 value for the register
- CRm is the operational register
- Op2 is the Opcode_2 value for the register.
- Type is:
 - Read-only (RO)
 - Write-only (WO)
 - Read/write (RW)
 - Lock (L).
- Reset is the reset value of the register

All system control coprocessor registers are 32 bits wide. Reserved register addresses are RAZ/WI.

4.2.1 Virtualization

The behavior of the Virtualization Control Register depends on whether the processor is in Secure or Non-secure state.

If the exception occurs when the processor is in Secure state the AMO, IMO, and IFO bits in the Virtualization Control Register are ignored. Whether the exception is taken or not depends solely on the setting of the CPSR A, I, and F bits.

Whether the corresponding exception is taken depends on the setting of the CPSR A, I, and F bits if the exception occurs when the processor is in Non-secure state, if the SCR.EA bit, FIQ bit, or IRQ bit is not set.

If the SCR.EA bit, FIQ bit, or IRQ bit is set, the corresponding exception is trapped to Monitor mode. In this case, the corresponding exception is taken or not depending on the CPSR.A bit, I bit or F bits masked by the AMO, IMO, or IFO bits in the Virtualization Control Register.

4.2.2 c0 summary table

Table 4-9 shows the system control registers you can access when CRn is c0.

Table 4-9 c0 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	MIDR	RO	0x410FC051	Main ID Register on page 4-22
		1	CTR	RO	0x83338003	Cache Type Register on page 4-22
		2	TCMTR	RO	0x00000000	TCM Type Register on page 4-23
		3	TLBTR	RO	0x00000000	TLB Type Register on page 4-24
		4	-	-	-	-
		5	MPIDR	RO	..a	Multiprocessor Affinity Register on page 4-24
		6-7	-	-	-	-
	c1	0	ID_PFR0	RO	0x00001231	Processor Feature Register 0 on page 4-25
		1	ID_PFR1	RO	0x00000011	Processor Feature Register 1 on page 4-25
		2	ID_DFR0	RO	0x02010444	Debug Feature Register 0 on page 4-26
		3	Reserved	-	-	-
		4	ID_MMFR0	RO	0x00100103	Memory Model Features Register 0 on page 4-27
		5	ID_MMFR1	RO	0x40000000	Memory Model Features Register 1 on page 4-28
		6	ID_MMFR2	RO	0x01230000	Memory Model Features Register 2 on page 4-29
	c2	0	ID_ISAR0	RO	0x00101111	Instruction Set Attributes Register 0 on page 4-31
		1	ID_ISAR1	RO	0x13112111	Instruction Set Attributes Register 1 on page 4-32
		2	ID_ISAR2	RO	0x21232041	Instruction Set Attributes Register 2 on page 4-33
		3	ID_ISAR3	RO	0x11112131	Instruction Set Attributes Register 3 on page 4-34
		4	ID_ISAR4	RO	0x00011142	Instruction Set Attributes Register 4 on page 4-35
		5	ID_ISAR5	RO	-	Instruction Set Attributes Register 5 on page 4-36
		6-7	Reserved	-	-	-
	c3-c7	0-7	Reserved	-	-	-
1	c0	0	CCSIDR	RO	-	Cache Size Identification Register on page 4-36
		1	CLIDR	RO	0x09200003	Cache Level ID Register on page 4-37
		7	AIDR	RO	0x00000000	Auxiliary ID Register on page 4-38
2	c0	0	CSSELR	RW	-	Cache Size Selection Register on page 4-39
3-7	c0-c15	0-7	-	-	-	-

a. Dependent on external signal **CLUSTERID** and the number of configured cores in the processor.

4.2.3 c1 summary table

Table 4-10 shows the system control registers you can access when CRn is c1.

Table 4-10 c1 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	SCTLR	RW	0x00C50078	<i>System Control Register</i> on page 4-39
		1	ACTLR ^a	RW	0x00006001	<i>Auxiliary Control Register</i> on page 4-42
		2	CPACR	RW	– ^b	<i>Coprocessor Access Control Register</i> on page 4-44
c1		0	SCR ^c	RW	0x00000000	<i>Secure Configuration Register</i> on page 4-46
		1	SDER ^c	RW	0x00000000	<i>Secure Debug Enable Register</i> on page 4-48
		2	NSACR	RW ^d	– ^e	<i>Non-secure Access Control Register</i> on page 4-49
		3	VCR ^c	RW	0x00000000	<i>Virtualization Control Register</i> on page 4-51

a. RO in Non-secure state if NSACR[18]=0 and RW if NSACR[18]=1.

b. 0x00000000 if NEON present, 0xC0000000 if FPU present, and 0x00000000 for integer only.

c. No access in Non-secure state. See *Virtualization* on page 4-14.

d. This is a read and write register in Secure state and a read-only register in the Non-secure state.

e. 0x00000000 if NEON present, 0x000C000 if FPU present, and 0x00000000 for integer only.

4.2.4 c2 summary table

Table 4-11 shows the system control registers when CRn is c2.

Table 4-11 c2 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	TTBR0	RW	–	<i>Translation Table Base Register 0</i> on page 4-52
		1	TTBR1	RW	–	<i>Translation Table Base Register 1</i> on page 4-53
		2	TTBCR	RW	0x00000000 ^a	<i>Translation Table Base Control Register</i> on page 4-55

a. In Secure state only. You must program the Non-secure version with the required value.

4.2.5 c3 summary table

Table 4-12 shows the system control registers you can access when CRn is c3.

Table 4-12 c3 system control register

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	DACR	RW	–	<i>Domain Access Control Register</i> on page 4-56

4.2.6 c4 summary table

There are no system control registers when CRn is c4.

4.2.7 c5 summary table

Table 4-13 shows the system control registers you can access when CRn is c5.

Table 4-13 c5 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	DFSR	RW	-	<i>Data Fault Status Register on page 4-57</i>
		1	IFSR	RW	-	<i>Instruction Fault Status Register on page 4-59</i>
	c1	0	ADFSR	-	-	<i>Auxiliary Data Fault Status Register on page 4-60</i>
		1	AIFSR	-	-	<i>Auxiliary Instruction Fault Status Register on page 4-61</i>

4.2.8 c6 summary table

Table 4-14 shows the system control registers you can access when CRn is c6.

Table 4-14 c6 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	DFAR	RW	-	<i>Data Fault Address Register on page 4-61</i>
		2	IFAR	RW	-	<i>Instruction Fault Address Register on page 4-62</i>

4.2.9 c7 summary table

Table 4-15 shows the system control registers you can access when CRn is c7.

Table 4-15 c7 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description	
0	c0	4	NOP	WO	-	-	
		c1	0	ICIALLUIS	WO	-	<i>Cache Operations Registers on page 4-4</i>
	6		BPIALLIS	WO	-	-	
	c4	0	PAR	RW	-	<i>Physical Address Register on page 4-62</i>	
	c5	0	0	ICIALLU	WO	-	<i>Cache Operations Registers on page 4-4</i>
			1	ICIMVAU	WO	-	
		4	ISB	WO	-	-	
		6	BPIALL	WO	-	<i>Cache Operations Registers on page 4-4</i>	
		7	BPIMVA	WO	-		
	c6	1	DCIMVAC	WO	-		
		2	DCISW	WO	-		
	c8	0-3	V2PCWPR	WO	-	<i>c7, VA to PA operations on page 4-8</i>	
4-7			V2POWPR	WO	-		

Table 4-15 c7 system control registers (continued)

Op1	CRm	Op2	Name	Type	Reset	Description
0	c10	1	DCCMVAC	WO	-	<i>Cache Operations Registers</i> on page 4-4
		2	DCCSW	WO	-	
		4	DSB	WO	-	-
		5	DMB	WO	-	-
	c11	1	DCCMVAU	WO	-	<i>Cache Operations Registers</i> on page 4-4
	c14	1	DCCIMVAC	WO	-	
		2	DCCISW	WO	-	

4.2.10 c8 summary table

Table 4-16 shows the system control registers you can access when CRn is c8.

Table 4-16 c8 system control register

Op1	CRm	Op2	Name	Type	Reset	Description
0	c3	0	TLBIALLIS	WO	-	<i>c8, TLB maintenance operations</i> on page 4-9
		1	TLBIMVAIS	WO	-	
		2	TLBIASIDIS	WO	-	
		3	TLBIMVAAIS	WO	-	
c5, c6, or c7		0	TLBIALL	WO	-	
		1	TLBIMVA	WO	-	
		2	TLBIASID	WO	-	
		3	TLBIMVAA	WO	-	

4.2.11 c9 summary table

Table 4-17 shows the system control registers you can access when CRn is c9.

Table 4-17 c9 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c12	0	PMCR	RW	0x41052000	Performance Monitor Control Register on page 12-4
		1	PMCNTENSET	RW	0x00000000	Count Enable Set Register on page 12-5
		2	PMCNTENCLR	RW	0x00000000	Count Enable Clear Register on page 12-6
		3	PMOVSr	RW	-	Overflow Flag Status Register on page 12-7
		4	PMSWINC	WO	-	Software Increment Register on page 12-8
		5	PMSELR	RW	0x00000000	Event Counter Selection Register on page 12-9
		6	PMCEID0	RO	0x003FFFFFF	Common Event Identification Registers on page 12-10
		7	PMCEID1	RO	-	
c13		0	PMCCNTR	RW	-	Cycle Count Register on page 12-11
		1 ^a	PMXEVTYPER	RW	-	Event Type Select Register on page 12-12
			PMCCFILTR	RW	-	Cycle Count Filter Control Register on page 12-14
		2	PMXEVCNTR	RW	-	Event Count Registers on page 12-15
c14		0	PMUSERENR	RW ^b	0x00000000	User Enable Register on page 12-16
		1	PMINTENSET	RW	0x00000000	Interrupt Enable Set Register on page 12-17
		2	PMINTENCLR	RW	0x00000000	Interrupt Enable Clear Register on page 12-18

a. Select the use of these registers in the *Event Counter Selection Register* on page 12-9.

b. RO in user mode

Note

See Chapter 12 *Performance Monitoring Unit* for more information on system performance monitoring.

4.2.12 c10 summary table

Table 4-18 shows the system control registers you can access when CRn is c10.

Table 4-18 c10 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c2	0	PRRR	RW	0x00098AA4	c10, Memory region remap on page 4-11
		1	NMRR	RW	0x44E048E0	

4.2.13 c11 summary table

There are no system control registers when CRn is c11.

4.2.14 c12 summary table

Table 4-19 shows the system control registers you can access when CRn is c12.

Table 4-19 c12 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	VBAR	RO	-	<i>Vector Base Address Register</i> on page 4-64
		1	MVBAR	RO	-	<i>Monitor Vector Base Address Register</i> on page 4-65
	c1	0	ISR	RO	-	<i>Interrupt Status Register</i> on page 4-65
		1	VIR	RW	0x00000000	<i>Virtualization Interrupt Register</i> on page 4-66

4.2.15 c13 summary table

Table 4-20 shows the system control registers you can access when CRn is c13.

Table 4-20 c13 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
0	c0	0	FCSEIDR	RO	0x00000000	<i>Fast Context Switch Extension (FCSE)</i> not implemented
		1	CONTEXTIDR	RW	-	<i>Context ID Register</i> on page 4-67
		2	TPIDRURW	RW ^a	-	<i>c13, Software Thread ID Registers</i> on page 4-11
		3	TPIDRURO	RO ^b	-	
		4	TPIDRPRW	RW	-	

a. RW in User mode

b. RO in User mode

4.2.16 c14 summary table

There are no system control registers when CRn is c14.

4.2.17 c15 summary table

Table 4-21 on page 4-21 shows the system control registers you can access when CRn is c15.

Table 4-21 c15 system control registers

Op1	CRm	Op2	Name	Type	Reset	Description
3 ^a	c0	0	Data Register 0	RO	-	-
		1	Data Register 1	RO	-	
	c2	0	Data Cache Tag Read Operation Register	WO	-	
		1	Instruction Cache Tag Read Operation Register	WO	-	
	c4	0	Data Cache Data Read Operation Register	WO	-	
		1	Instruction Cache Data Read Operation Register	WO	-	
		2	TLB Data Read Operation Register	WO	-	
4	c0	0	Configuration Base Address	RO ^b	^c	<i>Configuration Base Address Register</i> on page 4-68
5	c0	0	TLB Hitmap	RW	-	<i>c15, TLB access and attributes</i> on page 4-12

a. See *Direct access to internal memory* on page 7-8 for information on how these registers are used.

b. *Write Ignored* (WI) in Privileged modes and Undefined in User mode.

c. The configuration base address is reset to **PERIPHBASE[31:13]** so that software can determine the location of the Snoop Control Unit registers.

4.3 Register descriptions

This section describes the system registers in the order in which they appear in the summary tables.

4.3.1 Main ID Register

The MIDR characteristics are:

Purpose Returns the device ID code that contains information about the processor.

Usage constraints The MIDR is:

- common to the Secure and Non-secure states.
- only accessible in privileged mode.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-7 shows the MIDR bit assignments.

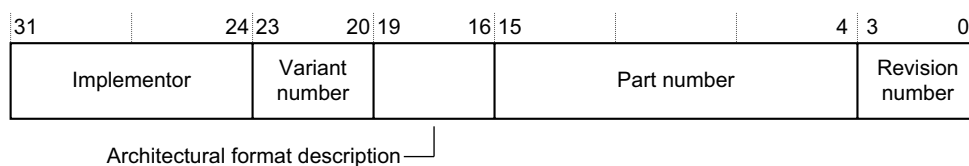


Figure 4-7 MIDR bit assignments

Table 4-22 shows the MIDR bit assignments.

Table 4-22 MIDR bit assignments

Bits	Description
[31:24]	Implementor.
[23:20]	Variant number. In ARM implementations this is the major revision number <i>n</i> of the <i>rnpn</i> revision status.
[19:16]	Architectural format description.
[15:4]	Part number.
[3:0]	Revision. In ARM implementations this is the minor revision number <i>n</i> of the <i>rnpn</i> revision status.

See the reset value in Table 4-9 on page 4-15 for the field values.

To access the MIDR, use:

```
MRC p15, 0, <Rd>, c0, c0, 0; Read Main ID Register
```

4.3.2 Cache Type Register

The CTR characteristics are:

Purpose Provides information about the size and architecture of the cache for the operating system.

- Usage constraints** The CTR is
- common to the Secure and Non-secure states.
 - only accessible in privileged mode.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-8 shows the CTR bit assignments.

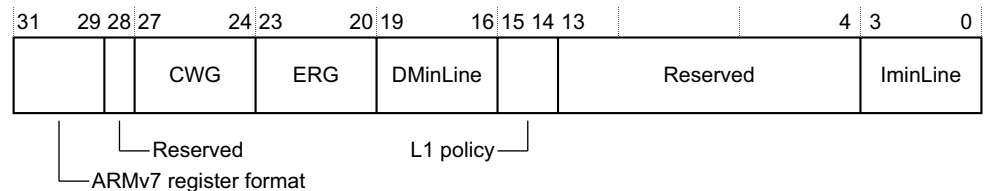


Figure 4-8 CTR bit assignments

Table 4-23 shows the CTR bit assignments.

Table 4-23 CTR bit assignments

Bits	Name	Description
[31:29]	-	ARMv7 register format.
[28]	Reserved	RAZ.
[27:24]	CWG	Cache Writeback Granule. Log ₂ of the number of words of the maximum size of memory that can be overwritten as a result of the eviction of a cache entry that has had a memory location in it modified. b0011 = 8 word granularity for the Cortex-A5 MPCore processor.
[23:20]	ERG	Exclusives Reservation Granule. Log ₂ of the number of words of the maximum size of the reservation granule that has been implemented for the Load-Exclusive and Store-Exclusive instructions. b0011 = 8 word granularity for the Cortex-A5 MPCore processor.
[19:16]	DMinLine	Log ₂ of the number of words in the smallest cache line of all the data and unified caches under the core control. b0011 = 8 words for the Cortex-A5 MPCore processor.
[15:14]	L1 policy	Indicates the level 1 instruction cache policy for indexing and tagging. b10 = virtual index, physical tag, VIPT.
[13:4]	Reserved	RAZ.
[3:0]	IminLine	Log ₂ of the number of words in the smallest cache line of all the instruction caches under the control of the processor. b0011 = 8 words for the Cortex-A5 MPCore processor.

To access the CTR, use:

MRC p15, 0, <Rd>, c0, c0, 1; returns cache details

4.3.3 TCM Type Register

The Cortex-A5 MPCore processor does not implement instruction or data *Tightly Coupled Memory* (TCM), so this register always *Reads-As-Zero* (RAZ).

4.3.4 TLB Type Register

The *Translation Lookaside Buffer* (TLB) Type Register, TLBTR, returns the number of lockable entries for the TLB. The Cortex-A5 MPCore processor does not implement this feature, so this register always RAZ.

4.3.5 Multiprocessor Affinity Register

The MPIDR characteristics are:

Purpose	To identify: <ul style="list-style-type: none"> whether the processor is part of a Cortex-A5 MPCore implementation the target core in a Cortex-A5 MPCore processor.
Usage constraints	The MPIDR is: <ul style="list-style-type: none"> only accessible in privileged mode. common to the Secure and Non-secure states.
Configurations	Available in all configurations. The value of bit [30] indicates a Cortex-A5 MPCore multiprocessor or a uniprocessor configuration.
Attributes	See the register summary in Table 4-9 on page 4-15.

Figure 4-9 shows the MPIDR bit assignments.



Figure 4-9 MPIDR bit assignments

Table 4-24 shows the MPIDR bit assignments.

Table 4-24 MPIDR bit assignments

Bits	Name	Description
[31]	Reserved	Indicates that the register uses the new multiprocessor format. This is always 1.
[30]	U bit	0 = Processor is always part of a multiprocessor system.
[29:12]	Reserved	SBZ.
[11:8]	Cluster ID	Value read in CLUSTERID configuration pins. It identifies a Cortex-A5 MPCore processor in a system with more than one Cortex-A5 MPCore processor present.
[7:2]	Reserved	SBZ.
[1:0]	CPU ID	The value depends on the number of configured cores in the Cortex-A5 MPCore processor. For: <ul style="list-style-type: none"> one Cortex-A5 core, the CPU ID is 0x0 two Cortex-A5 cores, the CPU IDs are 0x0 and 0x1 three Cortex-A5 cores, the CPU IDs are 0x0, 0x1, and 0x2 four Cortex-A5 cores, the CPU IDs are 0x0, 0x1, 0x2, and 0x3.

To access the MPIDR use:

MRC p15, 0, <Rd>, c0, c0, 5 ; read Multiprocessor ID register

4.3.6 Processor Feature Register 0

The ID_PFR0 characteristics are:

Purpose	Provides: <ul style="list-style-type: none"> information about the programmers model. top-level information about the instruction set support for the processor
Usage constraints	Must be interpreted with ID_PFR1.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-9 on page 4-15.

Figure 4-10 shows the ID_PFR0 bit assignments.

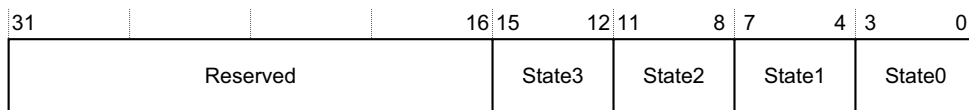


Figure 4-10 ID_PFR0 bit assignments

Table 4-25 shows the ID_PFR0 bit assignments.

Table 4-25 ID_PFR0 bit assignments

Bits	Name	Description
[31:16]	Reserved	RAZ.
[15:12]	State3	0x1 Jazelle RCT supported.
[11:8]	State2	0x2 Jazelle extension interface supported with clearing of J0SCR.CV on exception entry.
[7:4]	State1	0x3 Support for Thumb encoding after the introduction of Thumb-2 technology, and for all 16-bit and 32-bit Thumb basic instructions.
[3:0]	State 0	0x1 32-bit ARM instruction set supported.

To access ID_PFR0, use:

MRC p15, 0, <Rd>, c0, c1, 0

4.3.7 Processor Feature Register 1

The ID_PFR1 characteristics are:

Purpose	Provides information about the execution state support and programmers model for the processor.
Usage constraints	The ID_PFR1 is: <ul style="list-style-type: none"> common to the Secure and Non-secure states only accessible in privileged modes. The ID_PFR1 must be interpreted with ID_PFR0.
Configurations	Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-11 shows the ID_PFR1 Register bit assignments.

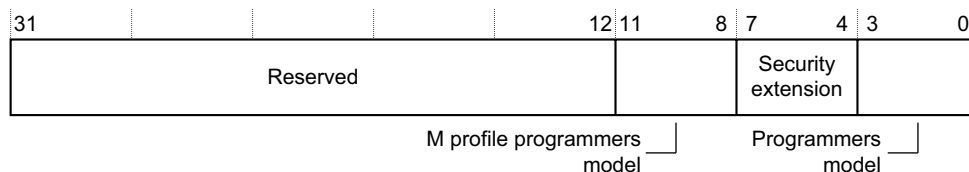


Figure 4-11 ID_PFR1 bit assignments

Table 4-26 shows the ID_PFR1 bit assignments.

Table 4-26 ID_PFR1 bit assignments

Bits	Name	Description
[31:12]	Reserved	RAZ.
[11:8]	M profile programmers model	0x0 Not supported.
[7:4]	Security extensions	0x1 Security extension architecture v1 supported.
[3:0]	Programmers model	0x1 standard ARMv4 programmers model supported.

To access ID_PFR1, use:

```
MRC p15, 0, <Rd>, c0, c1, 1
```

4.3.8 Debug Feature Register 0

The ID_DFR0 characteristics are:

Purpose Provides information about the debug system for the processor.

Usage constraints The ID_DFR0 is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-12 shows the ID_DFR0 bit assignments.

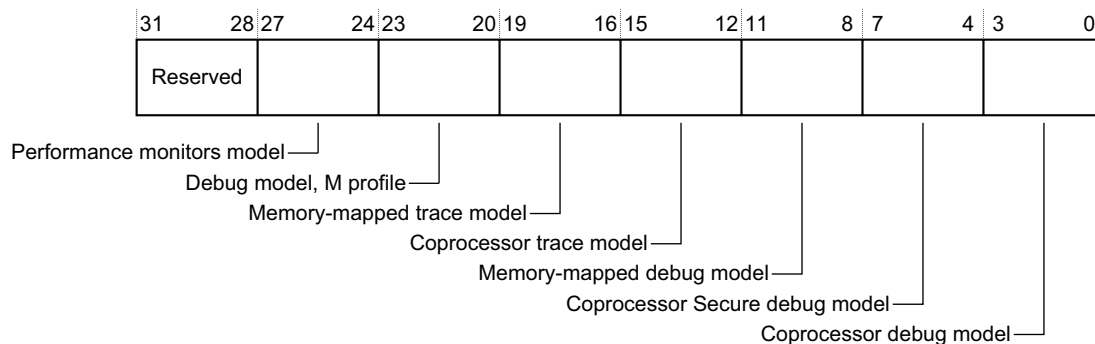


Figure 4-12 ID_DFR0 bit assignments

Table 4-27 shows the ID_DFR0 bit assignments.

Table 4-27 ID_DFR0 bit assignments

Bits	Name	Description
[31:28]	Reserved	RAZ.
[27:24]	Performance monitors model	0x2 Version 2.
[23:20]	Debug model, M profile	0x0 Not supported.
[19:16]	Memory-mapped trace model	0x1 Memory-mapped trace debug model supported.
[15:12]	Coprocessor trace model	0x0 Not supported.
[11:8]	Memory-mapped debug model	0x4 Memory-mapped core debug model supported.
[7:4]	Coprocessor Secure debug model	0x4 Coprocessor based secure debug model supported using CP14.
[3:0]	Coprocessor debug model	0x4 Coprocessor based core debug model supported supported using CP14.

To access ID_DFR0, use:

MRC p15, 0, <Rd>, c0, c1, 2

4.3.9 Auxiliary Feature Register 0

The ID_AFR0 characteristics are:

Purpose Can provide additional information about the features of the processor. Not used in this implementation.

Table 4-28 shows the ID_AFR0 bit assignments.

Table 4-28 ID_AFR0 bit assignments

Bits	Name	Description
[31:0]	-	RAZ/WI

To access the ID_AFR0, use:

MRC p15, 0, <Rd>, c0, c1, 3 ; Read Auxiliary Feature Register 0

4.3.10 Memory Model Features Register 0

The ID_MMFR0 characteristics are:

Purpose Provides information about the memory model, memory management, cache support, and TLB operations of the processor.

Usage constraints The ID_MMFR0 is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-13 on page 4-28 shows the ID_MMFR0 bit assignments.

31	28	27	24	23	20	19	16	15	12	11	8	7	4	3	0
Innermost shareability		FCSE support		Auxiliary registers		TCM support		Shareability levels		Outermost shareability		PMSA support		VMSA support	

Figure 4-13 ID_MMFR0 bit assignments

Table 4-29 shows the ID_MMFR0 bit assignments.

Table 4-29 ID_MMFR0 bit assignments

Bits	Name	Description
[31:28]	Innermost shareability	0x0 Not supported.
[27:24]	FCSE support	0x0 Not supported.
[23:20]	Auxiliary registers	0x1 One Auxiliary Control Register supported.
[19:16]	TCM support	0x0 Not supported.
[15:12]	Shareability levels	0x0 One level of shareability supported.
[11:8]	Outermost shareability	0x1 L1 cache coherency supported.
[7:4]	PMSA support	0x0 Not supported.
[3:0]	VMSA support	0x3 <i>Virtual Memory System Architecture</i> (VMSA) supported including remapping of access permission flags.

To access the ID_MMFR0, use:

MRC p15, 0, <Rd>, c0, c1, 4

4.3.11 Memory Model Features Register 1

The ID_MMFR1 characteristics are:

Purpose Provides information about the memory model, memory management, cache support, and TLB operations of the processor.

Usage constraints The ID_MMFR1 is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-14 shows the ID_MMFR1 bit assignments.

31	28	27	24	23	20	19	16	15	12	11	8	7	4	3	0
Branch Predictor		L1 cache Test and Clean		L1 unified cache		L1 Harvard cache		L1 unified cache s/w		L1 Harvard cache s/w		L1 unified cache VA		L1 Harvard cache VA	

Figure 4-14 ID_MMFR1 bit assignments

Table 4-30 shows the ID_MMFR1 bit assignments.

Table 4-30 ID_MMFR1 bit assignments

Bits	Name	Description
[31:28]	Branch Predictor	0x4 For execution correctness, Branch Predictor requires no flushing at any time.
[27:24]	L1 cache Test and Clean	0x0 L1 data cache test and clean operation not supported.
[23:20]	L1 unified cache	0x0 L1 unified cache clean/invalidate-all operation not supported.
[19:16]	L1 Harvard cache	0x0 L1 data cache clean/invalidate-all operation not supported.
[15:12]	L1 unified cache s/w	0x0 L1 unified cache maintenance operations by set/way not supported.
[11:8]	L1 Harvard cache s/w	0x0 L1 Harvard cache maintenance operations by set/way not supported.
[7:4]	L1 unified cache VA	0x0 L1 unified cache maintenance operations by VA not supported.
[3:0]	L1 Harvard cache VA	0x0 L1 Harvard cache maintenance operations by VA not supported.

To access the ID_MMFR1 use:

MRC p15, 0, <Rd>, c0, c1, 5

4.3.12 Memory Model Features Register 2

The ID_MMFR2 characteristics are:

Purpose	Provides information about the memory model, memory management, cache support, and TLB operations of the processor.
Usage constraints	The ID_MMFR2 is: <ul style="list-style-type: none"> only accessible in privileged modes. common to the Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-9 on page 4-15.

Figure 4-15 shows the ID_MMFR2 bit assignments.

31	28:27	24:23	20:19	16:15	12:11	8	7	4	3	0
HW access flag	WFI stall	Mem barrier	Unified TLB	Harvard TLB	L1 Harvard range	L1Harvard bg prefetch	L1Harvard fg prefetch			

Figure 4-15 ID_MMFR2 bit assignments

Table 4-31 shows the ID_MMFR2 bit assignments.

Table 4-31 ID_MMFR2 bit assignments

Bits	Name	Description
[31:28]	HW access flag	0x0 Not supported.
[27:24]	WFI stall	0x1 <i>Wait For Interrupt</i> (WFI) supported.
[23:20]	Mem barrier	0x2 Supports: <ul style="list-style-type: none"> • <i>Data Synchronization Barrier</i> (DSB) • <i>Instruction Synchronization Barrier</i> (ISB) • <i>Data Memory Barrier</i> (DMB).
[19:16]	Unified TLB	0x3 Supports: <ul style="list-style-type: none"> • invalidate all entries • invalidate TLB entry by VA • invalidate TLB entries by ASID match.
[15:12]	Harvard TLB	0x0 Not supported.
[11:8]	L1 Harvard range	0x0 Not supported.
[7:4]	L1 Harvard background prefetch	0x0 Not supported.
[3:0]	L1 Harvard foreground prefetch	0x0 Not supported.

To access the ID_MMFR2 use:

MRC p15, 0, <Rd>, c0, c1, 6

4.3.13 Memory Model Features Register 3

The ID_MMFR3 characteristics are:

- Purpose** Provides information about the memory model, memory management, cache support, and TLB operations of the processor.
- Usage constraints** The ID_MMFR3 is:
- only accessible in privileged modes.
 - common to the Secure and Non-secure states.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-9 on page 4-15.

Figure 4-16 shows the ID_MMFR3 bit assignments.

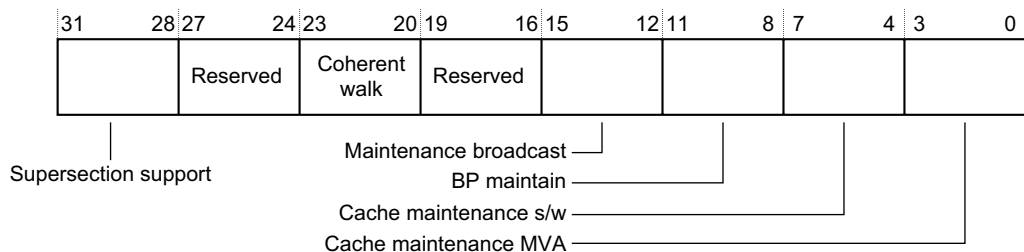


Figure 4-16 ID_MMFR3 bit assignments

Table 4-32 shows the ID_MMFR3 bit assignments.

Table 4-32 ID_MMFR3 bit assignments

Bits	Name	Description
[31:28]	Supersection support	0x0 16MB supersections supported.
[27:24]	Reserved	RAZ.
[23:20]	Coherent walk	0x1 Supported. Updates to translation tables do not require a clean to the point of unification to ensure visibility by subsequent translation table walks.
[19:16]	Reserved	RAZ.
[15:12]	Maintenance broadcast	0x2 Supported. Cache, TLB and Branch prediction operations broadcast.
[11:8]	BP maintain	0x2 Supports: <ul style="list-style-type: none"> invalidate entire branch predictor array invalidate branch predictor by MVA.
[7:4]	Cache maintenance set/way	0x1 Supported.
[3:0]	Cache maintenance MVA	0x1 Supported.

To access the ID_MMFR3 use:

MRC p15, 0, <Rd>, c0, c1, 7

4.3.14 Instruction Set Attributes Register 0

The ID_ISAR0 characteristics are:

- Purpose** Provides information about the instruction set that the processor supports beyond the basic set.
- Usage constraints** The ID_ISAR0 is:
- only accessible in privileged modes.
 - common to the Secure and Non-secure states.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-9 on page 4-15.

Figure 4-17 shows the ID_SAR0 bit assignments.

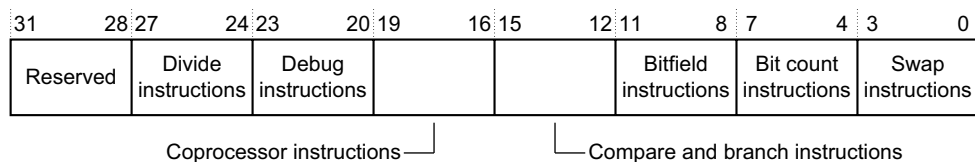


Figure 4-17 ID_ISAR0 bit assignments

Table 4-33 shows the ID_ISAR0 bit assignments.

Table 4-33 ID_ISAR0 bit assignments

Bits	Name	Description
[31:28]	Reserved	RAZ.
[27:24]	Divide instructions	0x0 Integer hardware divide not supported.
[23:20]	Debug instructions	0x1 BKPT supported.
[19:16]	Coprocessor instructions	0x0 Not supported. VFPv4, CP14, and CP15 described elsewhere.
[15:12]	Compare and branch instructions	0x1 CBZ and CBNZ supported.
[11:8]	Bit field instructions	0x1 BFC, BFI, SBFX, and UBFX supported.
[7:4]	Bit count instructions	0x1 CLZ supported.
[3:0]	Swap instructions	0x1 SWP and SWPB supported.

To access the ID_ISAR0 use:

MRC p15, 0, <Rd>, c0, c2, 0

4.3.15 Instruction Set Attributes Register 1

The ID_ISAR1 characteristics are:

Purpose	Provides information about the instruction set that the processor supports beyond the basic set.
Usage constraints	The ID_ISAR1 is: <ul style="list-style-type: none"> only accessible in privileged modes. common to the Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-9 on page 4-15.

Figure 4-18 shows the ID_ISAR1 bit assignments.

31	28:27	24:23	20:19	16:15	12:11	8	7	4	3	0
Jazelle instructions	Inter-working instructions	Immediate instructions	ITE instructions	Extend instructions	Exception 2 instructions	Exception 1 instructions	Endianness instructions			

Figure 4-18 ID_ISAR1 bit assignments

Table 4-34 shows the ID_ISAR1 bit assignments.

Table 4-34 ID_ISAR1 bit assignments

Bits	Name	Description
[31:28]	Jazelle instructions	0x1 BXJ and J bit in PSRs supported.
[27:24]	Interwork instructions	0x3 ARM/Thumb interworking instructions supported. BX, BLX, T bit in PSRs PC loads and DP instructions have BX-like behavior
[23:20]	Immediate instructions	0x1 Special immediate-generating instructions supported.

Table 4-34 ID_ISAR1 bit assignments (continued)

Bits	Name	Description
[19:16]	IfThen instructions	0x1 Thumb IT blocks supported.
[15:12]	Extend instructions	0x2 All supported
[11:8]	Exception2 instructions	0x1 SRS, RFE, and CPS supported.
[7:4]	Exception1 instructions	0x1 (LDM(2), LDM(3), and STM(2) supported.
[3:0]	Endian instructions	0x1 BE8 endian change supported with SETEND.

To access the ID_ISAR1, use:

MRC p15, 0, <Rd>, c0, c2, 1

4.3.16 Instruction Set Attributes Register 2

The ID_ISAR2 characteristics are:

Purpose Provides information about the instruction set that the processor supports beyond the basic set.

Usage constraints The ID_ISAR2 is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-19 shows the ID_ISAR2 bit assignments.

31	28	27	24	23	20	19	16	15	12	11	8	7	4	3	0
Reversal instructions	PSR instructions		Unsigned multiply instructions	Signed multiply instructions		Multiply instructions		Interruptible instructions	Memory hint instructions		Load and store instructions				

Figure 4-19 ID_ISAR2 bit assignments

Table 4-35 shows the ID_SAR2 bit assignments.

Table 4-35 ID_ISAR2 bit assignments

Bits	Name	Description
[31:28]	Reversal instructions	0x2 Reversal instructions REV, REV16, REVSH, and RBIT supported.
[27:24]	PSR instructions	0x1 PSR instructions MRS and MSR, and exception return data-processing instructions supported.
[23:20]	Multiply instructions (advanced, unsigned)	0x2 Long multiply instructions and UMAAL supported.
[19:16]	Multiply instructions (advanced, signed)	0x3 Multiply instructions SMULL, SMAL, SMLABB, SMLABT, SMLALBB, SMLALBT, SMLALTB, SMLALTT, SMLATB, SMLATT, SMLAWB, SMLAWT, SMULBB, SMULBT, SMULTB, SMULTT, SMULWB, SMULWT, and Q flag in PSRs supported.
[15:12]	Multiply instructions	0x2 Multiply instructions MUL, MLA, and MLS supported.

Table 4-35 ID_ISAR2 bit assignments (continued)

Bits	Name	Description
[11:8]	Multi-access interruptible instructions	0x0 Interrupting of multi-cycle operations not supported.
[7:4]	Memory hint instructions	0x4 memory hint instructions PLD, PLI, and PLDW supported.
[3:0]	Load and store instructions	0x1 Load and store instructions LDRD or STRD supported.

To access the ID_ISAR2 use:

MRC p15, 0, <Rd>, c0, c2, 2

4.3.17 Instruction Set Attributes Register 3

The ID_ISAR3 characteristics are:

Purpose Provides information about the instruction set that the processor supports beyond the basic set.

Usage constraints The ID_ISAR3 is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-20 shows the ID_ISAR3 bit assignments.

31	28	27	24	23	20	19	16	15	12	11	8	7	4	3	0
ThumbEE extension instructions	NOP instructions		Thumb copy instructions	Table branch instructions	Exclusive instructions		SVC instructions		SIMD instructions		Saturate instructions				

Figure 4-20 ID_ISAR3 bit assignments

Table 4-36 shows the ID_ISAR3 bit assignments.

Table 4-36 ID_ISAR3 bit assignments

Bits	Name	Description
[31:28]	Thumb-2 Executable Environment Extension instructions	0x1 Thumb-2 Executable Environment Extension instructions supported
[27:24]	True NOP instructions	0x1 True no-operation instruction NOP32 supported.
[23:20]	Thumb copy instructions	0x1 Thumb copy instruction Thumb MOV(3) low reg -> low reg and CPY alias supported.
[19:16]	Table branch instructions	0x1 Thumb table branch instruction TBB and TBH supported
[15:12]	Exclusive instructions	0x2 Exclusive instructions LDREX, STREX, LDRBEX, STRBEX, LDRHEX, STRHEX, LDRDEX, STRDEX, and CLREX supported.
[11:8]	SVC instructions	0x1 Supported.
[7:4]	SIMD instructions	0x3 All supported.
[3:0]	Saturate instructions	0x1 Saturate instructions QADD, QDADD, QDSUB, and QSUB, and Q flag in PSRs supported.

To access the ID_ISAR3 use:

MRC p15, 0, <Rd>, c0, c2, 3

4.3.18 Instruction Set Attributes Register 4

The ID_ISAR4 characteristics are:

Purpose Provides information about the instruction set that the processor supports beyond the basic set.

Usage constraints The ID_ISAR4 is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-21 shows the ID_ISAR4 bit assignments.

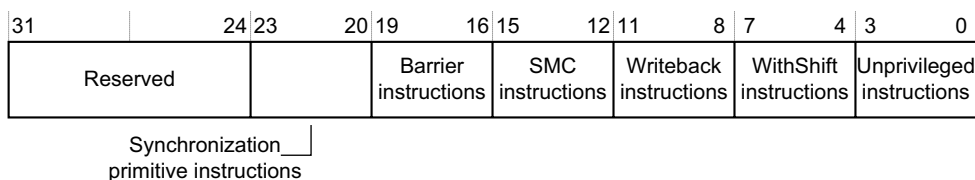


Figure 4-21 ID_ISAR4 bit assignments

Table 4-37 shows the ID_ISAR4 bit assignments.

Table 4-37 ID_ISAR4 bit assignments

Bits	Name	Description
[31:24]	Reserved	RAZ.
[23:20]	Synchronization primitive instructions	0x0 Synchronization primitive instructions supported.
[19:16]	Barrier instructions	0x1 Barrier instructions DMB, DSB, and ISB supported.
[15:12]	SMC instructions	0x1 <i>Secure Monitor Call</i> (SMC) instructions supported.
[11:8]	Write-back instructions	0x1 All defined write-back addressing modes supported.
[7:4]	With-shift instructions	0x4 Immediate and register control shifted operations supported: <ul style="list-style-type: none"> • shifts of loads and stores over the range LSL 0-3 • constant shift options • register-controlled shift options.
[3:0]	Unprivileged instructions	0x2 Unprivileged load/store instructions LDRT and STRT supported.

To access the ID_ISAR4 use:

MRC p15, 0, <Rd>, c0, c2, 4

4.3.19 Instruction Set Attributes Register 5

The ID_ISAR5 characteristics are:

Purpose	Provides information about the instruction set that the processor supports beyond the basic set.
Usage constraints	The ID_ISAR5 is: <ul style="list-style-type: none"> only accessible in privileged modes. common to the Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-9 on page 4-15.

Table 4-38 shows the ID_ISAR5 bit assignments.

Table 4-38 ID_ISAR5 bit assignments

Bits	Name	Description
[31:0]	Reserved	RAZ

To access the ID_ISAR5 use:

MRC p15, 0, <Rd>, c0, c2, 5

4.3.20 Instruction Set Attributes Registers 6-7

ID_ISAR6 and ID_ISAR7 are reserved, and read as 0x00000000.

4.3.21 Cache Size Identification Register

The CCSIDR characteristics are:

Purpose	Provides information about the architecture of the caches selected by the <i>Cache Size Selection Register</i> on page 4-39.
Usage constraints	The CCSIDR is: <ul style="list-style-type: none"> only accessible in privileged modes. common to the Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-9 on page 4-15.

Figure 4-22 shows the CCSIDR bit assignments.

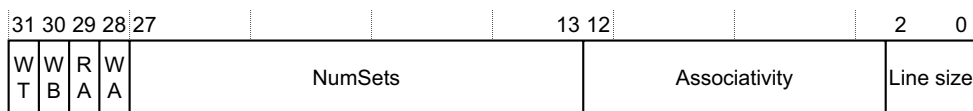


Figure 4-22 CCSIDR bit assignments

Table 4-39 shows the CSSIDR bit assignments.

Table 4-39 CCSIDR bit assignments

Bits	Name	Description																		
[31]	WT	Write-Through not supported. Read as 0x0.																		
[30]	WB	Write-Back supported only for L1 data cache. Read as: 0x1 for data cache 0x0 for instruction cache.																		
[29]	RA	Cache read allocation supported. Read as 0x1.																		
[28]	WA	Write allocation supported only for L1 data cache. Read as: 0x1 for data cache 0x0 for instruction cache.																		
[27:13]	NumSets	Indicates number of cache sets. The number of sets depends on the cache size and whether data or instruction cache is selected using the Cache Size Selection Register:																		
		<table border="1"> <thead> <tr> <th>Cache size</th> <th>Data</th> <th>Instruction</th> </tr> </thead> <tbody> <tr> <td>4KB</td> <td>0x1F</td> <td>0x3F</td> </tr> <tr> <td>8KB</td> <td>0x3F</td> <td>0x7F</td> </tr> <tr> <td>16KB</td> <td>0x7F</td> <td>0xFF</td> </tr> <tr> <td>32KB</td> <td>0xFF</td> <td>0x1FF</td> </tr> <tr> <td>64KB</td> <td>0x1FF</td> <td>0x3FF</td> </tr> </tbody> </table>	Cache size	Data	Instruction	4KB	0x1F	0x3F	8KB	0x3F	0x7F	16KB	0x7F	0xFF	32KB	0xFF	0x1FF	64KB	0x1FF	0x3FF
Cache size	Data	Instruction																		
4KB	0x1F	0x3F																		
8KB	0x3F	0x7F																		
16KB	0x7F	0xFF																		
32KB	0xFF	0x1FF																		
64KB	0x1FF	0x3FF																		
[12:3]	Associativity	Indicates cache associativity. Read as: 0x3 for 4-way data cache 0x1 for 2-way instruction cache.																		
[2:0]	LineSize	Indicates number of words per line. 0x1 = Eight words per line.																		

To access the CCSIDR, use:

MRC p15, 1, <Rd>, c0, c0, 0; Read current Cache Size Identification Register

If the CSSELR reads the instruction cache values, bits [31:28] are b0010.

If the CSSELR reads the data cache values, bits [31:28] are b0111. See *Cache Size Selection Register* on page 4-39.

4.3.22 Cache Level ID Register

The CLIDR characteristics are:

Purpose Indicates the cache levels that are implemented.

Usage constraints The CLIDR is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-23 on page 4-38 shows the CLIDR bit assignments.

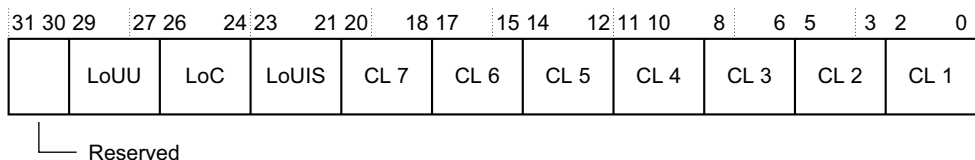


Figure 4-23 CLIDR bit assignments

Table 4-40 shows the CLIDR bit assignments.

Table 4-40 CLIDR bit assignments

Bits	Name	Description
[31:30]	Reserved	RAZ
[29:27]	LoUU	b001 = Level of Unification Uniprocessor
[26:24]	LoC	b001 = Level of Coherency
[23:21]	LoUIS	b001 = Level of Unification Inner Shared
[20:18]	CL 7	b000 = No cache at CL 7
[17:15]	CL 6	b000 = No cache at CL 6
[14:12]	CL 5	b000 = No cache at CL 5
[11:9]	CL 4	b000 = No cache at CL 4
[8:6]	CL 3	b000 = No cache at CL 3
[5:3]	CL 2	b000 = No cache at CL 2
[2:0]	CL 1	b011 = Separate instruction and data caches at CL 1

To access the CLIDR, use:

MRC p15, 1, <Rd>, c0, c0, 1 ; Read CLIDR

4.3.23 Auxiliary ID Register

The AIDR characteristics are:

Purpose Provides implementation-specific information.

Usage constraints The AIDR is:

- only accessible in privileged modes.
- common to the Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Table 4-41 shows the AIDR bit assignments.

Table 4-41 AIDR bit assignments

Bits	Name	Description
[31:0]	Reserved	RAZ

To access the AIDR, use:

MRC p15, 1, <Rd>, c0, c0, 7 ; Read Auxiliary ID Register

———— **Note** —————

The AIDR is not used in this implementation.

4.3.24 Cache Size Selection Register

The CSSELR characteristics are:

Purpose Selects the cache described by the *Cache Size Identification Register* on page 4-36.

Usage constraints The CSSELR is:

- only accessible in privileged modes.
- banked for Secure and Non-secure states

Configurations Available in all configurations.

Attributes See the register summary in Table 4-9 on page 4-15.

Figure 4-24 shows the CSSELR bit assignments.

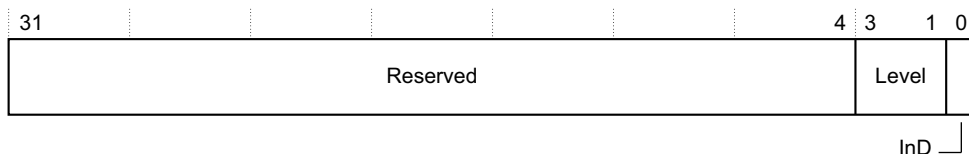


Figure 4-24 CSSELR bit assignments

Table 4-42 shows the CSSELR bit assignments.

Table 4-42 CSSELR bit assignments

Bits	Name	Description
[31:4]	Reserved	UNP or SBZ
[3:1]	Level	Cache level selected RAZ/WI There is only one level of cache in the Cortex-A5 MPCore processor so the value for this field is b000.
[0]	InD	0x1 = Instruction cache 0x0 = Data cache.

To access the CSSELR, use:

MRC p15, 2, <Rd>, c0, c0, 0 ; Read CSSELR

MCR p15, 2, <Rd>, c0, c0, 0 ; Write CSSELR

4.3.25 System Control Register

The SCTLR characteristics are:

Purpose Provides control and configuration of:

- memory alignment and endianness

- memory protection and fault behavior
- MMU and cache enables
- interrupts and behavior of interrupt latency
- location for exception vectors
- program flow prediction.

Usage constraints The SCTLR is:

- only accessible in privileged modes
- banked, with some bits common to the Secure and Non-secure copies of the register.

Attempts to read or write the SCTLR from Secure or Non-secure User modes result in an Undefined instruction exception.

Attempts to write to this register in secure privileged modes when **CP15SDISABLE** is HIGH result in an Undefined instruction exception, see *Security Extensions write access disable* on page 3-10.

Attempts to modify read-only bits are ignored.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-10 on page 4-16.

Figure 4-25 shows the SCTLR bit assignments.

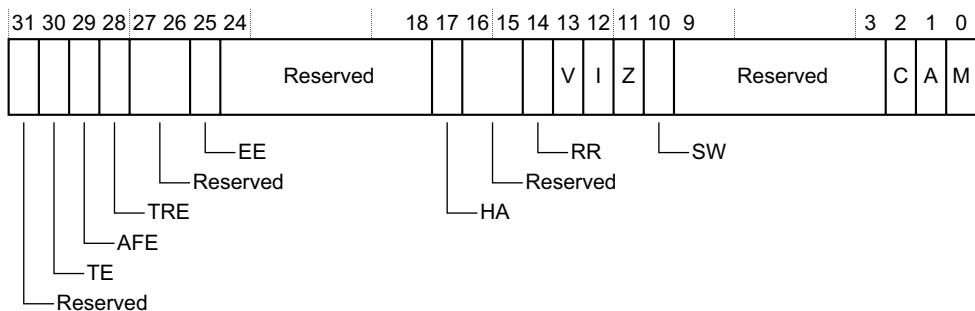


Figure 4-25 SCTLR bit assignments

Table 4-43 shows the SCTLR bit assignments.

Table 4-43 SCTLR bit assignments

Bits	Name	Access	Description
[31]	Reserved	-	RAZ/WI.
[30]	TE	Banked	TE, Thumb exception enable: 0 = exceptions including reset are handled in ARM state. 1 = exceptions including reset are handled in Thumb state. The TEINIT signal defines the reset value.
[29]	AFE	Banked	This is the Access Flag Enable bit. 0 = Full access permissions behavior. This is the reset value. The software maintains binary compatibility with ARMv6K behavior. 1 = Simplified access permissions behavior. The Cortex-A5 MPCore processor redefines the AP[0] bit as an access flag. You must invalidate the TLB after changing the AFE bit.

Table 4-43 SCTLR bit assignments (continued)

Bits	Name	Access	Description
[28]	TRE	Banked	This bit controls the TEX remap functionality in the MMU. 0 = TEX remap disabled. This is the reset value. 1 = TEX remap enabled.
[27:26]	Reserved	-	RAZ/WI
[25]	EE bit	Banked	Determines the value the CPSR.E bit is set to on an exception: 0 = Set to 0, little-endian. sets the reset value. 1 = Set to 1, big-endian. This value also indicates the endianness of the translation table data for translation table look-ups.
[24]	Reserved	-	RAZ/WI.
[23:22]	Reserved	-	RAO/WI.
[21]	Reserved	-	RAZ/WI.
[20:19]	Reserved	-	RAZ/WI.
[18]	Reserved	-	RAO/WI.
[17]	HA	-	RAZ/WI. Hardware management access flag disabled. The Cortex-A5 MPCore processor does not support this feature.
[16]	Reserved	-	RAO/WI
[15]	Reserved	-	RAZ/WI
[14]	RR	-	RAZ/WI. Cache replacement strategy. The Cortex-A5 processor only supports a fixed random replacement strategy.
[13]	V	Banked	Vectors bit. This bit selects the base address of the exception vectors: 0 = Normal exception vectors, base address 0x00000000. This base address can be remapped. 1 = High exception vectors, Hivecs, base address 0xFFFF0000. This base address is never remapped. At reset the value for this bit is taken from VINITHI .
[12]	I bit	Banked	Determines if instructions can be cached at any available cache level: 0 = instruction caching disabled at all levels. This is the reset value. 1 = instruction caching enabled.
[11]	Z bit	Banked	RAO/WI. Program flow prediction control. Branch prediction is always enabled on the Cortex-A5 MPCore processor when the MMU is enabled.
[10]	SW bit	Banked	SWP/SWPB Enable bit: 0 = SWP and SWPB are Undefined. This is the reset value. 1 = SWP and SWPB perform normally.
[9:7]	Reserved	-	RAZ/WI.
[6:3]	Reserved	-	RAO/WI.

Table 4-43 SCTLR bit assignments (continued)

Bits	Name	Access	Description
[2]	C bit	Banked	Determines if data can be cached at any available cache level: 0 = data caching disabled at all levels. This is the reset value. 1 = data caching enabled.
[1]	A bit	Banked	Enables strict alignment of data to detect alignment faults in data accesses: 0 = strict alignment fault checking disabled. This is the reset value. 1 = strict alignment fault checking enabled.
[0]	M bit	Banked	Enables the MMU: 0 = MMU disabled. This is the reset value. 1 = MMU enabled.

To access the SCTLR, use:

MRC p15, 0, <Rd>, c1, c0, 0 ; Read SCTLR
MCR p15, 0, <Rd>, c1, c0, 0 ; Write SCTLR

4.3.26 Auxiliary Control Register

The ACTLR characteristics are:

Purpose Controls extended processor functionality from software, such as:

- behavior of the direct and indirect branch prediction in the *Prefetch Unit* (PFU)
- the limited dual issue capability of the *Data Processing Unit* (DPU)
- coherency mode, *Symmetric Multiprocessing* (SMP) or *Asymmetric Multiprocessing* (AMP).

Usage constraints The ACTLR is:

- Only accessible in privileged modes.
- Common to the Secure and Non-secure states.
- RW in Secure state
- RO in Non-secure state if NSACR.NS_SMP=0
- RW in Non-secure state if NSACR.NS_SMP=1. In this case all bits are Write Ignore except for the SMP bit.

Attempts to write to this register in Secure privileged mode when **CP15SDISABLE** is HIGH result in an Undefined instruction exception, see *Security Extensions write access disable* on page 3-10.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-10 on page 4-16.

Figure 4-26 on page 4-43 shows the ACTLR bit assignments.

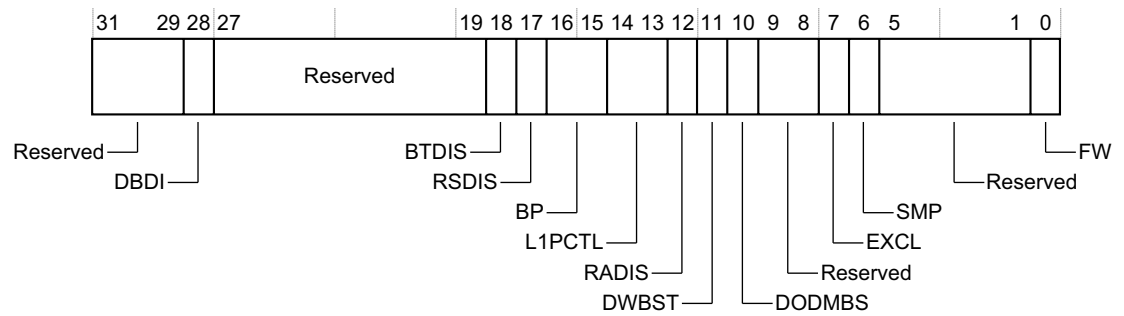


Figure 4-26 ACTLR bit assignments

Table 4-44 shows the ACTLR bit assignments.

Table 4-44 ACTLR bit assignments

Bits	Name	Description
[31:29]	Reserved	RAZ/WI.
[28]	DBDI	Disable branch dual issue.
[27:19]	Reserved	RAZ/WI.
[18]	BTDIS	Disable indirect <i>Branch Target Address Cache</i> (BTAC).
[17]	RSDIS	Disable return stack operation.
[16:15]	BP	Branch prediction policy: 00 = Normal operation 01 = Branch always taken 10 = Branch always not taken 11 = Reserved (Unpredictable).
[14:13]	L1PCTL	L1 Data prefetch control. The value of this field determines the maximum number of outstanding data prefetches allowed in the L1 memory system, not counting those generated by software load/PLD instructions: 00 = prefetch disabled 01 = 1 outstanding prefetch allowed 10 = 2 outstanding prefetches allowed 11 = 3 outstanding prefetches allowed.
[12]	RADIS	Disable Data Cache read-allocate mode. See <i>Read allocate mode</i> on page 2-5.
[11]	DWBST	Disable data write bursts to normal non-cacheable memory. Set in conjunction with RADIS to disable data write bursts to cacheable memory..
[10]	DODMBS	Disable optimized Data Memory Barrier behavior.
[9:8]	Reserved	RAZ/WI.
[7]	EXCL ^a	Exclusive L1/L2 cache control. The exclusive cache configuration does not permit data to reside in the L1 and L2 caches at the same time. The exclusive cache configuration provides support for only caching data on an eviction from L1 when the inner cache attributes are Write-Back, Cacheable and allocated in L1. For this feature to operate correctly, the L2 cache controller must also be configured for exclusive caching.

Table 4-44 ACTLR bit assignments (continued)

Bits	Name	Description
[6]	SMP	Enable data coherency with other cores in the Cortex-A5 MPCore processor. When this bit is reset, data requests with Inner Cacheable shared attributes are treated as Non-cacheable. 0 = disabled. 1 = enabled.
[5:1]	Reserved	RAZ/WI.
[0]	FW	Cache and TLB maintenance broadcast: 0 = disabled. 1 = enabled. The SMP bit must also be set in the ACTLR for Cache and TLB maintenance operations to be broadcast by the core and received from other cores in the Cortex-A5 MPCore processor.

- a. This feature must only be enabled when the Cortex-A5 MPCore processor AXI master interface is directly connected to a PL310 L2 cache controller.

To access the ACTLR you must use a read modify write technique. To access the ACTLR, use:

MRC p15, 0, <Rd>, c1, c0, 1 ; Read ACTLR
MCR p15, 0, <Rd>, c1, c0, 1 ; Write ACTLR

4.3.27 Coprocessor Access Control Register

The CPACR characteristics are:

Purpose Sets access rights for coprocessors CP10 and CP11, that support the VFP and Advanced SIMD extensions, if implemented.

———— **Note** —————

This register has no effect on access to CP14, the debug control coprocessor, or CP15, the system control coprocessor.

Usage constraints The CPACR is:

- only accessible in privileged modes
- common to Secure and Non-secure states.

Behavior is unpredictable if the value of the CP11 field is not the same as the value of the CP10 field.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-10 on page 4-16.

Figure 4-27 shows the CPACR bit assignments.

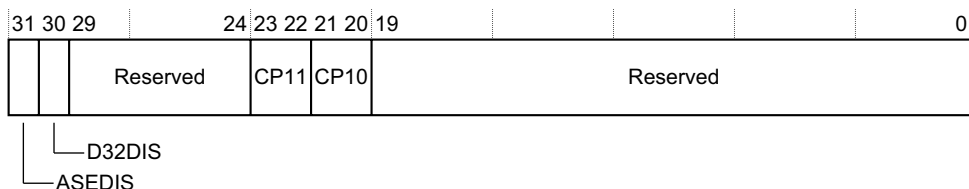


Figure 4-27 CPACR bit assignments

Table 4-45 shows the CPACR bit assignments.

Table 4-45 CPACR bit assignments

Bits	Name	Description
[31]	ASEDIS	Disable Advanced SIMD Extension functionality: 0 = All Advanced SIMD and VFP instructions execute normally. 1 = All Advanced SIMD instructions that are not VFP instructions are Undefined. See the <i>Cortex-A5 Floating-Point Unit Technical Reference Manual</i> and <i>Cortex-A5 NEON Media Processing Engine Technical Reference Manual</i> for more information. If implemented with floating point only, no NEON, this bit is RAO/WI. If implemented without both floating point and NEON, this bit is UNK/SBZP.
[30]	D32DIS	Disable use of registers D16-D31 of the VFP register file: 0 = All instructions accessing D0-D31 execute normally. 1 = Any VFP instruction that attempts to access any of registers D16-D31 is undefined. See the <i>Cortex-A5 Floating-Point Unit Technical Reference Manual</i> and <i>Cortex-A5 NEON Media Processing Engine Technical Reference Manual</i> for more information. If implemented with floating point only, no NEON, this bit is RAO/WI. If implemented without both floating point and NEON, this bit is UNK/SBZP.
[29:24]	Reserved	RAZ/WI.
[23:22]	CP11	Defines access permissions for the coprocessor. Access denied is the reset condition and is the behavior for nonexistent coprocessors. 00 = Access denied. This is the reset value. Attempted access generates an Undefined instruction exception. 01 = Privileged mode access only. 10 = Reserved. 11 = Privileged and User mode access.
[21:20]	CP10	Defines access permissions for the coprocessor. Access denied is the reset condition and is the behavior for nonexistent coprocessors. 00 = Access denied. This is the reset value. Attempted access generates an Undefined instruction exception. 01 = Privileged mode access only. 10 = Reserved. 11 = Privileged and User mode access.
[19:0]	Reserved	RAZ/WI.

Access to coprocessors in the Non-secure state depends on the permissions set in the *Non-secure Access Control Register* on page 4-49.

Attempts to read or write the CPACR access bits depend on the corresponding bit for each coprocessor in *Non-secure Access Control Register* on page 4-49. Table 4-46 shows the results of attempted access to coprocessor access bits for each mode.

Table 4-46 Results of access to the CPACR

NSACR[11:10]	Secure privileged	Non-secure privileged	Secure or Non-secure User
b00	RW	RAZ/WI	Access prohibited ^a
b01	RW	RW	Access prohibited ^a

a. User privilege access generates an Undefined instruction exception.

To access the CPACR, use:

MRC p15, 0, <Rd>, c1, c0, 2 ; Read Coprocessor Access Control Register
MCR p15, 0, <Rd>, c1, c0, 2 ; Write Coprocessor Access Control Register

You must execute an ISB immediately after an update of the CPACR. See Memory Barriers in the *ARM Architecture Reference Manual*. You must not attempt to execute any instructions that are affected by the change of access rights between the ISB and the register update.

To determine if any particular coprocessor exists in the system, write the access bits for the coprocessor of interest with b11. If the coprocessor does not exist in the system the access rights will remain set to b00.

———— **Note** —————

You must enable both CP10 and CP11 before accessing any NEON or VFP system registers.

4.3.28 Secure Configuration Register

The SCR characteristics are:

Purpose Contains the fields used by the TrustZone secure monitor to control the overall Secure or Non-secure state of the Cortex-A5 MPCore processor. They can be used to access the banked CP15 registers and also to alter the behavior of the CPU when external asynchronous events are detected.

Usage constraints The SCR is:

- only accessible in privileged modes
- only accessible in Secure state.

An attempt to access the SCR from any state other than secure privileged results in an Undefined instruction exception.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-10 on page 4-16.

Figure 4-28 shows the SCR bit assignments.

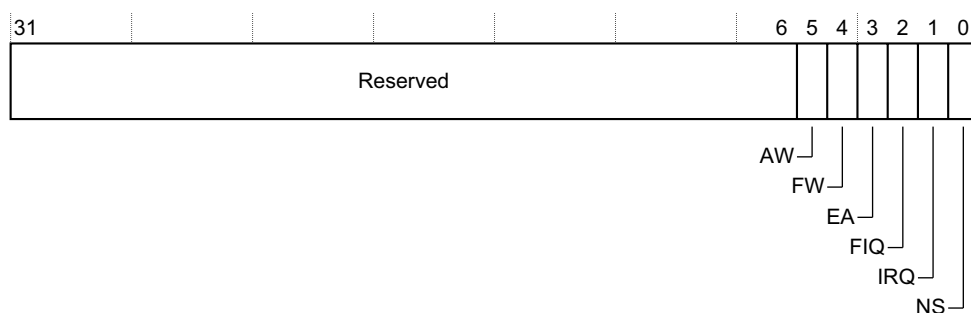


Figure 4-28 SCR bit assignments

Table 4-47 shows the SCR bit assignments.

Table 4-47 SCR bit assignments

Bits	Name	Description
[31:6]	Reserved	RAZ/WI.
[5]	AW	Determines if the A bit in the CPSR can be modified when in the Non-secure state: 0 = disable modification of the A bit in the CPSR in the Non-secure state. This is the reset value. 1 = enable modification of the A bit in the CPSR in the Non-secure state. See Table 4-49 on page 4-48 for more information.
[4]	FW	Determines if the F bit in the CPSR can be modified when in the Non-secure state: 0 = disable modification of the F bit in the CPSR in the Non-secure state. This is the reset value. 1 = enable modification of the F bit in the CPSR in the Non-secure state. See Table 4-48 for more information.
[3]	EA	Determines external abort behavior for Secure and Non-secure states: 0 = branch to abort mode on an external abort exception. This is the reset value. 1 = branch to Monitor mode on an external abort exception. When this bit is set to 1, and an external abort causes entry to Monitor mode, fault information is written to the Secure versions of the Fault Status and Fault Address registers. See Table 4-49 on page 4-48 for more information.
[2]	FIQ	Determines FIQ behavior for Secure and Non-secure states: 0 = branch to FIQ mode on an FIQ exception. This is the reset value. 1 = branch to Monitor mode on an FIQ exception. See Table 4-48 for more information.
[1]	IRQ	Determines IRQ behavior for Secure and Non-secure states: 0 = branch to IRQ mode on an IRQ exception. This is the reset value. 1 = branch to Monitor mode on an IRQ exception.
[0]	NS	In modes other than Monitor mode, indicates whether the processor is in Secure or Non-secure state. In Monitor mode, indicates whether CP15 register accesses are to the Secure or the Non-secure view of the registers.: 0 = Secure. This is the reset value. 1 = Non-secure.

The values of the bits in the SCR have security implications. Table 4-48 shows the results for combinations of the FW and FIQ bits.

Table 4-48 Operation of the SCR FW and FIQ bits

FW	FIQ	Description
1	0	FIQs handled locally.
0	1	FIQs can be configured to give deterministic secure interrupts.
1	1	Non-secure state able to make denial of service attack. Do not use this combination of values.
0	0	The core might enter an infinite loop for Non-secure FIQ. Do not use this combination of values.

Table 4-49 shows the results for combinations of the AW and EA bits.

Table 4-49 Operation of the SCR AW and EA bits

AW	EA	Description
1	0	External aborts handled locally.
0	1	All external aborts trapped to Monitor mode.
1	1	All external aborts trapped to Monitor mode but the Non-secure state can hide secure aborts from the Monitor. Do not use this combination of values.
0	0	The core can unexpectedly enter an abort mode in the Non-secure state. Do not use this combination of values.

To access the SCR, use:

MRC p15, 0, <Rd>, c1, c1, 0 ; Read SCR data
MCR p15, 0, <Rd>, c1, c1, 0 ; Write SCR data

4.3.29 Secure Debug Enable Register

The SDER characteristics are:

Purpose Controls processor debug.

Usage constraints The SDER is:

- only accessible in privileged modes
- only accessible in Secure state.

Accesses in Non-secure state cause an Undefined instruction exception.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-10 on page 4-16.

Figure 4-29 shows the SDER bit assignments.

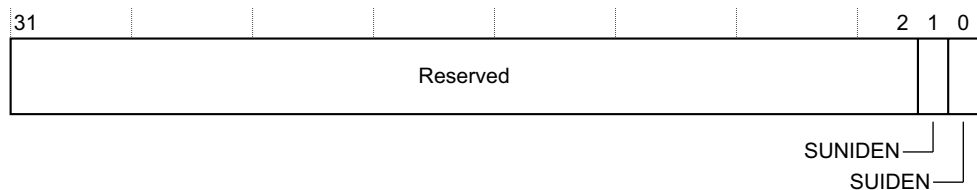


Figure 4-29 SDER bit assignments

Table 4-50 shows the SDER bit assignments.

Table 4-50 SDER bit assignments

Bits	Name	Description
[31:2]	Reserved	RAZ.
[1]	SUNIDEN	Secure User Non-Invasive Debug Enable: 0 = non-invasive debug not permitted in Secure User mode. This is the reset value. 1 = non-invasive debug permitted in Secure User mode.
[0]	SUIDEN	Secure User Invasive Debug Enable: 0 = invasive debug not permitted in Secure User mode. This is the reset value. 1 = invasive debug permitted in Secure User mode.

To access the SDER, use:

MRC p15, 0, <Rd>, c1, c1, 1; Read Secure debug enable Register
MCR p15, 0, <Rd>, c1, c1, 1; Write Secure debug enable Register

4.3.30 Non-secure Access Control Register

The NSACR characteristics are:

Purpose Sets the Non-secure access permission for coprocessors.

Usage constraints The NSACR is:

- only accessible in privileged modes
- a read and write register in Secure state
- a read-only register in Non-secure state.

———— **Note** —————

This register has no effect on Non-secure access permissions for the debug control coprocessor, or the system control coprocessor.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-10 on page 4-16.

Figure 4-30 shows the NSACR bit assignments.

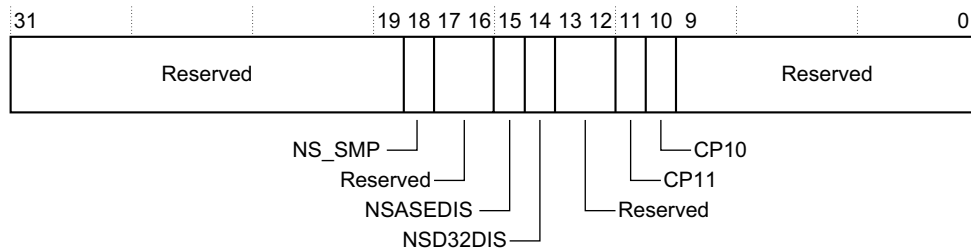


Figure 4-30 NSACR bit assignments

Table 4-51 shows the NSACR bit assignments.

Table 4-51 NSACR bit assignments

Bits	Name	Description
[31:19]	Reserved	UNP or SBZP.
[18]	NS_SMP	Determines if the SMP bit of the Auxiliary Control Register is writable in Non-secure state: 0 = A write to Auxiliary Control Register in Non-secure state takes an Undefined instruction exception and the SMP bit is write ignored. This is the reset value. 1 = A write to Auxiliary Control Register in Non-secure state can modify the value of the SMP bit. Other bits are write ignored.
[17:16]	Reserved	RAZ/WI
[15]	NSASEDIS	Disable Non-secure Advanced SIMD Extension functionality: 0 = this bit has no effect on the ability to write CPACR.ASEDIS. This is the reset value. 1 = the CPACR.ASEDIS bit when executing in Non-secure state has a fixed value of 1 and writes to it are ignored.
[14]	NSD32DIS	Disable the Non-secure use of D16-D31 of the VFP register file: 0 = this bit has no effect on the ability to write CPACR.D32DIS. This is the reset value. 1 = the CPACR.D32DIS bit when executing in Non-secure state has a fixed value of 1 and writes to it are ignored.
[13:12]	Reserved	UNP or SBZP.
[11]	CP11	Determines permission to access coprocessor 11 in the Non-secure state: 0 = Secure access only. This is the reset value. 1 = Secure or Non-secure access.
[10]	CP10	Determines permission to access coprocessor 10 in the Non-secure state: 0 = Secure access only. This is the reset value. 1 = Secure or Non-secure access.
[9:0]	Reserved	UNP or SBZ

To access the NSACR, use:

MRC p15, 0, <Rd>, c1, c1, 2 ; Read NSACR data
MCR p15, 0, <Rd>, c1, c1, 2 ; Write NSACR data

Table 4-52 shows the results of attempted access for each mode.

Table 4-52 Results of access to the NSACR

Secure privileged		Non-secure privileged		User	
Read	Write	Read	Write	Read	Write
Data	Data	Data	Undefined Instruction exception	Undefined Instruction exception	Undefined Instruction exception

See the *Cortex-A5 Floating-Point Unit Technical Reference Manual* and *Cortex-A5 NEON Media Processing Engine Technical Reference Manual* for more information.

4.3.31 Virtualization Control Register

The VCR characteristics are:

- Purpose** Forces an exception regardless of the value of the A, I, or F bits in the *Current Program Status Register (CPSR)*.
- Usage constraints** The VCR is:
- only accessible in privileged modes
 - only accessible in Secure state.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-10 on page 4-16.

Figure 4-31 shows the VCR bit assignments.

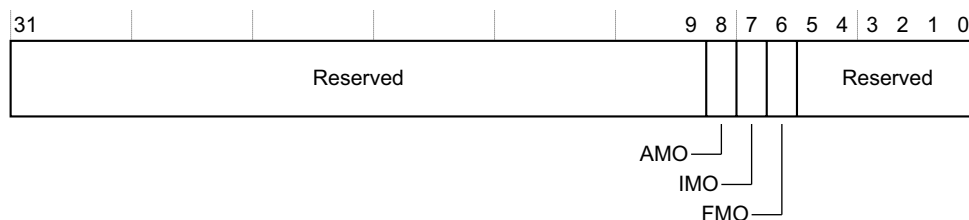


Figure 4-31 VCR bit assignments

Table 4-53 shows the VCR bit assignments.

Table 4-53 VCR bit assignments

Bits	Name	Description
[31:9]	Reserved	SBZ.
[8]	AMO	When the processor is in Non-secure state and the SCR.EA bit is set, if the AMO bit is set, this enables an asynchronous Data Abort exception to be taken regardless of the value of the CPSR.A bit. When the processor is in Secure state, or when the SCR.EA bit is not set, the AMO bit is ignored. See <i>Secure Configuration Register</i> on page 4-46.
[7]	IMO	IRQ Mask Override. When the processor is in Non-secure state and the SCR.IRQ bit is set, if the IMO bit is set, this enables an IRQ exception to be taken regardless of the value of the CPSR.I bit. When the processor is in Secure state, or when the SCR.IRQ bit is not set, the IMO bit is ignored. See <i>Secure Configuration Register</i> on page 4-46.
[6]	FMO	FIQ Mask Override. When the processor is in Non-secure state and the SCR.FIQ bit is set, if the FMO bit is set, this enables an FIQ exception to be taken regardless of the value of the CPSR.F bit. When the processor is in Secure state, or when the SCR.FIQ bit is not set, the FMO bit is ignored. See <i>Secure Configuration Register</i> on page 4-46.
[5:0]	Reserved	SBZ.

To access the VCR, use:

MRC p15, 0, <Rd>, c1, c1, 3 ; Read VCR data
MCR p15, 0, <Rd>, c1, c1, 3 ; Write VCR data

4.3.32 Translation Table Base Register 0

The TTBR0 characteristics are:

- Purpose** Holds the physical address of the first level translation table.
- Usage constraints** The TTBR0 is:
- only accessible in privileged modes
 - banked for Secure and Non-secure states
- Attempts to write to this register in Secure privileged mode when **CP15SDISABLE** is HIGH result in an Undefined instruction exception. See *Security Extensions write access disable* on page 3-10.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-11 on page 4-16.

Figure 4-32 shows the TTBR0 bit assignments. For an explanation of N in the figure, see *Translation Table Base Control Register* on page 4-55.

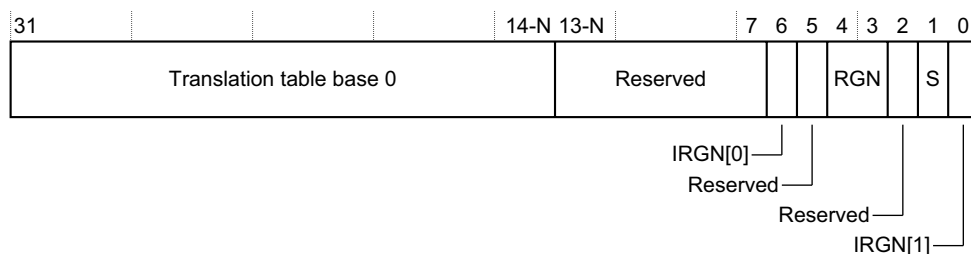


Figure 4-32 TTBR0 bit assignments

Table 4-54 shows the TTBR0 bit assignments. For an explanation of N in the table see *Translation Table Base Control Register* on page 4-55.

Table 4-54 TTBR0 bit assignments

Bits	Name	Description
[31:14-N]	Translation table base 0	Pointer to the level one translation table.
[13-N:7]	Reserved	UNP or SBZ.
[6]	IRGN[0]	Used with bit 0, IRGN[1] to describe inner cacheability.
[5]	Reserved	RAZ/WI.
[4:3]	RGN	Outer Cacheable attributes for translation table walking: b00 = Outer Non-cacheable b01 = Outer Cacheable Write-Back cached, Write-Allocate b10 = Outer Cacheable Write-Through, no allocate on write b11 = Outer Cacheable Write-Back, no allocate on write.

Table 4-54 TTBR0 bit assignments (continued)

Bits	Name	Description
[2]	Reserved	SBZ. This bit is not implemented on this processor.
[1]	S	Translation table walk: 0 = to non-shared memory. 1 = to shared memory.
[0]	IRGN[1]	Indicates inner cacheability for the translation table walk: IRGN[1], IRGN[0] 00 = Non-cacheable 01 = Write-Back Write-Allocate 10 = Write-Through, no allocate on write 11 = Write-Back no allocate on write. Page table walks do look-ups in the data cache only in write-back. Write-Through is treated as non-cacheable.

A write to the TTBR0 updates the address of the first level translation table from the value in bits [31:7] of the written value, to account for the maximum value of 7 for N. The number of bits of this address that the processor uses, and therefore the required alignment of the first level translation table, depends on the value of N, see *Translation Table Base Control Register* on page 4-55.

A read from the TTBR0 returns the complete address of the first level translation table in bits [31:7] of the read value, regardless of the value of N.

To access TTBR0, use:

MRC p15, 0, <Rd>, c2, c0, 0; Read Translation Table Base Register 0TTBR0
MCR p15, 0, <Rd>, c2, c0, 0; Write Translation Table Base Register 0TTBR0

4.3.33 Translation Table Base Register 1

The TTBR1 characteristics are:

Purpose Holds the physical address of the first-level translation table.

Usage constraints The TTBR1 is:

- only accessible in privileged modes
- banked for Secure and Non-secure states

Configurations Available in all configurations.

Attributes See the register summary in Table 4-11 on page 4-16.

Figure 4-33 on page 4-54 shows the TTBR1 bit assignments.

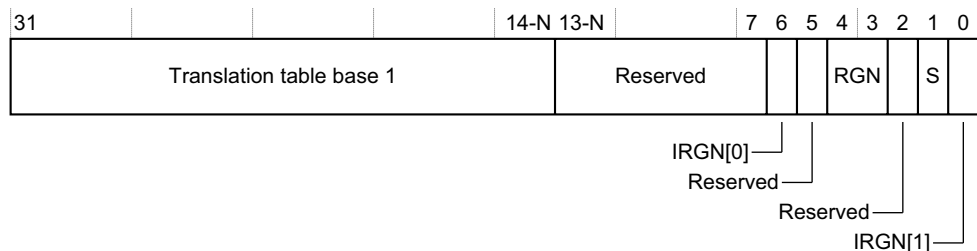


Figure 4-33 TTBR1 bit assignments

Table 4-55 shows the TTBR1 bit assignments.

Table 4-55 TTBR1 bit assignments

Bits	Name	Description
[31:14]	Translation table base 1	Pointer to the level one translation table.
[13:7]	Reserved	UNP or SBZ
[6]	IRGN[0]	Used with IRGN[1] to describe inner cacheability.
[5]	Reserved	RAZ/WI
[4:3]	RGN	Outer cacheable attributes for translation table walking: b00 = Outer Non-cacheable b01 = Outer Cacheable Write-Back cached, Write-Allocate b10 = Outer Cacheable Write-Through, no allocate on write b11 = Outer Cacheable Write-Back, no allocate on write.
[2]	Reserved	SBZ
[1]	S	Translation table walk: 1 = to shared memory 0 = to non-shared memory.
[0]	IRGN[1]	Indicates inner cacheability for the translation table walk: IRGN[1], IRGN[0] 00 = Non-cacheable 01 = Write-Back Write-Allocate 10 = Write-Through, no allocate on write 11 = Write-Back no allocate on write. Page table walks do look-ups in the data cache only in write-back. Write-Through is treated as non-cacheable.

To access TTBR1, use:

MRC p15, 0, <Rd>, c2, c0, 1; Read TTBR1
MCR p15, 0, <Rd>, c2, c0, 1; Write TTBR1

Writing to CP15 c2 updates the pointer to the first level translation table from the value in bits [31:14] of the written value. Bits [13:7] Should Be Zero. The address specified by TTBR1 must reside on a 16KB page boundary.

4.3.34 Translation Table Base Control Register

The TTBCR characteristics are:

- Purpose** Determines which of the Translation Table Base Registers, TTBR0 or TTBR1, defines the base address for the translation table walk that is required when a VA is not found in the TLB.
- Usage constraints** The TTBCR is:
- only accessible in privileged modes
 - banked.
- Attempts to write to this register in secure privileged mode when **CP15SDISABLE** is HIGH result in an Undefined instruction exception. See *Security Extensions write access disable* on page 3-10.
- This register has a defined reset value of 0. This reset value applies only to the Secure copy of the register, and software must program the Non-secure copy of the register with the required value.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-11 on page 4-16.

Figure 4-34 shows the TTBCR bit assignments.

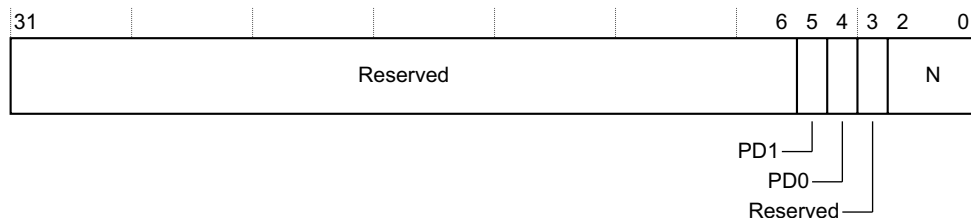


Figure 4-34 TTBCR bit assignments

Table 4-56 shows the TTBCR bit assignments.

Table 4-56 TTBCR bit assignments

Bits	Name	Description
[31:6]	Reserved	UNP or SBZ.
[5]	PD1	Specifies occurrence of a translation table walk on a TLB miss when using TTBR1. When translation table walk is disabled, a section translation fault occurs instead of a TLB miss: 0 = The processor performs a translation table walk on a TLB miss, with Secure or Non-secure privilege appropriate to the current Secure or Non-secure state. This is the reset value. The Non-secure version of this register must be programmed by software. 1 = The processor does not perform a translation table walk. If a TLB miss occurs with TTBR1 in use, the processor returns a section translation fault.

Table 4-56 TTBCR bit assignments (continued)

Bits	Name	Description
[4]	PD0	Specifies occurrence of a translation table walk on a TLB miss when using TTBR0. When translation table walk is disabled, a section translation fault occurs instead of a TLB miss. 0 = The processor performs a translation table walk on a TLB miss, with Secure or Non-secure privilege appropriate to the current Secure or Non-secure state. This is the reset value. The Non-secure version of this register must be programmed by software. 1 = The processor does not perform a translation table walk. If a TLB miss occurs with TTBR0 in use, the processor returns a section translation fault.
[3]	Reserved	UNP or SBZ.
[2:0]	N	Specifies the boundary size of TTBR0. b000 = 16KB. This is the reset value. b001 = 8KB b010 = 4KB b011 = 2KB b100 = 1KB b101 = 512 bytes b110 = 256 bytes b111 = 128 bytes.

To access the TTBCR, use:

```
MRC p15, 0, <Rd>, c2, c0, 2 ; Read TTBCR
MCR p15, 0, <Rd>, c2, c0, 2 ; Write TTBCR
```

A translation table base register is selected as follows:

- If N is set to 0, always use TTBR0. This is the default case at reset for the Secure version of this register. It is backwards compatible with ARMv5 and earlier processors.
- If N is set greater than 0, and bits [31:32-N] of the VA are all zeros, use TTBR0, otherwise use TTBR1. N must be in the range 0-7.

4.3.35 Domain Access Control Register

The DACR characteristics are:

Purpose Holds the access permissions for a maximum of 16 domains.

Usage constraints The DACR is:

- only accessible in privileged modes
- banked.

Attempts to write to this register in secure privileged mode when **CP15SDISABLE** is HIGH result in an Undefined instruction exception. See *Security Extensions write access disable* on page 3-10.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-12 on page 4-16.

Figure 4-35 on page 4-57 shows the DACR bit assignments.

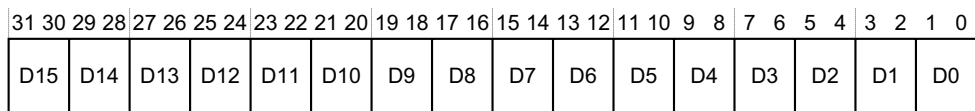


Figure 4-35 DACR bit assignments

Table 4-57 shows the DACR bit assignments.

Table 4-57 DACR bit assignments

Bits	Name	Description
-	D<n> ^a	<p>The fields D15-D0 in the register define the access permissions for each one of the 16 domains.</p> <p>b00 = No access. Any access generates a domain fault.</p> <p>b01 = Client. Accesses are checked against the access permission bits in the TLB entry.</p> <p>b10 = Reserved. Any access generates a domain fault.</p> <p>b11 = Manager. Accesses are not checked against the access permission bits in the TLB entry, so a permission fault cannot be generated. Attempting to execute code in a page that has the TLB <i>eXecute Never</i> (XN) attribute set does not generate an abort.</p>

a. n is the Domain number in the range between 0 and 15.

To access the DACR, use:

MRC p15, 0, <Rd>, c3, c0, 0 ; Read DACR
MCR p15, 0, <Rd>, c3, c0, 0 ; Write DACR

4.3.36 Data Fault Status Register

The DFSR characteristics are:

- Purpose**
- Holds the source of the last data fault.
 - Indicates the domain and type of access being performed when an abort occurred
- Usage constraints** The DFSR is:
- only accessible in privileged modes
 - banked.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-13 on page 4-17.

Figure 4-36 shows the DFSR bit assignments.

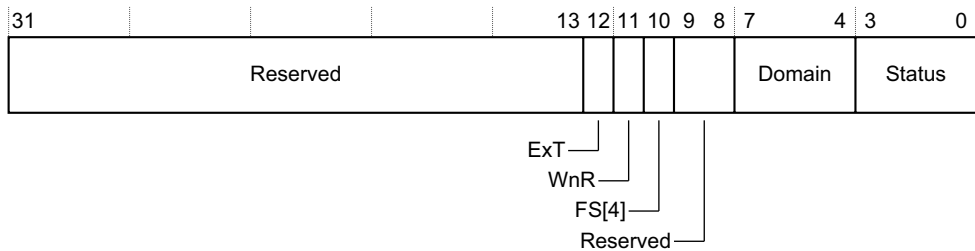


Figure 4-36 DFSR bit assignments

Table 4-58 shows the DFSR bit assignments.

Table 4-58 DFSR bit assignments

Bits	Name	Description
[31:13]	Reserved	UNP or SBZ.
[12]	ExT	External Abort Qualifier. Indicates whether an AXI Decode or Slave error caused an abort. This bit is only valid for External Aborts. For all other aborts this bit <i>Should Be Zero</i> . 0 = external abort marked as DECERR ^a 1 = external abort marked as SLVERR
[11]	WnR	Not read and write. Indicates what type of access caused the abort: 0 = read 1 = write. In case of aborted CP15 operations, this bit is set to 1.
[10]	FS[4]	Part of the Status field. See bit [12] and bits [3:0] in this table.
[9:8]	Reserved	Always read as 0.
[7:4]	Domain	Specifies which of the 16 domains, D15-D0, was being accessed when a data fault occurred.
[3:0]	Status	Indicates the type of exception generated. To determine the data fault, bits [12] and [10] must be used in conjunction with bits [3:0]. The following encodings are in priority order, highest first: <ol style="list-style-type: none"> 1. b000001 alignment fault 2. b000100 instruction cache maintenance fault 3. bx01100 1st level translation, synchronous external abort 4. bx01110 2nd level translation, synchronous external abort 5. b000101 translation fault, section 6. b000111 translation fault, page 7. b000011 access flag fault, section 8. b000110 access flag fault, page 9. b001001 domain fault, section 10. b001011 domain fault, page 11. b001101 permission fault, section 12. b001111 permission fault, page 13. bx01000 synchronous external abort, nontranslation 14. bx10110 asynchronous external abort 15. b000010 debug event. Any unused encoding not listed is reserved. Where <i>x</i> represents bit [12] in the encoding, bit [12] can be either: 0 = AXI Decode error caused the abort. This is the reset value. 1 = AXI Slave error caused the abort.

a. SLVERR and DECERR are the two possible types of abort reported in an AXI bus.

To access the DFSR, use:

```
MRC p15, 0, <Rd>, c5, c0, 0; Read DFSR
MCR p15, 0, <Rd>, c5, c0, 0; Write DFSR
```

Reading CP15 c5 with Opcode_2 set to 0 returns the value of the DFSR.

Writing CP15 c5 with Opcode_2 set to 0 sets the DFSR to the value of the data written. This is useful for a debugger to restore the value of the DFSR. The register must be written using a read modify write sequence.

4.3.37 Instruction Fault Status Register

The IFSR characteristics are:

- Purpose**
- Holds the source of the last instruction fault.
 - Indicates the domain and type of access being performed when an abort occurred
- Usage constraints** The IFSR is:
- only accessible in privileged modes
 - banked.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-13 on page 4-17.

Figure 4-37 shows the IFSR bit assignments.

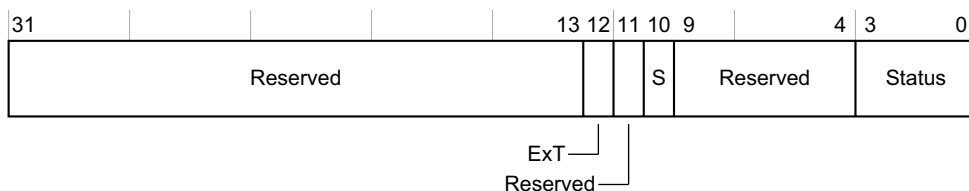


Figure 4-37 IFSR bit assignments

Table 4-59 shows the IFSR bit assignments.

Table 4-59 IFSR bit assignments

Bits	Name	Description
[31:13]	Reserved	UNP or SBZ.
[12]	ExT	External abort qualifier 0 = External abort marked as DECERR 1 = External abort marked as SLVERR.
[11]	Reserved	Always reads as 0.

Table 4-59 IFSR bit assignments (continued)

Bits	Name	Description
[10]	S	Part of the status field. Must be used in conjunction with bit [12] and bits [3:0]
[9:4]	Reserved	Always reads as 0.
[3:0]	Status	<p>Type of fault generated. Indicates the type of exception generated.</p> <p>To determine the data fault, bits [12] and [10] must be used in conjunction with bits [3:0]. The following encodings are in priority order, with 1 being highest:</p> <ol style="list-style-type: none"> 1. bx01100 L1 translation, synchronous external abort 2. bx01110 L2 translation, synchronous external abort 3. b000101 translation fault, section 4. b000111 translation fault, page 5. b000011 access flag fault, section 6. b000110 access flag fault, page 7. b001001 domain fault, section 8. b001011 domain fault, page 9. b001101 permission fault, section 10. b001111 permission fault, page 11. bx01000 synchronous external abort 12. b000010 debug event. <p>Any unused encoding not listed is reserved.</p> <p>Where <i>x</i> represents bit [12] in the encoding, bit [12] can be either:</p> <p>0 = AXI Decode error caused the abort. This is the reset value.</p> <p>1 = AXI Slave error caused the abort.</p>

You can access the IFSR by reading or writing CP15 c5 with the Opcode_2 field set to 1:

```
MRC p15, 0, <Rd>, c5, c0, 1; Read Instruction Fault Status Register
MCR p15, 0, <Rd>, c5, c0, 1; Write Instruction Fault Status Register
```

———— **Note** —————

When the SCR.EA bit is set the processor writes to the Secure Data Fault Status Register on a Monitor entry caused by an External Abort. See *Secure Configuration Register* on page 4-46.

Reading CP15 c5 with the Opcode_2 field set to 1 returns the value of the IFSR.

Writing CP15 c5 with the Opcode_2 field set to 1 sets the IFSR to the value of the data written. This is useful for a debugger to restore the value of the IFSR. The register must be written using a read, modify, write sequence. Bits [31:4] Should Be Zero.

4.3.38 Auxiliary Data Fault Status Register

The ADFSR characteristics are:

Purpose	Can provide implementation specific information.
Usage constraints	The ADFSR is: <ul style="list-style-type: none"> • only accessible in privileged modes • common to the Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-13 on page 4-17.

Note

The ADFSR is not used in this implementation.

To access the ADFSR, use:

MRC p15, 0, <Rd>, c5, c1, 0; Read Data Auxiliary Fault Status Register
MCR p15, 0, <Rd>, c5, c1, 0; Write Data Auxiliary Fault Status Register

4.3.39 Auxiliary Instruction Fault Status Register

The AIFSR characteristics are:

Purpose	Can provide implementation specific information.
Usage constraints	The AIFSR is: <ul style="list-style-type: none"> • only accessible in privileged modes • common to the Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-13 on page 4-17.

Note

The AIFSR is not used in this implementation.

To access the AIFSR, use

MRC p15, 0, <Rd>, c5, c1, 1; Read Instruction Auxiliary Fault Status Register
MCR p15, 0, <Rd>, c5, c1, 1; Write Instruction Auxiliary Fault Status Register

The Auxiliary Fault Status Registers are provided for compatibility with all ARMv7-A designs. The processor always reads the registers as RAZ. All writes are ignored.

4.3.40 Data Fault Address Register

The DFAR characteristics are:

Purpose	Holds the MVA of the faulting address when a synchronous fault occurs.
Usage constraints	The DFAR is: <ul style="list-style-type: none"> • only accessible in privileged modes • banked for Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-14 on page 4-17.

To access the DFAR, use:

MRC p15, 0, <Rd>, c6, c0, 0 ; Read Data Fault Address Register
MCR p15, 0, <Rd>, c6, c0, 0 ; Write Data Fault Address Register

A write to this register sets the DFAR to the value of the data written. This is useful for a debugger to restore the value of the DFAR.

4.3.41 Instruction Fault Address Register

The IFAR characteristics are:

Purpose	Holds the MVA of the faulting address of the instruction that caused a prefetch abort.
Usage constraints	The IFAR is: <ul style="list-style-type: none"> • only accessible in privileged modes • banked for Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-14 on page 4-17.

To access the IFAR, use:

MRC p15, 0, <Rd>, c6, c0, 2 ; Read Instruction Fault Address Register
MCR p15, 0, <Rd>, c6, c0, 2 ; Write Instruction Fault Address Register

A write to this register sets the IFAR to the value of the data written. This is useful for a debugger to restore the value of the IFAR. For more information, see *Breakpoints and watchpoints* on page 11-6.

4.3.42 NOP Register

The use of this register is optional and deprecated. Use the NOP instruction instead.

4.3.43 Physical Address Register

The PAR characteristics are:

Purpose	Holds: <ul style="list-style-type: none"> • the PA after a successful translation • the source of the abort for an unsuccessful translation.
Usage constraints	The PAR is: <ul style="list-style-type: none"> • only accessible in privileged modes • banked for Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-15 on page 4-17.

The PAR format depends on the value of bit F This bit signals whether or not there is an error during the VA to PA translation. See *VA format* on page 4-7 for information on Virtual Addresses.

The PAR is accessed by reading to CP15 c7 with <CRm> field set to c4 and Opcode_2 field set to 0:

MRC p15, 0, <Rd>, c7, c4, 0; Read PA register

If the translation aborted, the FSR bits give the encoding of the source of the abort as shown in Figure 4-38 on page 4-63. See *Data Fault Status Register* on page 4-57 for information on the Fault Status Register bits and the ExT bit. Figure 4-38 on page 4-63 shows the bit assignment for PAR aborted translations.

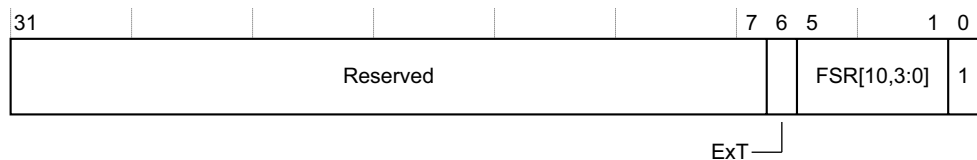


Figure 4-38 PAR aborted translation bit assignments

Figure 4-39 shows the PAR bit assignment if the translation completed successfully.

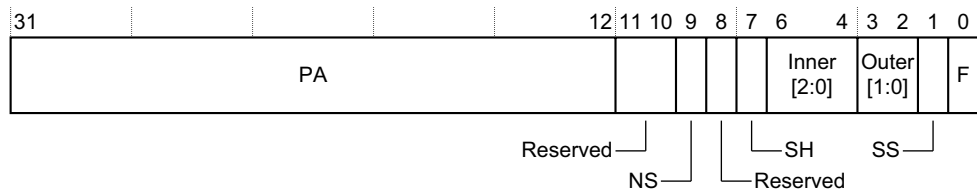


Figure 4-39 PAR successful translation bit assignments

Table 4-60 shows the PAR bit assignments.

Table 4-60 PAR bit assignments

Bits	Name	Description
[31:12]	PA	Physical address.
[11:10]	Reserved	RAZ/WI
[9]	NS	Non-secure. The NS bit from the translation table entry.
[8]	Reserved	RAZ/WI
[7]	SH	Shareable attribute. Indicates whether the physical memory is shareable: 0 = Memory is non-shareable. 1 = Memory is shareable.
[6:4]	Inner	Signals region inner attributes: b000 = Inner non-cacheable. b001 = Strongly-ordered. b011 = Device. b101 = Inner Write-Back Write-Allocate. b110 = Inner Write-Through. No Write-Allocate (treated as inner Non-cacheable). b111 = Inner Write-Back. No Write-Allocate (treated as Write-Allocate).
[3:2]	Outer	Signals region outer attributes for normal memory type (type = b10): b00 = Outer Non-cacheable. b01 = Outer Write-Back Write-Allocate. b10 = Outer Write-Through. No Write-Allocate. b11 = Outer Write-Back. No Write-Allocate.
[1]	SS bit	Supersection bit: 0 = The translation is not a supersection. 1 = The translation is a supersection.
[0]	F	Result of conversion: 0 = Successful translation.

4.3.44 Instruction Synchronization Barrier

The use of ISB is optional and deprecated. Use the instruction ISB instead.

4.3.45 Data Synchronization Barrier

The use of DSB is deprecated and, on Cortex-A5 MPCore, behaves as NOP. Use the instruction DSB instead.

4.3.46 Data Memory Barrier

The use of DMB is deprecated and, on Cortex-A5 MPCore, behaves as NOP. Use the instruction DMB instead.

4.3.47 Vector Base Address Register

The VBAR characteristics are:

Purpose	Provides the exception base address for exceptions that are not handled in monitor mode.
Usage constraints	The VBAR is: <ul style="list-style-type: none"> • only accessible in privileged modes • only accessible in Secure state.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-19 on page 4-20.

Figure 4-40 shows the VBAR bit assignments.



Figure 4-40 VBAR bit assignments

Table 4-61 shows the VBAR bit assignments.

Table 4-61 VBAR bit assignments

Bits	Name	Description
[31:5]	Vector Base Address	The base address of the normal exception vectors.
[4:0]	Reserved	UNK/SBZP.

To access the VBAR, use:

MRC p15, 0, <Rd>, c12, c0, 0 ; Read VBAR Register
MCR p15, 0, <Rd>, c12, c0, 0 ; Write VBAR Register

The Secure copy of the VBAR holds the vector base address for the Secure state, described as the Secure exception base address.

The Non-secure copy of the VBAR holds the vector base address for the Non-secure state, described as the Non-secure exception base address.

4.3.48 Monitor Vector Base Address Register

The MVBAR characteristics are:

- Purpose** Provides the exception base address for exceptions that are not handled in monitor mode.
- Usage constraints** The MVBAR is:
- only accessible in privileged modes
 - only accessible in Secure state.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-19 on page 4-20.

Figure 4-41 shows the MVBAR bit assignments.

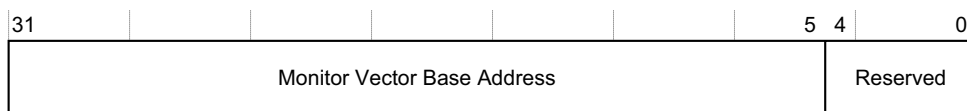


Figure 4-41 MVBAR bit assignments

Table 4-62 shows the MVBAR bit assignments.

Table 4-62 MVBAR bit assignments

Bits	Name	Description
[31:5]	Monitor Vector Base Address	The base address of the exception vectors for exceptions that are handled in Monitor mode.
[4:0]	Reserved	UNK/SBZP.

To access the MVBAR, use:

MRC p15, 0, <Rd>, c12, c0, 1 ; Read MVBAR Register
MCR p15, 0, <Rd>, c12, c0, 1 ; Write MVBAR Register

4.3.49 Interrupt Status Register

The ISR characteristics are:

- Purpose** Reports the status of virtual or physical interrupts.
- Usage constraints** The ISR is:
- only accessible in privileged modes
 - common to Secure and Non-secure state.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-19 on page 4-20.

The ISR reports pending virtual interrupts and aborts in Non-secure state if the relevant mask override field in the VCR and exception taken in monitor mode bits in the SCR are set. Otherwise it reflects pending physical interrupts and aborts. The register continues to report a virtual interrupt until the corresponding field in the VIR is cleared.

Figure 4-42 on page 4-66 shows the ISR bit assignments.

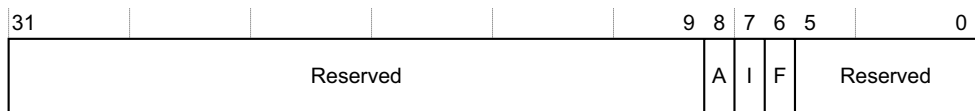


Figure 4-42 ISR bit assignments

Table 4-63 shows the ISR bit assignments.

Table 4-63 ISR bit assignments

Bits	Name	Description
[31:9]	Reserved	RAZ/UNK.
[8]	A	External abort pending flag: 0 = no pending external abort 1 = an external abort is pending.
[7]	I	Interrupt pending flag. Indicates whether an IRQ interrupt is pending: 0 = no pending IRQ 1 = an IRQ interrupt is pending.
[6]	F	Fast interrupt pending flag. Indicates whether an FIQ fast interrupt is pending: 0 = no pending FIQ 1 = an FIQ fast interrupt is pending.
[5:0]	Reserved	UNK/SBZP.

To access the ISR, use:

MRC p15, 0, <Rd>, c12, c1, 0 ; Read ISR Register

4.3.50 Virtualization Interrupt Register

The VIR characteristics are:

Purpose Triggers a pending interrupt from software running on the processor.

Usage constraints The VIR is:

- only accessible in privileged modes
- common to Secure and Non-secure state.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-19 on page 4-20.

Figure 4-43 shows the VIR bit assignments.



Figure 4-43 VIR bit assignments

Table 4-64 shows the VIR bit assignments.

Table 4-64 VIR bit assignments

Bits	Name	Description
[31:9]	Reserved	RAZ/WI.
[8]	VA	Virtual Abort bit. When set the virtual abort becomes pending when SCR.EA and VCR.AMO are b1. The virtual abort exception happens only when the processor is in Non-secure state and the CPSR.A field is clear.
[7]	VI	Virtual IRQ bit. When set the virtual interrupt becomes pending when SCR.IRQ and VCR.IMO are b1. The virtual interrupt exception happens only when the processor is in Non-secure state and the CPSR.I field is clear.
[6]	VF	Virtual FIQ bit. When set the virtual interrupt becomes pending when SCR.FIQ and VCR.FMO are b1. The virtual interrupt exception happens only when the processor is in Non-secure state and the CPSR.F field is clear.
[5:0]	Reserved	RAZ/WI.

To access the VIR, use:

```
MRC p15, 0, <Rd>, c12, c1, 1 ; Read VIR Register
MCR p15, 0, <Rd>, c12, c1, 1 ; Write VIR Register
```

A virtual abort or interrupt becomes pending when the associated abort/interrupt field in the SCR {EA, IRQ, FIQ} is set and the appropriate VCR mask override field in the VCR {AMO, IMO, FMO} is also set. The actual virtual interrupt/abort exception is taken only when the CPU enters Non-secure state and can be masked using the CPSR {A,I,F} fields.

When a virtual abort is taken, the corresponding bit in the VIR is cleared automatically by hardware. When a virtual interrupt is taken, the corresponding bit in the VIR is not changed by hardware. For the purposes of WFE and WFI, virtual interrupts and aborts are treated in the same way as normal interrupts and aborts.

4.3.51 Context ID Register

The CONTEXTIDR characteristics are:

Purpose Identifies the current *Process Identifier* (PROCID) and *Address Space Identifier* (ASID). The value of the whole of this register is called the Context ID and is used by the debug logic and the trace logic.

Usage constraints The CONTEXTIDR is:

- only accessible in privileged modes
- common to Secure and Non-secure state.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-20 on page 4-20.

Figure 4-44 on page 4-68 shows the CONTEXTIDR bit assignments.

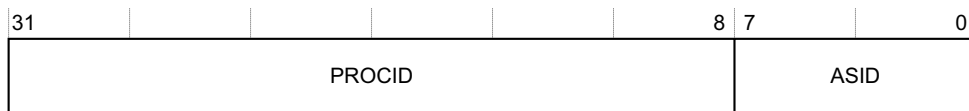


Figure 4-44 CONTEXTIDR bit assignments

Table 4-65 shows the CONTEXTIDR bit assignments.

Table 4-65 CONTEXTIDR bit assignments

Bits	Name	Description
[31:8]	PROCID	Process Identifier. This field must be programmed with a unique value that identifies the current process. It is used by the trace logic and the debug logic to identify the process that is currently running.
[7:0]	ASID	Address Space Identifier. This field is programmed with the value of the current ASID.

To access the CONTEXTIDR, use:

MRC p15, 0, <Rd>, c13, c0, 1 ; Read CONTEXTIDR Register

MCR p15, 0, <Rd>, c13, c0, 1 ; Write CONTEXTIDR Register

4.3.52 Configuration Base Address Register

The CBAR characteristics are:

Purpose Takes the physical base address value of the memory-mapped SCU peripherals at reset from the external signal **PERIPHBASE[31:13]**.

Usage constraints The CBAR is:

- only accessible in privileged modes
- common to Secure and Non-secure state.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-21 on page 4-21.

Figure 4-45 shows the CBAR bit assignments.

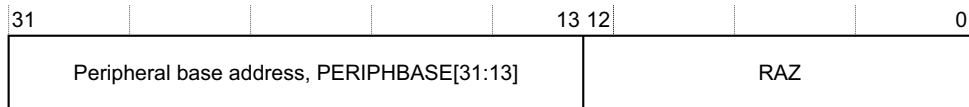


Figure 4-45 CBAR bit assignments

To access the CBAR, use:

MRC p15, 4, <Rd>, c15, c0, 0; Read Configuration Base Address Register

Chapter 5

Non-debug Use of CP14

This chapter introduces the CP14 coprocessor and describes the non-debug use of CP14. It contains the following sections:

- *About coprocessor CP14* on page 5-2
- *CP14 Jazelle register summary* on page 5-3
- *CP14 Jazelle register descriptions* on page 5-4.

5.1 About coprocessor CP14

Coprocessor CP14 provides support for the hardware acceleration of Java bytecodes.

5.2 CP14 Jazelle register summary

In the optional Cortex-A5 MPCore implementation of the Jazelle Extension:

- Jazelle state is supported.
- The BXJ instruction enters Jazelle state.

Table 5-1 shows the CP14 Jazelle registers. All Jazelle registers are 32 bits wide.

Table 5-1 CP14 Jazelle registers summary

CRn	Op1	CRm	Op2	Name	Type	Reset	Description
0	7	0	0	JIDR	RW ^a	0xF410014A	<i>Jazelle Identity and Miscellaneous Functions Register</i> on page 5-4
7	1	0	0	JOSCR	RW	-	<i>Jazelle Operating System Control Register</i> on page 5-5
7	2	0	0	JMCR	RW	-	<i>Jazelle Main Configuration Register</i> on page 5-6
7	3	0	0	JPR	RW	-	<i>Jazelle Parameters Register</i> on page 5-7
7	4	0	0	JCOTTR	WO	-	<i>Jazelle Configurable Opcode Translation Table Register</i> on page 5-8

a. See *Write operation of the JIDR* on page 5-5 for the effect of a write operation.

See the *ARM Architecture Reference Manual* for details of the Jazelle Extension.

5.3 CP14 Jazelle register descriptions

The following sections describe the CP14 Jazelle DBX registers arranged in numerical order, as shown in Table 5-1 on page 5-3:

- *Jazelle Identity and Miscellaneous Functions Register*
- *Jazelle Operating System Control Register* on page 5-5
- *Jazelle Main Configuration Register* on page 5-6
- *Jazelle Parameters Register* on page 5-7
- *Jazelle Configurable Opcode Translation Table Register* on page 5-8.

5.3.1 Jazelle Identity and Miscellaneous Functions Register

The JIDR characteristics are:

Purpose	Enables software to determine the implementation of the Jazelle Extension provided by the processor.
Usage constraints	The JIDR is: <ul style="list-style-type: none"> • accessible in privileged modes • also accessible in user mode if the CD bit is clear. See <i>Jazelle Operating System Control Register</i> on page 5-5.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 5-1 on page 5-3.

Figure 5-1 shows the JIDR bit assignments.

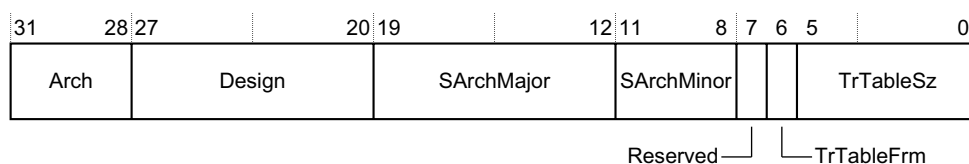


Figure 5-1 JIDR bit assignment

Table 5-2 shows the JIDR bit assignments.

Table 5-2 JIDR bit assignments

Bits	Name	Description
[31:28]	Arch	This uses the same architecture code that appears in the Main ID register.
[27:20]	Design	Contains the implementor code of the designer of the subarchitecture.
[19:12]	SArchMajor	The subarchitecture code.
[11:8]	SArchMinor	The subarchitecture minor code.
[7]	Reserved	RAZ.
[6]	TrTbleFrm	Indicates the format of the <i>Jazelle Configurable Opcode Translation Table Register</i> (JCOTTR).
[5:0]	TrTbleSz	Indicates the size of the JCOTTR.

To access the JIDR, use:

MRC p14, 7, <Rd>, c0, c0, 0 ; Read Jazelle Identity Register

Write operation of the JIDR

A write to the JIDR clears the translation table. This has the effect of making all configurable opcodes executed in software only. See *Jazelle Configurable Opcode Translation Table Register* on page 5-8.

5.3.2 Jazelle Operating System Control Register

The JOSCR characteristics are:

Purpose	Enables operating systems to control access to Jazelle Extension hardware.
Usage constraints	The JOSCR is: <ul style="list-style-type: none"> • only accessible in privileged modes • set to zero after a reset and must be written in privileged modes.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 5-1 on page 5-3.

Figure 5-2 shows the JOSCR bit assignments.

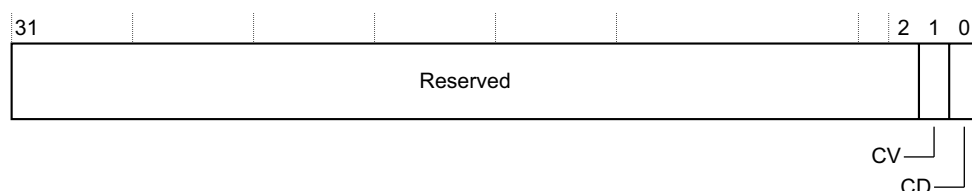


Figure 5-2 JOSCR bit assignments

Table 5-3 shows the JOSCR bit assignments.

Table 5-3 JOSCR bit assignments

Bits	Name	Description
[31:2]	Reserved	SBZ.
[1]	CV	Configuration Valid bit. 0 = The Jazelle configuration is invalid. Any attempt to enter Jazelle state when the Jazelle hardware is enabled: <ul style="list-style-type: none"> • generates a configuration invalid Jazelle exception • sets this bit, marking the Jazelle configuration as valid. 1 = The Jazelle configuration is valid. Entering Jazelle state succeeds when the Jazelle hardware is enabled. The CV bit is automatically cleared on an exception.
[0]	CD	Configuration Disabled bit. 0 = Jazelle configuration in User mode is enabled: <ul style="list-style-type: none"> • reading the JIDR succeeds • reading any other Jazelle configuration register generates an Undefined Instruction exception • writing the JOSCR generates an Undefined Instruction exception • writing any other Jazelle configuration register succeeds. 1 = Jazelle configuration from User mode is disabled: <ul style="list-style-type: none"> • reading any Jazelle configuration register generates an Undefined Instruction exception • writing any Jazelle configuration register generates an Undefined Instruction exception.

To access the JOSCR, use:

```
MRC p14, 7, <Rd>, c1, c0, 0 ; Read JOSCR
MCR p14, 7, <Rd>, c1, c0, 0 ; Write JOSCR
```

5.3.3 Jazelle Main Configuration Register

The JMCR characteristics are:

Purpose Describes the Jazelle hardware configuration and its behavior.

Usage constraints Only accessible in privileged modes.

Configurations Available in all configurations.

Attributes See the register summary in Table 5-1 on page 5-3.

Figure 5-3 shows the JMCR bit assignments.

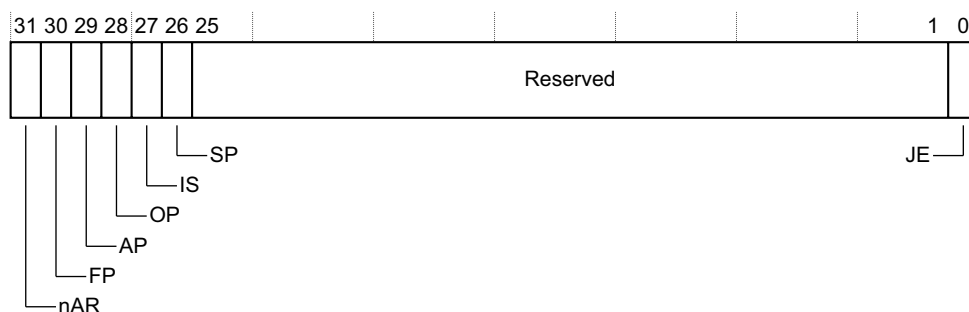


Figure 5-3 JMCR bit assignments

Table 5-4 shows the JMCR bit assignments.

Table 5-4 JMCR bit assignments

Bits	Name	Description
[31]	nAR	<i>not Array Operations</i> (nAR) bit. 0 = Execute array operations in hardware, if implemented. Otherwise, call the appropriate handlers in the VM Implementation Table. 1 = Execute all array operations by calling the appropriate handlers in the VM Implementation Table.
[30]	FP	The FP bit controls how the Jazelle hardware executes JVM floating-point opcodes: 0 = Execute all JVM floating-point opcodes by calling the appropriate handlers in the VM Implementation Table. 1 = Execute JVM floating-point opcodes by issuing VFP instructions, where possible. Otherwise, call the appropriate handlers in the VM Implementation Table. In this implementation FP is set to zero and is read only.
[29]	AP	The <i>Array Pointer</i> (AP) bit controls how the Jazelle hardware treats array references on the operand stack: 0 = Array references are treated as handles. 1 = Array references are treated as pointers.
[28]	OP	The <i>Object Pointer</i> (OP) bit controls how the Jazelle hardware treats object references on the operand stack: 0 = Object references are treated as handles. 1 = Object references are treated as pointers.

Table 5-4 JMCR bit assignments (continued)

Bits	Name	Description
[27]	IS	The <i>Index Size</i> (IS) bit specifies the size of the index associated with quick object field accesses: 0 = Quick object field indices are 8 bits. 1 = Quick object field indices are 16 bits.
[26]	SP	The <i>Static Pointer</i> (SP) bit controls how the Jazelle hardware treats static references: 0 = Static references are treated as handles. 1 = Static references are treated as pointers.
[25:1]	Reserved	SBZ
[0]	JE	The <i>Jazelle Enable</i> (JE) bit controls whether the Jazelle hardware is enabled, or is disabled: 0 = The Jazelle hardware is disabled: <ul style="list-style-type: none"> • BXJ instructions behave like BX instructions • setting the J bit in the CPSR generates a Jazelle-Disabled Jazelle exception. 1 = The Jazelle hardware is enabled: <ul style="list-style-type: none"> • BXJ instructions enter Jazelle state • setting the J bit in the CPSR enters Jazelle state.

To access the JMCR, use:

MRC p14, 7, <Rd>, c2, c0, 0 ; Read JMCR
MCR p14, 7, <Rd>, c2, c0, 0 ; Write JMCR

5.3.4 Jazelle Parameters Register

The JPR characteristics are:

Purpose Describes the parameters that configure how the Jazelle hardware behaves.

Usage constraints Only accessible in privileged modes.

Configurations Available in all configurations.

Attributes See the register summary in Table 5-1 on page 5-3.

Figure 5-4 shows the JPR bit assignments.

31		22 21	17 16	12 11	8	7	4	3	0
Reserved		BSH	sADO	ARO	STO	ODO			

Figure 5-4 JPR bit assignments

Table 5-5 shows the JPR bit assignments.

Table 5-5 Jazelle Parameters Register bit assignments

Bits	Name	Description
[31:22]	Reserved	SBZ
[21:17]	BSH	The <i>Bounds SHift</i> (BSH) bits contain the offset, in bits, of the array bounds (number of items in the array) within the array descriptor word.
[16:12]	sADO	The <i>signed Array Descriptor Offset</i> (sADO) bits contain the offset, in words, of the array descriptor word from an array reference. The offset is a sign-magnitude signed quantity: <ul style="list-style-type: none"> • Bit [16] gives the sign of the offset. The offset is positive if the bit is clear, and negative if the bit is set. • Bits [15:12] give the absolute magnitude of the offset.
[11:8]	ARO	The <i>Array Reference Offset</i> (ARO) bits contain the offset, in words, of the array data or the array data pointer from an array reference.
[7:4]	STO	The <i>Static Offset</i> (STO) bits contain the offset, in words, of the static or static pointer from a static reference.
[3:0]	ODO	The <i>Object Descriptor Offset</i> (ODO) bits contain the offset, in words, of the field from the base of an object data block.

To access the JPR, use:

MCR p14, 7, <Rd>, c3, c0, 0 ; Read Jazelle Parameters Register
MCR p14, 7, <Rd>, c3, c0, 0 ; Write Jazelle Parameters Register

5.3.5 Jazelle Configurable Opcode Translation Table Register

The JCOTTR characteristics are:

- Purpose** Provides translations between the configurable opcodes in the range 0xCB-0xFD and the operations that are provided by the Jazelle hardware.
- Usage constraints** Only accessible in privileged modes.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 5-1 on page 5-3.

Figure 5-5 shows the JCOTTR bit assignments.

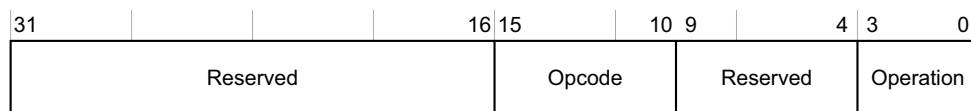


Figure 5-5 JCOTTR bit assignments

Table 5-6 shows the JCOTTR bit assignments.

Table 5-6 JCOTTR bit assignments

Bits	Name	Description
[31:16]	Reserved	SBZ

Table 5-6 JCOTTR bit assignments (continued)

Bits	Name	Description
[15:10]	Opcode	Contains the bottom bits of the configurable opcode.
[9:4]	Reserved	SBZ
[3:0]	Operation	Contains the code for the operation 0x0- 0x9

To access this register, use:

MCR p14, 7, <Rd>, c4, c0, 0 ; Write Jazelle Configurable Opcode Translation Table Register

Chapter 6

Memory Management Unit

This chapter describes the *Memory Management Unit* (MMU). It contains the following sections:

- *About the MMU* on page 6-2
- *Memory management system* on page 6-3
- *TLB organization* on page 6-5
- *Memory access sequence* on page 6-7
- *Interaction with memory system* on page 6-8
- *External aborts* on page 6-9
- *MMU software accessible registers* on page 6-10.

6.1 About the MMU

The MMU works with the L1 and L2 memory system to translate virtual addresses to physical addresses. It also controls accesses to and from external memory.

The ARM v7 *Virtual Memory System Architecture* (VMSA) features include the following:

- Page table entries that support:
 - 16MB supersections. The processor supports supersections that consist of 16MB blocks of memory.
 - 1MB sections.
 - 64KB large pages.
 - 4KB small pages.
- 16 access domains
- Global and application-specific identifiers to remove the requirement for context switch TLB flushes.
- Extended permissions checking capability.

TLB maintenance and configuration operations are controlled through a dedicated coprocessor, CP15, integrated with the core. This coprocessor provides a standard mechanism for configuring the L1 memory system.

See the *ARM Architecture Reference Manual* for a full architectural description of the ARMv7 VMSA.

6.2 Memory management system

The Cortex-A5 MPCore processor supports the ARM v7 VMSA including the TrustZone security extension. The translation of a *Virtual Address* (VA) used by the instruction set architecture to a *Physical Address* (PA) used in the memory system and the management of the associated attributes and permissions is carried out using a two-level MMU.

The first level MMU uses a Harvard design with separate micro TLB structures in the PFU for instruction fetches (IuTLB) and in the DPU for data read and write requests (DuTLB).

A miss in the micro TLB results in a request to the main unified TLB shared between the data and instruction sides of the memory system. The TLB consists of a 128-entry two-way set-associative RAM based structure. The TLB page-walk mechanism supports page descriptors held in the L1 data cache. These cached descriptors are coherent across the cores in the Cortex-A5 MPCore processor. The caching of page descriptors is configured globally for each translation table base register, TTBRx, in the system coprocessor, CP15.

The TLB contains a hitmap cache of the page types which have already been stored in the TLB. When the core is put into dormant mode as described in *Individual Cortex-A5 core power management* on page 2-13, the TLB RAM data is retained. To save and restore the hitmap, the register can be accessed directly from software using CP15 as described in *c15, TLB access and attributes* on page 4-12.

6.2.1 Memory types

Although various different memory types can be specified in the page tables, the Cortex-A5 MPCore processor does not implement all possible combinations:

- Write-through caches are not supported. Any memory marked as write-through is treated as Non-cacheable.
- The outer shareable attribute is not supported. Anything marked as outer shareable is treated in the same way as inner shareable.
- Write-back no write allocate is not supported. It is treated as write-back write-allocate.

Table 6-1 shows the treatment of each different memory type in the Cortex-A5 MPCore processor in addition to the architectural requirements.

Table 6-1 Treatment of memory attributes

Memory type attribute	Shareability	Other attributes	Notes
Strongly Ordered	-	-	-
Device	Non-shareable	-	-
	Shareable	-	-

Table 6-1 Treatment of memory attributes (continued)

Memory type attribute	Shareability	Other attributes	Notes
Normal	Non-shareable	Non-cacheable	Does not access L1 caches.
		Write-through cacheable	Treated as non-cacheable.
		Write-back cacheable, write allocate	Can dynamically switch to no write allocate, if more than three full cache lines are written in succession. See <i>Read allocate mode</i> on page 2-5.
		Write-back cacheable, no write allocate	Treated as non-shareable write-back cacheable, write allocate
	Inner shareable	Non-cacheable	-
		Write-through cacheable	Treated as inner shareable non-cacheable.
		Write-back cacheable, write allocate	Treated as inner shareable non-cacheable unless the SMP bit in the Auxiliary Control Register is set (ACTLR[6] = b1). See <i>Auxiliary Control Register</i> on page 4-42. If this bit is set the area is treated as Write-back cacheable write allocate.
		Write-back cacheable, no write allocate	
	Outer shareable	Non-cacheable	Treated as inner shareable non-cacheable.
		Write-through cacheable	
		Write-back cacheable, write allocate	Treated as inner shareable non-cacheable unless the SMP bit in the Auxiliary Control Register is set (ACTLR[6] = b1). See <i>Auxiliary Control Register</i> on page 4-42. If this bit is set the area is treated as Write-back cacheable write allocate.
		Write-back cacheable, no write allocate	

6.3 TLB organization

TLB organization is described in the following sections:

- *Micro TLB*
- *Main TLB.*

6.3.1 Micro TLB

The first level of caching for the page table information is a micro TLB of 10 entries that is implemented on each of the instruction and data sides. These blocks provide a lookup of the virtual addresses in a single cycle.

The micro TLB returns the physical address to the cache for the address comparison, and also checks the access permissions to signal either a Prefetch Abort or a Data Abort.

All main TLB related maintenance operations affect both the instruction and data micro TLBs, causing them to be flushed. In the same way, any change of the following registers causes the micro TLBs to be flushed:

- *Context ID Register (CONTEXTIDR)*
- *Domain Access Control Register (DACR)*
- *Primary Region Remap Register (PRRR)*
- *Normal Memory Remap Register (NMRR)*
- *Translation Table Base Registers (TTBR0 and TTBR1).*

6.3.2 Main TLB

Misses from the instruction and data micro TLBs are handled by a unified main TLB. Accesses to the main TLB take a variable number of cycles, according to competing requests from each of the micro TLBs and other implementation-dependent factors.

The main TLB is 128-entry two-way set-associative.

TLB match process

Each TLB entry contains a virtual address, a page size, a physical address, and a set of memory properties. Each is marked as being associated with a particular application space (ASID), or as global for all application spaces. The CONTEXTIDR determines the currently selected application space.

A TLB entry matches when these conditions are true:

- its virtual address matches that of the requested address
- its Non-secure TLB ID (NSTID) matches the Secure or Non-secure state of the MMU request
- its ASID matches the current ASID in the CONTEXTIDR or is global.

The operating system must ensure that, at most, one TLB entry matches at any time. The TLB can store entries based on the following block sizes:

Supersections	Describe 16MB blocks of memory.
Sections	Describe 1MB blocks of memory.
Large pages	Describe 64KB blocks of memory.
Small pages	Describe 4KB blocks of memory.

Supersections, sections and large pages are supported to permit mapping of a large region of memory while using only a single entry in the TLB. If no mapping for an address is found within the TLB, then the translation table is automatically read by hardware and a mapping is placed in the TLB.

6.4 Memory access sequence

When the processor generates a memory access, the MMU:

1. Performs a lookup for the requested virtual address and current ASID and security state in the relevant instruction or data micro TLB.
2. If there is a miss in the micro TLB, performs a lookup for the requested virtual address and current ASID and security state in the main TLB.
3. If there is a miss in main TLB, performs a hardware translation table walk.

You can configure the MMU to perform hardware translation table walks in cacheable regions by setting the IRGN bits in *Translation Table Base Register 0* on page 4-52 and *Translation Table Base Register 1* on page 4-53. If the encoding of the IRGN bits is write-back, an L1 data cache lookup is performed and data is read from the data cache. If the encoding of the IRGN bits is write-through or non-cacheable, an access to external memory is performed.

The MMU might not find a global mapping, or a mapping for the currently selected ASID, with a matching *Non-secure TLB ID (NSTID)* for the virtual address in the TLB. In this case, the hardware does a translation table walk if the translation table walk is enabled by the PD0 or PD1 bit in the *Translation Table Base Control Register* on page 4-55. If translation table walks are disabled, the processor returns a Section Translation fault.

If the TLB finds a matching entry, it uses the information in the entry as follows:

1. The access permission bits and the domain determine if the access is enabled. If the matching entry does not pass the permission checks, the MMU signals a memory abort. See the *ARM Architecture Reference Manual* for a description of access permission bits, abort types and priorities, and for a description of the *Instruction Fault Status Register (IFSR)* and *Data Fault Status Register (DFSR)*.
2. The memory region attributes specified in both the TLB entry and the CP15 c10 remap registers determine if the access is
 - Secure or Non-secure
 - Shared or not
 - Normal memory, Device, or Strongly-ordered.
 See *c10, Memory region remap* on page 4-11.
3. The TLB translates the virtual address to a physical address for the memory access.

6.5 Interaction with memory system

You can enable or disable the MMU as described in the *ARM Architecture Reference Manual*.

6.6 External aborts

External memory errors are defined as those that occur in the memory system rather than those that are detected by the MMU. External memory errors are expected to be extremely rare. External aborts are caused by errors flagged by the AXI interfaces when the request goes external to the Cortex-A5 MPCore processor. External aborts can be configured to trap to Monitor mode by setting the EA bit in the *Secure Configuration Register* on page 4-46.

6.6.1 External aborts on data write

Externally generated errors during a data write can be asynchronous. This means that the r14_abt on entry into the abort handler on such an abort might not hold the address of the instruction that caused the exception.

The DFAR is Unpredictable when an asynchronous abort occurs.

Externally generated errors during data read are always synchronous. The address captured in the DFAR matches the address which generated the external abort.

6.6.2 Synchronous and asynchronous aborts

Chapter 4 *System Control* describes synchronous and asynchronous aborts, their priorities, and the IFSR and DFSR. To determine a fault type, read the DFSR for a data abort or the IFSR for an instruction abort.

The processor supports an Auxiliary Fault Status Register for software compatibility reasons only. The processor does not modify this register because of any generated abort.

6.7 MMU software accessible registers

The system control coprocessor registers, CP15, in conjunction with page table descriptors stored in memory, control the MMU as shown in Table 6-2.

You can access all the registers with instructions of the form:

MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>

MCR p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>

CRn is the system control coprocessor register. Unless specified otherwise, CRm and Opcode_2 Should Be Zero.

Table 6-2 CP15 register functions

Register	Cross reference
TLB Type Register	<i>TLB Type Register</i> on page 4-24.
Control Register	<i>System Control Register</i> on page 4-39
Non-secure Access Control Register	<i>Non-secure Access Control Register</i> on page 4-49
Translation Table Base Register 0	<i>Translation Table Base Register 0</i> on page 4-52
Translation Table Base Register 1	<i>Translation Table Base Register 1</i> on page 4-53
Translation Table Base Control Register	<i>Translation Table Base Control Register</i> on page 4-55
Domain Access Control Register	<i>Domain Access Control Register</i> on page 4-56
DFSR	<i>Data Fault Status Register</i> on page 4-57
IFSR	<i>Instruction Fault Status Register</i> on page 4-59
DFAR	<i>Data Fault Address Register</i> on page 4-61
IFAR	<i>Instruction Fault Address Register</i> on page 4-62
TLB operations	<i>c8, TLB maintenance operations</i> on page 4-9.
Primary Region Remap Register	<i>c10, Memory region remap</i> on page 4-11
Normal Memory Remap Register	
TLB Hitmap Register	<i>c15, TLB access and attributes</i> on page 4-12.
Context ID Register	<i>Context ID Register</i> on page 4-67

Chapter 7

Level 1 Memory System

This chapter describes the *Level 1* (L1) memory system. It contains the following sections:

- *About the L1 memory system* on page 7-2
- *Security extensions support* on page 7-3
- *L1 instruction side memory system* on page 7-4
- *L1 data side memory system* on page 7-6
- *Data prefetching* on page 7-7
- *Direct access to internal memory* on page 7-8.

7.1 About the L1 memory system

The L1 memory system has:

- separate instruction and data caches each with a fixed line length of 32 bytes
- 64-bit data paths throughout the memory system
- support for four sizes of memory page
- export of memory attributes for external memory systems
- support for Security Extensions.

The data side of the L1 memory system has:

- two 16-byte linefill buffers and one 32-byte eviction buffer
- a 4-entry, 64-bit merging store buffer.

7.1.1 Memory system

This section describes:

- *Cache features*
- *Store buffer.*

Cache features

The Cortex-A5 MPCore processor has separate instruction and data caches. The caches have the following features:

- Each cache can be disabled independently, using the system control coprocessor. See *System Control Register* on page 4-39.
- Cache replacement policy is pseudo random.
- Data cache is 4-way set-associative.
- Instruction cache is 2-way set-associative.
- The cache line length is eight words.
- On a cache miss, critical word first filling of the cache is performed.
- You can configure the instruction and data caches independently during implementation to sizes of 4KB, 8KB, 16KB, 32KB, or 64KB.
- For optimum area and performance, all of the cache RAMs, and the associated tag RAMs, are designed to be implemented using standard ASIC RAM compilers.

Instruction cache features

The instruction cache is virtually indexed and physically tagged.

Data cache features

The data cache is physically indexed and physically tagged.

Store buffer

The Cortex-A5 MPCore processor has a store buffer with four 64-bit slots with data merging capability.

7.2 Security extensions support

The Cortex-A5 MPCore processor supports the TrustZone architecture, and exports the Secure or Non-secure status of its memory requests to the memory system.

7.3 L1 instruction side memory system

The L1 instruction side memory system is responsible for providing an instruction stream to the Cortex-A5 MPCore processor. To increase overall performance and to reduce power consumption, it contains the following functionality:

- dynamic branch prediction
- Instruction caching.

The ISide comprises the following:

Prefetch Unit (PFU)

The PFU implements a two-level prediction mechanism, comprising the following:

- A 256 entry branch pattern history table.
- A four-entry BTAC.
- A four-entry return stack.

The prediction scheme is available in ARM state, Thumb state, ThumbEE state, and Jazelle state. It is also capable of predicting state changes from ARM to Thumb, and from Thumb to ARM. It does not predict any other state changes, or any instruction that changes the mode of the core. See *Program flow prediction*.

Instruction Cache Controller

The instruction cache controller fetches the instructions from memory depending on the program flow predicted by the PFU.

The instruction cache is two-way set-associative. It comprises the following features:

- configurable sizes of 4KB, 8KB, 16KB, 32KB, or 64KB
- *Virtually Indexed Physically Tagged* (VIPT)
- 64-bit native accesses to provide up to four instructions per cycle to the PFU
- security extensions support
- no lockdown support.

7.3.1 Enabling program flow prediction

Program flow prediction is always enabled when the MMU is enabled by setting the M-bit in the CP15 c1 Control register to 1. See *System Control Register* on page 4-39.

7.3.2 Program flow prediction

The following sections describe program flow prediction:

- *Predicted and non-predicted instructions* on page 7-5
- *Thumb state conditional branches* on page 7-5
- *Return stack predictions* on page 7-5.

Predicted and non-predicted instructions

This section shows the instructions that the processor predicts. Unless otherwise specified, the list applies to ARM, Thumb, ThumbEE, and Jazelle instructions. As a general rule, the flow prediction hardware predicts all branch instructions regardless of the addressing mode, including:

- conditional branches
- unconditional branches
- indirect branches associated with function-call and return instructions
- branches that switch between ARM and Thumb states.

However, some branch instructions are not predicted:

- PC destination data processing operations
- branches that switch between states, except ARM to Thumb transitions, and Thumb to ARM transitions
- Instructions with the S suffix are not predicted because they are typically used to return from exceptions and have side-effects that can change privilege mode and security state
- All mode changing instructions.

Thumb state conditional branches

In Thumb state, a branch that is normally encoded as unconditional can be made conditional by inclusion in an *If-Then-Else* (ITE) block. Then it is treated as a normal conditional branch.

Return stack predictions

The return stack stores the address and the ARM or Thumb state of the instruction after a function-call type branch instruction. This address is equal to the link register value stored in r14. The following instructions cause a return stack push if predicted:

- BL immediate
- BLX immediate
- BLX register.

The following instructions cause a return stack pop if predicted:

- BX r14
- POP {...,pc}
- LDR pc, [r13].

The LDR instruction can use any of the addressing modes, as long as r13 is the base register.

Because return-from-exception instructions can change processor privilege mode and security state, they are not predicted. This includes the LDM[^] instruction, RFE, and the MOV^S pc, r14 instruction.

7.4 L1 data side memory system

The L1 data cache is organized as a physically indexed and physically tagged cache. The micro TLB produces the physical address from the virtual address before performing the cache access.

7.4.1 Internal exclusive monitor

The Cortex-A5 MPCore processor L1 memory system has an internal exclusive monitor. This is a two-state, open and exclusive, state machine that manages load/store exclusive (LDREXB, LDREXH, LDREX, LDREXD, STREXB, STREXH, STREX, and STREXD) accesses and clear exclusive (CLREX) instructions. You can use these instructions to construct semaphores, ensuring synchronization between different processes running on the CPU, and also between different processors that are using the same coherent memory locations for the semaphore.

———— **Note** —————

A store exclusive can generate an MMU fault or cause the processor to take a data watchpoint exception regardless of the state of the local monitor. See *Watchpoint Control Register* on page 11-25.

See the *ARM Architecture Reference Manual* for more information about these instructions.

Treatment of intervening STR operations

In cases where there is an intervening STR operation in an LDREX/STREX code sequence, the intermediate STR does not produce any direct effect on the internal exclusive monitor. The local monitor is in the Exclusive Access state after the LDREX, remains in the Exclusive Access state after the STR, and returns to the Open Access state only after the STREX.

However, if the address LDREX/STREX code sequence is in cacheable memory, any eviction of the cache line containing that address clears the monitor. It is therefore recommended that no load or store instructions are placed between the LDREX and STREX because these additional instructions can cause a cache eviction.

7.4.2 External aborts handling

The L1 data cache handles two types of external abort depending on the attributes of the memory region of the access:

- All load accesses use the synchronous abort mechanism.
- All store accesses use the asynchronous abort mechanism, except for SWP and SWPB to any type of memory, and STREX, STREXB, STREXH, and STREXD to shareable non-cacheable normal or shareable device or strongly-ordered memory.

7.5 Data prefetching

This section describes:

- *The PLD instruction*
- *Data prefetching and monitoring.*

7.5.1 The PLD instruction

PLD instructions lookup in the cache, and start a linefill if they missed, just like a normal load instruction. However, the PLD instruction retires immediately rather than waiting for the data to arrive in the cache, which enables other instructions to execute while the linefill continues in the background.

7.5.2 Data prefetching and monitoring

The Cortex-A5 MPCore data cache implements an automatic prefetcher that monitors cache misses done by the processor. When a pattern is detected, the automatic prefetcher starts linefills in the background. Occasionally these linefills might be dropped before the data is allocated into the cache. It can be deactivated in software using a CP15 Auxiliary Control Register bit. See *Auxiliary Control Register* on page 4-42.

———— **Note** —————

Automatic data prefetching is only performed for memory that is marked as non-shared.

7.6 Direct access to internal memory

The Cortex-A5 MPCore processor provides a mechanism to read the internal memory used by the Cache and TLB structures through the implementation-defined region of the system coprocessor interface. This functionality can be useful when investigating issues where the coherency between the data in the cache and data in system memory is broken.

The appropriate memory block and location is selected using a number of write-only CP15 registers and the data is read from a pair of read-only CP15 registers as shown in Table 7-1. These operations are only available in secure privileged modes. In all other modes, executing the CP15 instruction results in an Undefined instruction exception.

Table 7-1 Cortex-A5 MPCore system coprocessor CP15 registers used to access internal memory

Function	Access	CP15 operation	Rd Data
Data Register 0	Read-only	MRC p15, 3, <Rd>, c15, c0, 0	Data
Data Register 1	Read-only	MRC p15, 3, <Rd>, c15, c0, 1	Data
Data Cache Tag Read Operation Register	Write-only	MCR p15, 3, <Rd>, c15, c2, 0	Set/Way
Instruction Cache Tag Read Operation Register	Write-only	MCR p15, 3, <Rd>, c15, c2, 1	Set/Way
Data Cache Data Read Operation Register	Write-only	MCR p15, 3, <Rd>, c15, c4, 0	Set/Way/Offset
Instruction Cache Data Read Operation Register	Write-only	MCR p15, 3, <Rd>, c15, c4, 1	Set/Way/Offset
TLB Data Read Operation Register	Write-only	MCR p15, 3, <Rd>, c15, c4, 2	Index/Way

The encodings for the operations and the format for the data read from the memory are described in the following sections:

- *Data Cache Tag and Data encoding*
- *Instruction Cache Tag and Data encoding* on page 7-9
- *TLB data encoding* on page 7-10.

7.6.1 Data Cache Tag and Data encoding

The Cortex-A5 MPCore processor data cache consists of a 4-way set-associative structure. The number of sets in each way depends on the configured size of the cache. The encoding, set in Rd in the appropriate MCR instruction, used to locate the required cache data entry for tag and data memory is shown in Table 7-2. It is very similar for both the tag and data RAM access. Data RAM access includes an additional field to locate the appropriate words in the cache line. The set-index range parameter (S) is determined by:

$$S = \log_2(\text{Data cache size} / 4).$$

Table 7-2 Data Cache Tag and Data location encoding

Bit-field of Rd	Description
[31:30]	Cache Way
[29:S+5]	Unused
[S+4:5]	Set index
[4:2]	Cache word data offset (Data Register only)
[1:0]	Unused

The tag information (MOESI coherency state and outer attributes) for the selected cache line is returned using only Data Register 0 using the format shown in Table 7-3. The Cortex-A5 MPCore processor encodes the 4-bit MOESI coherency state across two fields of Data Register 0.

Table 7-3 Data Cache Tag data format

Bit-field of Data Register 0	Description
[31:29]	Most significant bits of MOESI state
[28]	TrustZone Non-secure state (NS)
[27:6]	Tag Address
[5:3]	Unused
[2:1]	Outer memory attributes
[0]	Least significant bits of MOESI state

The 32 bits of cache data is also returned in Data register 0.

7.6.2 Instruction Cache Tag and Data encoding

The Cortex-A5 MPCore processor instruction cache is significantly different from the data cache and this is shown in the encodings and data format used in the CP15 operations used to access the Tag and data memories. Table 7-4 shows the encoding required to select a given cache line. The set-index range parameter (S) is determined by:

$S = \log_2(\text{Instruction cache size} / 2)$ for the 2-way set-associative cache.

Table 7-4 Instruction Cache Tag and Data location encoding

Bit-field of Rd	Description
[31]	Cache Way
[30:S+5]	Unused
[S+4:5]	Set index
[4:2]	Cache data element offset (Data Register only)
[1:0]	Unused

The Tag and valid bits for the selected cache line are returned using only Data Register 0 using the format shown in Table 7-5.

Table 7-5 Instruction Cache Tag data format

Bit-field of Data Register 0	Description
[31:24]	Unused.
[23:22]	Valid bits
[21]	TrustZone Non-secure state (NS).
[20:0]	Tag Address.

The CP15 Instruction Cache Data Read Operation returns two entries from the cache in Data Register 0 and Data Register 1 corresponding to the 16-bit aligned offset in the cache line:

Data Register 0 Data from cache offset+b00.

Data Register 1 Data from cache offset+b10.

In ARM mode these two fields combined always represent a single instruction. In Thumb they can represent any combination of 16-bit and partial or full 32-bit instructions.

7.6.3 TLB data encoding

The Cortex-A5 MPCore processor unified TLB is built from a two-way set-associative RAM based structure. The individual entries can be read into the data registers by writing to the TLB Data Read Operation Register using the encoding shown in Table 7-6.

The set-index range parameter (S) is determined by:

$$S = \log_2(\text{No. TLB entries} / 2).$$

For the Cortex-A5 MPCore processor, No. TLB entries is 128.

Table 7-6 TLB Data Read Operation Register location encoding

Bit-field of Rd	Description
[31]	TLB Way
[30:S]	Unused
[S-1:0]	TLB index

The TLB uses a 63-bit encoding for the descriptor which is returned in both Data Registers:

Data Register 0[31:0] TLB Descriptor[31:0].

Data Register 1[30:0] TLB Descriptor[62:32].

Table 7-7 shows the data fields in the TLB descriptor.

Table 7-7 TLB descriptor format

Bit-field	Field name	Width	Comments
[62:59]	Domain	4	-
[58:56]	Access Permissions (AP)	3	-
[55]	NS (Non-Secure Walk Flag)	1	The security state during the page-walk that fetched the entry.
[54]	NS (Non-Secure Page Flag)	1	The security state allocated to this memo
[53]	XN	1	Execute Never
[52:50]	TEX	3	-
[49]	Bufferable	1	-
[48]	Cacheable	1	-
[47]	Shareable	1	-
[46:39]	ASID	8	The current ContextID

Table 7-7 TLB descriptor format (continued)

Bit-field	Field name	Width	Comments
[38:37]	Size	2	b00 = Small Page b01 = Large Page b10 = Section b11 = SupersSection
[36:22]	VA	15	-
[21:2]	PA	20	-
[1]	Not-Global (nG)	1	b0 = entry is global to all ASIDs b1 = entry is local to listed ASID
[0]	Valid	1	-

Chapter 8

Level 2 Memory Interface

This chapter describes the *Level 2* (L2) memory interface. It contains the following sections:

- *About the L2 interface* on page 8-2
- *AXI privilege information* on page 8-6.

8.1 About the L2 interface

The L2 AXI interfaces enable the L1 memory system to have access to peripherals and to external memory using an AXI master port. The Cortex-A5 MPCore processor supports an optional second AXI master port and *Accelerator Coherency Port (ACP)* AXI Slave. The L2 interface is described in:

- *AXI master interface*
- *L2 memory interface attributes* on page 8-3
- *Supported AXI transfers* on page 8-3
- *AXI transaction IDs* on page 8-4
- *AXI user bits* on page 8-4
- *Write response* on page 8-5
- *Exclusive L2 cache* on page 8-5.

See Chapter 9 *Snoop Control Unit* for information about the configuration of the second master port and ACP.

8.1.1 AXI master interface

The AXI master interface provides a high bandwidth interface to second level caches, on-chip RAM, peripherals, and interfaces to external memory. It consists of one or two AXI ports with a 64-bit read channel for instruction fetches and data reads and a 64-bit write channel for data writes.

The AXI master can run at the same frequency as the processor, or at a lower synchronous frequency. If asynchronous clocking is required an external asynchronous AXI bridge is required.

8.1.2 L2 memory interface attributes

Table 8-1 shows the AXI master interface attributes for the Cortex-A5 MPCore processor. The table lists the maximum possible values for the read and write issuing capabilities if the processor includes four cores and ACP.

Table 8-1 AXI master interface attributes

Attribute	Value	Comments
Write issuing capability	516	<p>78 per core in the Cortex-A5 MPCore processor including:</p> <ul style="list-style-type: none"> 47 outstanding writes to normal memory, which can be evictions, single writes, or write bursts, of which: <ul style="list-style-type: none"> a maximum of 15 can be to shareable cacheable memory a maximum of 18 can be to non-shareable cacheable memory a maximum of 15 can be to non-cacheable memory. up to 31 outstanding writes to device or strongly ordered memory, which can be single writes or write bursts. <p>If the ACP is included in the processor, the following additional write transactions can be issued:</p> <ul style="list-style-type: none"> 31 writes for each of the 8 supported AXI IDs. <p>The processor supports a total of 16 shareable outstanding write transactions from either the cores or the ACP at any time.</p>
Read issuing capability	280	<p>8 per core in the Cortex-A5 MPCore processor including:</p> <ul style="list-style-type: none"> 5 data linefills 1 non-cacheable data read 1 non-cacheable TLB page-walk read 1 instruction fetch, either cacheable linefill or non-cacheable. <p>If the ACP is included in the processor, the following additional read transactions can be issued:</p> <ul style="list-style-type: none"> 31 reads for each of the 8 supported AXI IDs.
Combined issuing capability	796	-
Write ID capability	13	5 AXI IDs are used by the cores in the processor. 8 AXI IDs can be used by the ACP.
Write ID width	5	-
Write interleave capability	1	The AXI master interface presents all write data in order.
Read ID capability	13	5 AXI IDs are used by the cores in the processor. 8 AXI IDs can be used by the ACP.
Read ID width	5	-

The AXI protocol and meaning of each AXI signal are not described in this document. For more information see *AMBA AXI Protocol v1.0 Specification*.

8.1.3 Supported AXI transfers

The Cortex-A5 MPCore processor generates only a subset of all possible AXI transactions on the master interface.

For write-back write-allocate transfers the supported transfers are:

- WRAP4 64-bit for read transfers (linefills)
- INCR4 or WRAP4 64-bit for write transfers (evictions)
- INCR N (N:1-4) 64-bit write transfers.

For non-cacheable transactions:

- INCR N (N:1-4) 64-bit read transfers
- INCR N (N:1-4) 64-bit write transfers
- INCR 1 8-bit, 16-bit, 32-bit, and 64-bit read transfers
- INCR 1 8-bit, 16-bit, 32-bit, and 64-bit exclusive read transfers
- INCR 1 8-bit, 16-bit, 32-bit, and 64-bit exclusive write transfers
- INCR 1 32-bit read/write (locked) for swap
- INCR 1 8-bit read/write (locked) for swap.

For device, or strongly ordered transactions only:

- INCR N (N:1-8) 32-bit read transfers
- INCR N (N:1-8) 32-bit write transfers
- INCR 1 8-bit, 16-bit, and 32-bit read transfers
- INCR 1 8-bit, 16-bit, and 32-bit write transfers
- INCR 1 8-bit, 16-bit, 32-bit, and 64-bit exclusive read transfers
- INCR 1 8-bit, 16-bit, 32-bit, and 64-bit exclusive write transfers
- INCR 1 32-bit read/write (locked) for swap
- INCR 1 8-bit read/write (locked) for swap.

The following points apply to AXI transactions:

- WRAP bursts are only 64-bit, 4 transfers
- INCR 1 can be any size for read or write
- INCR burst (more than one transfer) are only 32-bit or 64-bit
- No transaction is marked as FIXED
- Write transfers with none, some, or all byte strobes low can occur.

Additional transaction types can be generated by a non-cached device connected to the ACP port sharing the master interface with the Cortex-A5 MPCore processor.

8.1.4 AXI transaction IDs

The AXI ID signal encodings are described in *AXI master interfaces* on page A-5.

8.1.5 AXI user bits

In Table 8-2 and Table 8-3 on page 8-5, x represents 0 (primary master port) or 1 (secondary master port).

Table 8-2 shows the bit encodings for **ARUSERM_x[4:0]**

Table 8-2 ARUSERM_x[4:0] encodings

Bits	Name	Description
[4:0]	Inner attributes	b00001 = Strongly ordered b00010 = Device, non-shareable b00011 = Device, shareable b00110 = Non-cacheable, non-shareable b00111 = Non-cacheable, shareable b11110 = Writeback cacheable, read and write allocate, non-shareable b11111 = Writeback cacheable, read and write allocate, shareable

Table 8-3 shows the bit encodings for **AWUSERMx[6:0]**.

Table 8-3 AWUSERMx[6:0] encodings

Bits	Name	Description
[6:5]	Exclusive mode	b00 = Not an eviction b01 = An eviction with dirty data b10 = Not used b11 = An eviction but the data is clean
[4:0]	Inner attributes	b00001 = Strongly ordered b00010 = Device, non-shareable b00011 = Device, shareable b00110 = Non-cacheable, non-shareable b00111 = Non-cacheable, shareable b11110 = Writeback cacheable, read and write allocate, non-shareable b11111 = Writeback cacheable, read and write allocate, shareable

Note

Table 8-2 on page 8-4 and Table 8-3 show the attributes after they have been modified by the TLB remapping, and therefore represent the attributes used by the L1 cache, not necessarily the attributes that were stored in the page tables. If the L1 data cache is disabled, all cacheable memory is remapped to non-cacheable.

The ACP interface AXI user bits **ARUSERS[4:0]** and **AWUSERS[4:0]** are passed through to the AXI master interfaces. For ACP write requests the corresponding value on **AWUSERMx[6:5]** is b00. **ARUSERS[0]** and **AWUSERS[0]** are used to indicated coherent transactions on ACP.

8.1.6 Write response

The AXI master requires that the slave does not return a write response until it has received the write address.

8.1.7 Exclusive L2 cache

The Cortex-A5 MPCore processor can be connected to an L2 cache that supports an exclusive cache mode. This mode must be activated both in the Cortex-A5 MPCore processor and in the L2 cache controller. See *Auxiliary Control Register* on page 4-42.

In this mode, the data cache of the processor and the L2 cache are exclusive. At any time, a given address is cached in either L1 data caches or in the L2 cache, but not in both. This has the effect of greatly increasing the usable space and efficiency of an L2 cache connected to the processor. When exclusive cache configuration is selected:

- Data cache line replacement policy is modified so that the victim line is always evicted to L2 memory, even if it is clean.
- If a line is dirty in the L2 cache controller, a read request to this address from the processor causes writeback to external memory and a linefill to the processor.

8.2 AXI privilege information

AXI provides information about the privilege level of an access on the **ARPROTM_x** and **AWPROTM_x** signals. However, when accesses might be cached or merged together, the resulting transaction can have both privileged and user data combined. If this happens, the Cortex-A5 MPCore processor marks the transaction as privileged, even if it was initiated by a user process.

Table 8-4 shows Cortex-A5 MPCore processor modes and corresponding **ARPROTM_x[0]** and **AWPROTM_x[0]** values.

Table 8-4 Cortex-A5 MPCore mode and APROT values

Processor mode	Type of access	Value of APROT
-	Cacheable read access	Privileged
User	Device, strongly ordered, or normal non-cacheable read access	User
Privileged		Privileged
-	Cacheable write access	Always marked as Privileged
User	Device or strongly ordered write	User
Privileged		Privileged
User	Normal non-cacheable write	Privileged, except for SWP, SWPB, STREX, STREXB, STREXH, and STREXD
Privileged	Normal non-cacheable write	Privileged
-	TLB pagewalk	Privileged

The ACP interface AXI privilege level signals **ARPROTS** and **AWPROTS** are passed through to the AXI master interfaces for ACP requests.

Chapter 9

Snoop Control Unit

This chapter describes the *Snoop Control Unit* (SCU). It contains the following sections:

- *About the SCU* on page 9-2
- *Cortex-A5 MPCore configuration and control registers* on page 9-6
- *SCU registers* on page 9-7
- *Timer and watchdog registers* on page 9-16
- *Global timer registers* on page 9-21.

9.1 About the SCU

The SCU connects between one and four cores in a Cortex-A5 MPCore processor to the memory system. The SCU programmers model also includes support for data security using the TrustZone memory model.

The SCU functions are to:

- maintain data cache coherency between the cores
- initiate L2 AXI memory accesses
- arbitrate between cores requesting L2 accesses
- manage *Accelerator Coherency Port* (ACP) accesses.

The SCU is described in:

- *Cache coherency*
- *SCU master interface*
- *Accelerator Coherency Port* on page 9-3
- *Timer and watchdog* on page 9-4
- *Global timer* on page 9-5.

9.1.1 Cache coherency

The SCU maintains coherency between the individual data caches in the Cortex-A5 MPCore processor using a variation of the MOESI protocol, as described in *Bus Interface Unit and SCU interface* on page 2-6. The SCU contains a set of duplicate tags which enable each coherent data request to be checked against the contents of the other caches in the processor.

The SCU features buffers which can handle direct cache-to-cache transfers between cores without having to read or write any data to the external memory system. Cache line migration enables dirty cache lines to be transferred directly between cores while remaining in the MOESI modified state, and there is no requirement to write-back transferred cache line data to the L2 subsystem.

The SCU features an optional ACP, implemented as an AMBA AXI 64-bit slave port, which can be connected to non-cached coherent masters. See *Accelerator Coherency Port* on page 9-3.

9.1.2 SCU master interface

The SCU can be configured to include one or two 64-bit AMBA AXI master ports. In the two master port configuration, the SCU can be given an address range that redirects all memory transactions in this range to the second master port. The SCU routes all other memory transactions to the first master port. The filtering mode enable control and the address range selection is provided in the SCU control registers, as described in *SCU registers* on page 9-7.

When two master ports are included and address filtering mode is not activated, both ports are used in parallel using a round-robin based load balancing mechanism. Exclusive and locked memory requests are always allocated to the primary AXI master.

The master interfaces can be clocked at integer ratios of the internal processor frequency. The AMBA AXI IDs used by the SCU interface include two extra bits to encode the requesting core or that the request came from the ACP.

9.1.3 Accelerator Coherency Port

The ACP is an AXI 64-bit slave port which can be connected to a DMA engine or a non-cached coherent master. The ACP interface supports an AXI ID width of 3. In systems where more AXI IDs are required, an additional bridge component is required to arbitrate between the different sources of requests.

Transactions on the ACP port can be marked as coherent or non-coherent. Coherent transactions are indicated by (**ARUSERS**[0] & **ARCACHES**[1]) or (**AWUSERS**[0] & **AWCACHES**[1]). Device or Strongly Ordered transactions are always treated as non-coherent. Non-coherent transactions pass through the SCU and are presented on the AXI master interface unchanged. Coherent AXI transactions on the ACP slave can be changed into more or fewer transactions on the AXI master interface with some of their attributes changed appropriately. The transformations performed are consistent with ARM architectural ordering and AXI ordering models.

The **ARUSERS** and **AWUSERS** signals are passed through unchanged to AXI master interface if the transaction, or part of the transaction appears on the external system. If the AXI USER signals are used by the system, ensure that either the encoding used on the ACP matches that used by the Cortex-A5 MPCore processor as described in *AXI user bits* on page 8-4, or that the external system can distinguish between transactions from ACP and the processor.

The following sections describe the ACP:

- *ACP requests*
- *ACP limitations* on page 9-4.

ACP requests

When a coherent write request is received on the ACP from the external master, the data caches of the cores are checked for the address. If present, the coherency protocol cleans and invalidates the appropriate lines in the processor and merges the cleaned data with the write request.

For coherent read requests from the external master, if the address is found in the processor data caches, either dirty or clean, the read data is returned to the external master through the ACP interface. If the address is not present in the data caches, an external request is made on the SCU AXI master interface and the data returned to the ACP from the external system.

———— Note —————

The external master and all cores must all agree that a particular physical address and NS combination is shareable or non-shareable. If the ACP master and cores disagree, the data will be corrupted.

A peripheral connected on the ACP can participate in the WFE/SEV event communication of the Cortex-A5 MPCore processor by using the external **EVENTI** signal. When this signal is asserted, an event message is sent to all the cores in the processor. This is equivalent to software executing an SEV instruction on one of the cores. This feature enables the peripheral to wake up the cores from power-saving mode if, for example, a semaphore has been released. There is also a complementary external output signal, **EVENTO**, which is raised when one of the cores in the processor executes an SEV instruction. **EVENTI** must be raised for a single **CLKIN** cycle to be visible to the cores in the processor. **EVENTO** is raised for a single cycle, and must be latched by the external signal if it cannot be dealt with immediately.

The ACP interface supports the same clocking schemes as the AXI master ports.

ACP limitations

The ACP is optimized for cache-line length transfers and it supports a wide range of AMBA 3 AXI requests, but it has some limitations that must be considered. This section describes the ACP limitations in:

- *ACP performance limitations*
- *ACP functional limitations.*

ACP performance limitations

ACP accesses are optimized for transfers which match, or are a subset of, the coherent requests generated by the cores inside the Cortex-A5 MPCore processor:

- a wrapped burst of four doublewords (length = 3, size = 3), with a 64-bit aligned address
- a wrapped burst of two doublewords (length = 1, size = 3), with a 128-bit aligned address
- an incremental burst of four or less doublewords, that does not cross a cache line boundary.

For maximum performance, use ACP accesses that match this format. ACP accesses that do not match this format are supported but cannot benefit from the SCU optimizations, and have lower performance.

ACP functional limitations

The ACP is a full AMBA 3 AXI slave component, with the exception of the following transfers which are not supported:

- coherent exclusive read and write transfers
- coherent locked read and write transfers.

As a consequence, it is not possible to use the LDREX/STREX mechanism through the ACP to gain exclusive access to coherent memory regions, which are marked with **AxUSER[0]** = 1 and **AxCACHE[1]** = 1. However, the LDREX/STREX mechanism is fully supported through the ACP for non-coherent memory regions, marked with **AxUSER[0]** = 0 or **AxCACHE[1]** = 0.

The only locked transactions supported through ACP consist of a locking read transaction, **ARLOCK[1]** = 1, followed by an unlocking write transaction, **AWLOCK[1]** = 0, both to non-coherent memory regions, marked with **AxUSER[0]** = 0 or **AxCACHE[1]** = 0. Any other combination of locking and unlocking transactions result in unpredictable behavior.

9.1.4 Timer and watchdog

The SCU provides a timer and watchdog blocks for each core in the processor. Both timer and watchdog blocks have the following features:

- a 32-bit decrementing counter that generates an interrupt when it reaches zero
- a 8-bit pre-scaler to enable better control of the timer period
- configurable single-shot or auto-reload modes
- configurable starting values for the counter
- the clock for the timer and watchdog blocks is **PERIPHCLK**.

The watchdog can generate a reset request when the counter reaches zero. It can also be configured as a timer, if necessary. Each timer and watchdog is directly connected to the Interrupt Controller through a dedicated interrupt interface.

9.1.5 Global timer

The SCU provides an additional 64-bit global timer accessible to all cores in the Cortex-A5 MPCore processor. The global timer includes a 64-bit incrementing counter and each core present in the processor has a separate 64-bit comparator register in the SCU, which can be used to assert a private interrupt when the counter reaches a particular value. All the cores use a common interrupt number, ID27, for this event, sent to the interrupt controller as a private peripheral interrupt. The clock for the global timer is **PERIPHCLK**

9.2 Cortex-A5 MPCore configuration and control registers

The SCU and internal peripherals are controlled and configured using a set of memory-mapped registers grouped into two contiguous 4KB pages accessed through a dedicated internal bus. The base address of these pages is defined by the external configuration signal **PERIPHBASE[31:13]**. ARM recommends that you tie this to a constant value. It can be changed during reset of the SCU, but must not be changed at any other time.

Each core in the processor contains a read-only/write-ignored CP15 *Configuration Base Address Register* (CBAR) that delivers the value the SCU is using. See *Configuration Base Address Register* on page 4-68.

Table 9-1 shows the layout of the registers in the memory region. Access to the reserved regions can result in a data abort exception in the requesting core.

Table 9-1 Cortex-A5 memory-mapped registers

Address offset	Peripheral
0x0000-0x00FF	SCU control and configuration
0x0100-0x01FF	Interrupt interface registers
0x0200-0x02FF	Global timer
0x0300-0x05FF	Reserved
0x0600-0x06FF	Timer and watchdog
0x0700-0x0FFF	Reserved
0x1000-0x1FFF	Interrupt distributor

In software the memory regions mapped to the peripheral registers must be marked as Device or Strongly-ordered. Normal cacheable or non-cacheable transactions to the region are treated as regular memory requests in the SCU. The registers can only be accessed with single load and store instructions. Load and store multiple, and load and store double instructions that transfer more than a single register cannot be used, and result in a data abort exception. Do not use NEON load and store instructions to access the registers because the results are unpredictable.

Most of the registers only accept byte and word requests except for the timer and watchdog registers which can only be accessed using word size transactions. Memory requests to the register region using an invalid size result in a data abort exception in the requesting core.

All data aborts from resulting from invalid transactions to the peripheral region are reported as a slave error in the *Data Fault Status Register* (DFSR).

The ACP cannot access any of the registers in this memory region. Any Device or Strongly-ordered request received on the ACP AXI slave interface is passed through the SCU to the AXI master interface.

The registers support TrustZone using the architecturally-defined memory security level access mechanism. Some of the registers are banked in Secure and Non-secure modes, and some are common. The appropriate banked or common registers can be read in Secure and Non-secure state. Write access is controlled for each core in the processor individually by the *SCU Access Control Register* (SAC) and the *SCU Secure Access Control Register* (SSAC). Write requests to registers without the appropriate access permissions set up with these registers are ignored without any exception occurring.

9.3 SCU registers

Table 9-2 shows the SCU registers. Addresses are relative to the base address of the region for the SCU memory map, which is **PERIPHBASE[31:13]**. All SCU registers are byte accessible and are reset by **nSCURESET**.

Table 9-2 SCU register summary

Offset from PERIPHBASE [31:13]	Name	Security state		Reset value	Banked	Page
		S	NS			
0x00	SCU Control Register	RW ^a	RW ^b	Implementation-defined	N	page 9-7
0x04	SCU Configuration Register	RO	RO	Implementation-defined	N	page 9-8
0x08	SCU CPU Power Status Register	RW ^a	RW ^b	-	N	page 9-9
0x0C	SCU Invalidate All in Secure State Register	WO ^a	-	-	N	page 9-11
0x40	SCU Filtering Start Address Register	RW ^a	RW ^b	Defined by FILTERSTART input ^c	N	page 9-12
0x44	SCU Filtering End Address Register	RW ^a	RW ^b	Defined by FILTEREND input ^c	N	page 9-12
0x50	SCU Access Control Register	RW ^a	RW ^b	0xF	N	page 9-13
0x54	SCU Secure Access Control Register	RW ^a	RO	0x0	N	page 9-14

- This register is writable if the relevant bits in the SCU Access Control Register are set.
- This register is writable if the relevant bits in the SCU Access Control Register and SCU Secure Access Control Register are set.
- If the optional second AXI master is not configured these registers reset to 0x0.

9.3.1 SCU Control Register

The SCU Control Register characteristics are:

Purpose	<ul style="list-style-type: none"> enables the SCU enables address filtering.
Usage constraints	<ul style="list-style-type: none"> This register is writable in Secure state if the relevant bit in the SAC register is set. This register is writable in Non-secure state if the relevant bits in the SAC and SSAC registers are set.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 9-2.

Figure 9-1 on page 9-8 shows the SCU Control Register bit assignments.

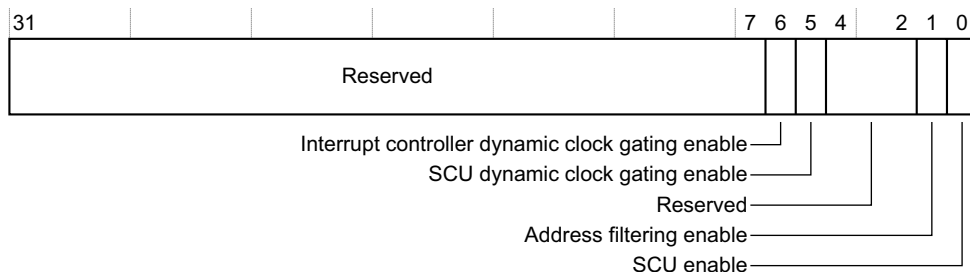


Figure 9-1 SCU Control Register bit assignments

Table 9-3 shows the SCU Control Register bit assignments.

Table 9-3 SCU Control Register bit assignments

Bits	Name	Description
[31:7]	Reserved	SBZ
[6]	Interrupt Controller Dynamic clock gating enable	Dynamically gate the clock to the Interrupt Controller logic when no interrupts are pending, and no CPU core in the processor is performing a read/write request to Interrupt Controller registers: 1 = Enable Dynamic clock gating 0 = Disable Dynamic clock gating. This is the default setting.
[5]	SCU Dynamic clock gating enable	Dynamically gate the clock to the SCU logic when all the CPU cores included in the processor are in one of the low-power modes, that is, Standby, Dormant, or Shutdown: 1 = Enable Dynamic clock gating 0 = Disable Dynamic clock gating. This is the default setting.
[4:2]	Reserved	SBZ
[1]	Address filtering enable	1 = Addressing filtering on. 0 = Addressing filtering off. The default value is the value of FILTEREN sampled on exit from reset. This bit is always zero if the SCU is implemented in the single master port configuration.
[0]	SCU enable	1 = SCU enable. 0 = SCU disable. This is the default setting.

9.3.2 SCU Configuration Register

The SCU Configuration Register characteristics are:

- Purpose**
- read the number of number of cores present in the processor
 - read the data cache sizes for the cores present in the Cortex-A5 MPCore processor
 - determine the cores in the processor that are taking part in coherency.
- Usage constraints** This register is read-only.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 9-2 on page 9-7.

Figure 9-2 on page 9-9 shows SCU Configuration Register bit assignments.

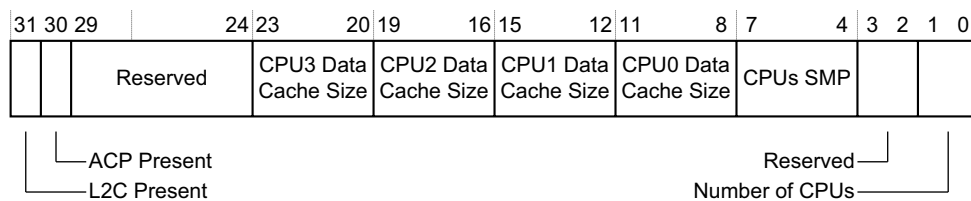


Figure 9-2 SCU Configuration Register bit assignments

Table 9-4 shows the SCU Configuration Register bit assignments.

Table 9-4 SCU Configuration Register bit assignments

Bits	Name	Description
[31]	L2C Present	Reflects the value of the L2CPRESENT external input signal. This enables software to determine the presence of an L2 cache controller in the system.
[30]	ACP Present	Reflects the <i>Accelerator Coherency Port</i> (ACP) configuration of the Cortex-A5 MPCore processor: 0 = ACP not present in the processor 1 = ACP present in the processor.
[29:24]	Reserved	SBZ.
[23:20]	CPU3 Data Cache Size	Data cache size of each core in the Cortex-A5 MPCore processor: b0000 = 4KB / CPU<n> Not present
[19:16]	CPU2 Data Cache Size	b0001 = 8KB
[15:12]	CPU1 Data Cache Size	b0011 = 16KB
[11:8]	CPU0 Data Cache Size	b0111 = 32KB b1111 = 64KB The presence of a particular CPU in the system can be determined by the value in bits [1:0].
[7:4]	CPUs SMP	Defines the cores that are in <i>Symmetric Multiprocessing</i> (SMP) or <i>Asymmetric Multiprocessing</i> (AMP) mode. 0 = this core is in AMP mode not taking part in coherency or not present. 1 = this core is in SMP mode taking part in coherency. Bit 7 is for CPU3 Bit 6 is for CPU2 Bit 5 is for CPU1 Bit 4 is for CPU0.
[3:2]	Reserved	SBZ
[1:0]	Number of CPUs	Number of CPUs present in the Cortex-A5 MPCore processor: b11 = four cores, CPU0, CPU1, CPU2, and CPU3 b10 = three cores, CPU0, CPU1, and CPU2 b01 = two cores, CPU0 and CPU1 b00 = one core, CPU0.

9.3.3 SCU CPU Power Status Register

The SCU CPU Power Status Register characteristics are:

Purpose Specifies the state of the Cortex-A5-MPCore processors with reference to power modes.

Usage constraints This register is writable in Secure state if the relevant bit in the SAC register is set.

This register is writable in Non-secure state if the relevant bits in the SAC and SSAC registers are set.

Dormant mode and powered-off mode are controlled by an external power controller. SCU CPU Status Register bits indicate to the external power controller the power domains that can be powered down.

Before entering any other power mode than Normal, the processor must set its status field to signal to the SCU the mode it is about to enter so that the SCU can determine if it still can send coherency requests to the processor. The processor then executes a WFI entry instruction. When in WFI state, the **PWRCTLOn[1:0]** bus is enabled and signals to the power controller what it must do with power domains.

The SCU CPU Power Status Register bits can also be read by a processor exiting low-power mode to determine its state before executing its reset set-up.

Cortex-A5 processor status fields take **PWRCTLIn[1:0]** values at reset, except for nonpresent processors. For nonpresent processors writing to this field has no effect.

Configurations Available in all configurations.

Attributes See the register summary in Table 9-2 on page 9-7.

Figure 9-3 shows the SCU CPU Power Status Register bit assignments.

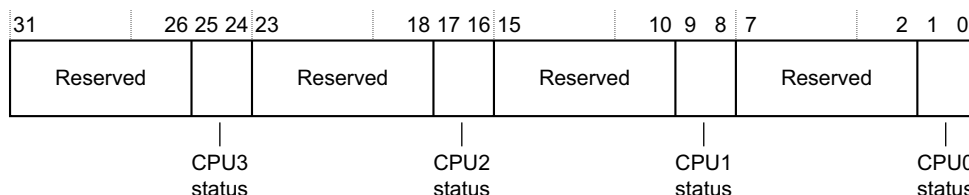


Figure 9-3 SCU CPU Power Status Register bit assignments

Table 9-5 shows the SCU CPU Power Status Register bit assignments.

Table 9-5 SCU CPU Power Status Register bit assignments

Bits	Name	Description
[31:26]	Reserved	SBZ
[25:24]	CPU3 status	Power status of the core in the Cortex-A5 MPCore processor: b00 = Normal mode. b01 = Reserved. b10 = the core is about to enter (or is in) dormant mode. No coherency requests ^a are sent to the core. b11 = the core is about to enter (or is in) powered-off mode, or is nonpresent. No coherency requests ^a are sent to the core.
[23:18]	Reserved	SBZ
[17:16]	CPU2 status	Power status of the core.
[15:10]	Reserved	SBZ

Table 9-5 SCU CPU Power Status Register bit assignments (continued)

Bits	Name	Description
[9:8]	CPU1 status	Power status of the core.
[7:2]	Reserved	SBZ
[1:0]	CPU0 status	Power status of the core.

a. Coherency requests include CP15 maintenance operations forwarded from other cores in the processor.

9.3.4 SCU Invalidate All in Secure State Register

The SCU Invalidate All in Secure State Register characteristics are:

Purpose Invalidates the SCU tag RAMs on a per-core basis.

Usage constraints This register:

- Invalidates all lines.
- Is writable in Secure state if the relevant bit in the SAC register is set.

When using the SCU Invalidate All operations the programmer must ensure that no shared data is present in the level 1 data cache of the corresponding core in the Cortex-A5 MPCore processor. This results in unpredictable behavior by the processor.

Configurations Available in all configurations.

Attributes See the register summary in Table 9-2 on page 9-7.

Figure 9-4 shows the SCU Invalidate All in Secure State Register bit assignments.

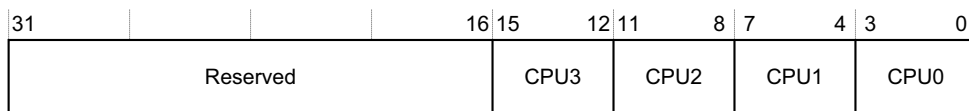


Figure 9-4 SCU Invalidate All in Secure State Register bit assignments

Table 9-6 shows the SCU Invalidate All in Secure State Register bit assignments.

Table 9-6 SCU Invalidate All in Secure State Register bit assignments

Bits	Name	Description
[31:16]	Reserved	SBZ
[15:12]	CPU3	Invalidate the tag RAMs for CPU3. Writing to these bits has no effect if the Cortex-A5 MPCore processor has fewer than four cores.
[11:8]	CPU2	Invalidate the tag RAMs for CPU2. Writing to these bits has no effect if the Cortex-A5 MPCore processor has fewer than three cores.
[7:4]	CPU1	Invalidate the tag RAMs for CPU1. Writing to these bits has no effect if the Cortex-A5 MPCore processor has fewer than two cores.
[3:0]	CPU0	Invalidate the tag RAMs for CPU0. ^a

a. The invalidate operation only takes place if the value b1111 is written to the CPU fields in this register. Other values have no effect.

9.3.5 SCU Filtering Start Address Register

The SCU Filtering Start Address Register characteristics are:

Purpose	Provides the start address for use with master port 1 in a two-master port configuration. If the end address is a lower value than the start address, master port 1 is not used. If the start address is the same as the end address, a 1MB section of the address space is filtered to master port 1.
Usage constraints	<ul style="list-style-type: none"> This register is writable in Secure state if the relevant bit in the SAC register is set. This register is writable in Non-secure state if the relevant bits in the SAC and SSAC registers are set.
Configurations	Available in all two-master port configurations. When only one master port is present writes have no effect and reads return a value of 0x0 for all filtering registers.
Attributes	See the register summary in Table 9-2 on page 9-7.

Figure 9-5 shows the SCU Filtering Start Address Register bit assignments.



Figure 9-5 SCU Filtering Start Address Register bit assignments

Table 9-7 shows the SCU Filtering Start Address Register bit assignments.

Table 9-7 SCU Filtering Start Address Register bit assignments

Bits	Name	Description
[31:20]	Filtering start address	Start address for use with master port 1 in a two-master port configuration when address filtering is enabled. The default value is the value of FILTERSTART sampled on exit from reset. The value on the pin gives the upper address bits with 1MB granularity.
[19:0]	Reserved	SBZ

See *Configuration signals* on page A-3.

9.3.6 SCU Filtering End Address Register

The SCU Filtering End Address Register characteristics are:

Purpose	Provides the end address for use with master port 1 in a two-master port configuration.
Usage constraints	<ul style="list-style-type: none"> This register is writable in Secure state if the relevant bit in the SAC register is set. This register is writable in Non-secure state if the relevant bits in the SAC and SSAC registers are set. The filtering end address is an inclusive address. This means that the topmost megabyte of address space of memory can be included in the filtering address range.

Configurations Available in all two-master port configurations. When only one master port is present writes have no effect and reads return a value of 0x0 for all filtering registers.

Attributes See the register summary in Table 9-2 on page 9-7.

Figure 9-6 shows the SCU Filtering End Address Register bit assignments.



Figure 9-6 SCU Filtering End Address Register bit assignments

Table 9-8 shows the SCU Filtering End Address Register bit assignments.

Table 9-8 SCU Filtering End Address Register bit assignments

Bits	Name	Description
[31:20]	Filtering end address	End address for use with master port 1 in a two-master port configuration, when address filtering is enabled. The default value is the value of FILTEREND sampled on exit from reset. The value on the pin gives the upper address bits with 1MB granularity.
[19:0]	Reserved	SBZ

See *Configuration signals* on page A-3.

9.3.7 SCU Access Control Register

The SAC Register characteristics are:

- Purpose** Controls access to the following registers on a per-core basis:
- *SCU Control Register* on page 9-7
 - *SCU CPU Power Status Register* on page 9-9
 - *SCU Invalidate All in Secure State Register* on page 9-11
 - *SCU Filtering Start Address Register* on page 9-12
 - *SCU Filtering End Address Register* on page 9-12
 - *SCU Access Control Register*
 - *SCU Secure Access Control Register* on page 9-14.
- Usage constraints**
- This register is writable in Secure state if the relevant bit in the SAC register is set.
 - This register is writable in Non-secure state if the relevant bits in the SAC and SSAC registers are set.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 9-2 on page 9-7.

Figure 9-7 on page 9-14 shows the SAC Register bit assignments.

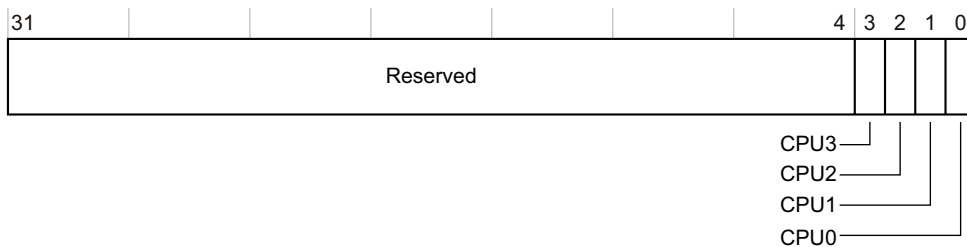


Figure 9-7 SAC Register bit assignments

Table 9-9 shows the SAC Register bit assignments.

Table 9-9 SAC Register bit assignments

Bits	Name	Description
[31:4]	Reserved	SBZ
[3]	CPU3	0 = CPU3 cannot write the registers. ^a 1 = CPU3 can write the registers. This is the default.
[2]	CPU2	0 = CPU2 cannot write the registers. ^a 1 = CPU2 can write the registers. This is the default.
[1]	CPU1	0 = CPU1 cannot write the registers. ^a 1 = CPU1 can write the registers. This is the default.
[0]	CPU0	0 = CPU0 cannot write the registers. ^a 1 = CPU0 can write the registers. This is the default.

a. The accessible registers are the SAC Register, the SSAC Register, the SCU Control Register, the SCU CPU Power Status Register, the SCU Invalidate All Register, and the filtering registers. Write requests to non-accessible registers are ignored.

A core in the Cortex-A5 MPCore processor can set up the SCU and then write zero to this register. This prevents any Secure or Non-secure access from altering the configuration of the register again. This is intended to prevent any further changes to the SCU configuration after booting.

9.3.8 SCU Secure Access Control Register

The SSAC characteristics are:

Purpose	Controls Non-secure access to the following registers on a per-core basis: <ul style="list-style-type: none"> • <i>SCU Control Register</i> on page 9-7 • <i>SCU CPU Power Status Register</i> on page 9-9 • <i>SCU Filtering Start Address Register</i> on page 9-12 • <i>SCU Filtering End Address Register</i> on page 9-12 • <i>SCU Access Control Register</i> on page 9-13.
Usage constraints	This register is writable in Secure state if the relevant bit in the SAC register is set.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 9-2 on page 9-7.

Figure 9-8 shows the SSAC Register bit assignments.

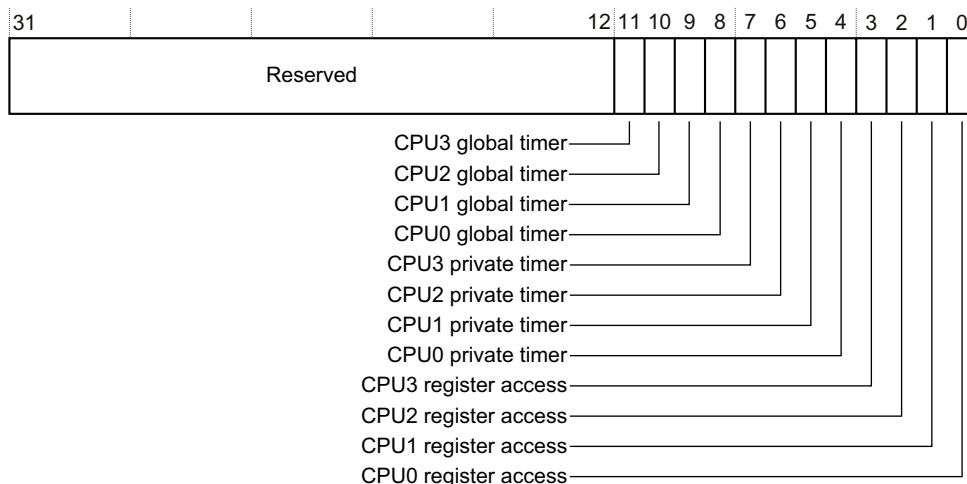


Figure 9-8 SSAC Register bit assignments

Table 9-10 shows the SSAC Register bit assignments.

Table 9-10 SSAC Register bit assignments

Bits	Name	Description
[31:12]	Reserved	SBZ
[11]	CPU3 global timer	Global timer access:
[10]	CPU2 global timer	0 = CPU<n> can only access the timer registers in Secure state. In Non-Secure state writes are ignored and reads return 0. This is the default value.
[9]	CPU1 global timer	1 = CPU<n> can access the timer registers in Secure and Non-Secure state.
[8]	CPU0 global timer	
[7]	CPU3 private timer	Private timer access:
[6]	CPU2 private timer	0 = CPU<n> can only access the timer registers in Secure state. In Non-Secure state writes are ignored and reads return 0. This is the default value.
[5]	CPU1 private timer	1 = CPU<n> can access the timer registers in Secure and Non-Secure state.
[4]	CPU0 private timer	
[3]	CPU3 register access	SCU register access: ^a
[2]	CPU2 register access	0 = CPU<n> cannot write the registers in Non-Secure state. This is the default value.
[1]	CPU1 register access	1 = CPU<n> can write the registers in Non-Secure state.
[0]	CPU0 register access	The accessible registers are the SAC Register, the SCU Control Register, the SCU CPU Power Status Register, and the filtering registers. Write requests to non-accessible registers are ignored.

a. Write access to the SCU registers in both Secure and Non-Secure state can be controlled by the SAC register.

9.4 Timer and watchdog registers

Addresses are relative to the base address of the timer and watchdog region defined by the SCU memory map, which is determined by **PERIPBASE[31:13]**.

Each core in the Cortex-A5 MPCore processor has its own set of private registers. All timer and watchdog registers are word-accessible only.

Use **nWDRESET** to reset the Watchdog Reset Status Register. Do not use NEON load and store instructions to access the registers because the results are unpredictable.

Access to the timer and watchdog registers in Secure and Non-secure state is controlled by the SSAC Register. See *SCU Secure Access Control Register* on page 9-14. The watchdog and timers are always accessible in the Secure state. They are only accessible from the Non-secure state if the SSAC register has the appropriate bit set. The SAC Register does not affect access.

Table 9-11 shows the timer and watchdog registers. All registers not described in Table 9-11 are Reserved.

Table 9-11 Timer and watchdog registers

Offset	Type	Reset value	Description
0x600	RW	0x00000000	Timer Load Register
0x604	RW	0x00000000	Timer Counter Register
0x608	RW	0x00000000	Timer Control Register on page 9-17
0x60C	RW	0x00000000	Timer Interrupt Status Register on page 9-18
0x620	RW	0x00000000	Watchdog Load Register on page 9-18
0x624	RW	0x00000000	Watchdog Counter Register on page 9-18
0x628	RW	0x00000000	Watchdog Control Register on page 9-19
0x62C	RW	0x00000000	Watchdog Interrupt Status Register on page 9-20
0x630	RW	0x00000000	Watchdog Reset Status Register on page 9-20
0x634	WO	-	Watchdog Disable Register on page 9-20

9.4.1 Timer Load Register

The Timer Load Register contains the value copied to the Timer Counter Register when it decrements down to zero with auto reload mode enabled. Writing to the Timer Load Register means that you also write to the Timer Counter Register.

9.4.2 Timer Counter Register

The Timer Counter Register is a decrementing counter.

The Timer Counter Register decrements if the timer is enabled using the timer enable bit in the Timer Control Register. If the core in the Cortex-A5 MPCore processor belonging to the timer is in debug state, the counter does not decrement until the core returns to non-debug state.

When the Timer Counter Register reaches zero and auto-reload mode is enabled, it reloads the value in the Timer Load Register and then decrements from that value. If auto-reload mode is not enabled, the Timer Counter Register decrements down to zero and stops.

When the Timer Counter Register reaches zero, the timer interrupt status event flag is set and the interrupt ID 29 is set as pending in the Interrupt Distributor, if interrupt generation is enabled in the Timer Control Register.

Writing to the Timer Counter Register or Timer Load Register forces the Timer Counter Register to decrement from the newly-written value.

9.4.3 Timer Control Register

Figure 9-9 shows the Timer Control Register bit assignments.

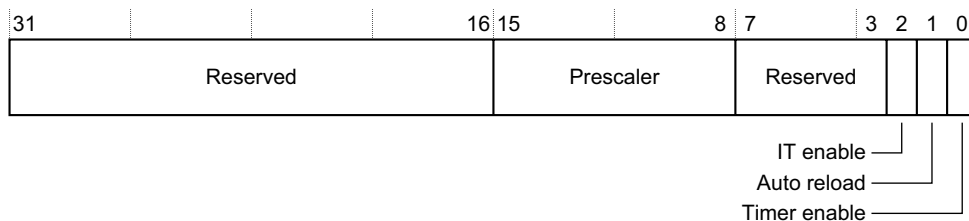


Figure 9-9 Timer Control Register bit assignments

Table 9-12 shows the Timer Control Register bit assignments.

Table 9-12 Timer Control Register bit assignments

Bits	Name	Description
[31:16]	Reserved	UNK/SBZP.
[15:8]	Prescaler	The prescaler modifies the clock period for the decrementing event for the Counter Register. The time between updates to the Counter Register is given by $(\text{Prescaler}+1) \times \text{PERIPHCLK}$ period.
[7:3]	Reserved	UNK/SBZP.
[2]	IT Enable	If set, the interrupt ID 29 is set as pending in the Interrupt Distributor when the event flag is set in the Timer Status Register.
[1]	Auto reload	b0 = Single shot mode. Counter decrements down to zero, sets the event flag and stops. b1 = Auto-reload mode. Each time the Counter Register reaches zero, it is reloaded with the value contained in the Timer Load Register.
[0]	Timer Enable	Timer enable: b0 = Timer is disabled and the counter does not decrement. All registers can still be read and written. b1 = Timer is enabled and the counter decrements normally.

9.4.4 Timer Interrupt Status Register

Figure 9-10 shows the Timer Interrupt Status Register bit assignment. The event flag is a sticky bit that is automatically set when the Counter Register reaches 0. If the timer interrupt is enabled, Interrupt ID 29 is set as pending in the Interrupt Distributor after the event flag is set. The event flag is cleared when written to 1. Attempting to write a 0 to the event flag bit, or writing a 1 when no timer event is active has no effect.

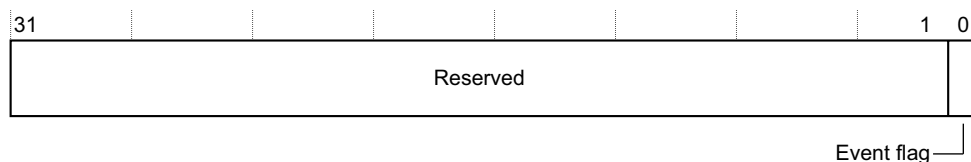


Figure 9-10 Timer Interrupt Status Register bit assignments

9.4.5 Watchdog Load Register

The Watchdog Load Register contains the value copied to the Watchdog Counter Register when it decrements down to zero with auto-reload mode enabled, in Timer mode. Writing to the Watchdog Load Register means that you also write to the Watchdog Counter Register.

9.4.6 Watchdog Counter Register

The Watchdog Counter Register is a decrementing counter. It decrements if the Watchdog is enabled using the Watchdog enable bit in the Watchdog Control Register. If the core in the Cortex-A5 MPCore processor belonging to the Watchdog is in debug state, the counter does not decrement until the core returns to non-debug state.

When the Watchdog Counter Register reaches zero and auto-reload mode is enabled, and in timer mode, it reloads the value in the Watchdog Load Register and then decrements from that value. If auto-reload mode is not enabled or the watchdog is not in timer mode, the Watchdog Counter Register decrements down to zero and stops.

When in watchdog mode, the only way to update the Watchdog Counter Register is to write to the Watchdog Load Register. When in timer mode the Watchdog Counter Register is write accessible.

The behavior of the watchdog when the Watchdog Counter Register reaches zero depends on its current mode:

Timer mode When the Watchdog Counter Register reaches zero, the watchdog interrupt status event flag is set and the interrupt ID 30 is set as pending in the Interrupt Distributor, if interrupt generation is enabled in the Watchdog Control Register.

Watchdog mode

If a software failure prevents the Watchdog Counter Register from being refreshed, the Watchdog Counter Register reaches zero, the Watchdog reset status flag is set and the associated **WDRESETREQ** reset request output pin is asserted. The external reset source is then responsible for resetting the Cortex-A5 MPCore processor.

9.4.7 Watchdog Control Register

Figure 9-11 shows the Watchdog Control Register bit assignments.

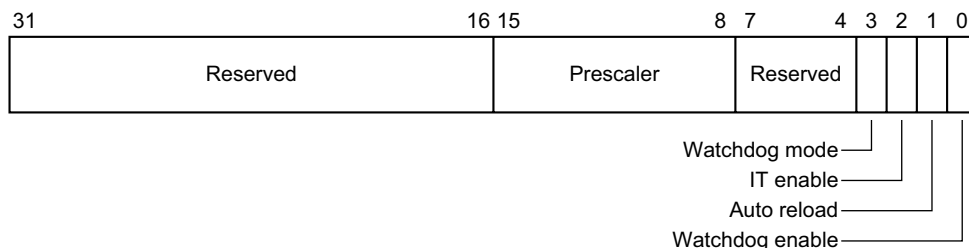


Figure 9-11 Watchdog Control Register bit assignments

Table 9-13 shows the Watchdog Control Register bit assignments.

Table 9-13 Watchdog Control Register bit assignments

Bits	Name	Description
[31:16]	Reserved	RAZ
[15:8]	Prescaler	The prescaler modifies the clock period for the decrementing event for the Counter Register. The time between updates to the Counter Register is given by $(\text{Prescaler}+1) \times \text{PERIPHCLK}$ period.
[7:4]	Reserved	RAZ
[3]	Watchdog mode	b0 = Timer mode, default Writing a zero to this bit has no effect. You must use the Watchdog Disable Register to put the watchdog into timer mode. See <i>Watchdog Disable Register</i> on page 9-20. b1 = Watchdog mode.
[2]	IT Enable	If set, the interrupt ID 30 is set as pending in the Interrupt Distributor when the event flag is set in the watchdog Status Register. In watchdog mode this bit is ignored.
[1]	Auto-reload	b0 = Single shot mode. Counter decrements down to zero, sets the event flag and stops. b1 = Auto-reload mode. Each time the Counter Register reaches zero, it is reloaded with the value contained in the Load Register and then continues decrementing.
[0]	Watchdog Enable	Global watchdog enable: b0 = Watchdog is disabled and the counter does not decrement. All registers can still be read and/or written b1 = Watchdog is enabled and the counter decrements normally.

9.4.8 Watchdog Interrupt Status Register

Figure 9-12 shows the Watchdog Interrupt Status Register bit assignments.

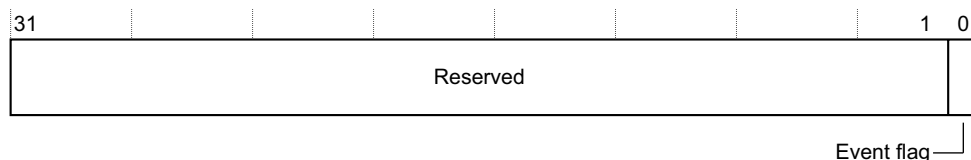


Figure 9-12 Watchdog Interrupt Status Register bit assignments

The event flag is a sticky bit that is automatically set when the Counter Register reaches 0 in timer mode. If the watchdog interrupt is enabled, Interrupt ID 30 is set as pending in the Interrupt Distributor after the event flag is set. The event flag is cleared when written with a value of 1. Trying to write a 0 to the event flag or a 1 when it is not set has no effect.

9.4.9 Watchdog Reset Status Register

Figure 9-13 shows the Watchdog Reset Status Register bit assignments.

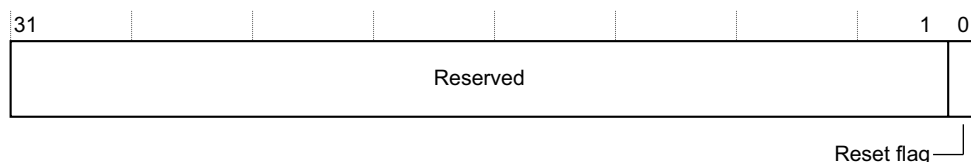


Figure 9-13 Watchdog Reset Status Register bit assignments

The reset flag is a sticky bit that is automatically set when the Counter Register reaches 0 and a reset request is sent accordingly, in watchdog mode.

The reset flag is cleared when written with a value of 1. Trying to write a 0 to the reset flag or a one when it is not set has no effect. This flag is not reset by normal Cortex-A5 MPCore processor resets but has its own reset line that must not be asserted when the processor reset assertion is the result of a watchdog reset request with **WDRESETREQ**. This distinction enables software to differentiate between a normal boot sequence, reset flag is 0, and one caused by a previous watchdog time-out, reset flag set to 1.

9.4.10 Watchdog Disable Register

Use the Watchdog Disable Register to switch from watchdog to timer mode. The software must write 0x12345678 then 0x87654321 successively to the Watchdog Disable Register so that the watchdog mode bit in the Watchdog Control Register is set to 0.

If one of the values written to the Watchdog Disable Register is incorrect or if any other write occurs in between the two word writes, the watchdog remains in its current state. To reactivate the Watchdog, the software must write 1 to the watchdog mode bit of the Watchdog Control Register. See *Watchdog Control Register* on page 9-19.

9.5 Global timer registers

Addresses are relative to the base address of the timer and watchdog region defined by the SCU memory map, which is determined by **PERIPBASE[31:13]**.

Access to the global timer registers in Secure and Non-secure state is controlled by the SSAC Register. See *SCU Secure Access Control Register* on page 9-14.

Table 9-14 shows the global timer registers. All registers not described in Table 9-14 are Reserved. Use **nPERIPHRESET** to reset these registers.

Table 9-14 Global timer registers

Offset	Type	Reset value	Description
0x200	RW	0x00000000	<i>Global Timer Counter Registers, 0x00 and 0x04</i>
0x204	RW	0x00000000	
0x208	RW	0x00000000	<i>Global Timer Control Register</i> on page 9-22
0x20C	RW	0x00000000	<i>Global Timer Interrupt Status Register</i> on page 9-23
0x210	RW	0x00000000	<i>Comparator Value Registers</i> on page 9-23
0x214	RW	0x00000000	
0x218	RW	0x00000000	<i>Auto-increment Register</i> on page 9-23

9.5.1 Global Timer Counter Registers, 0x00 and 0x04

There are two timer counter registers, the lower 32-bit timer counter and the upper 32-bit timer counter.

You must access these registers with 32-bit accesses. You cannot use LDM/STM or LDRD/STRD or NEON load or store instructions.

To modify the register proceed as follows:

1. Clear the timer enable bit in the Global Timer Control Register.
2. Write the lower 32-bit timer counter register.
3. Write the upper 32-bit timer counter register.
4. Set the timer enable bit.

To get the value from the Global Timer Counter register proceed as follows:

1. Read the upper 32-bit timer counter register.
2. Read the lower 32-bit timer counter register.
3. Read the upper 32-bit timer counter register again. If the value is different to the 32-bit upper value read previously, go back to step 2. Otherwise the 64-bit timer counter value is correct.

9.5.2 Global Timer Control Register

This register controls the operation of the timer peripheral including the primary enable bit and the prescaler and auto-increment functionality. Figure 9-14 shows the Global Timer Control Register bit assignments.

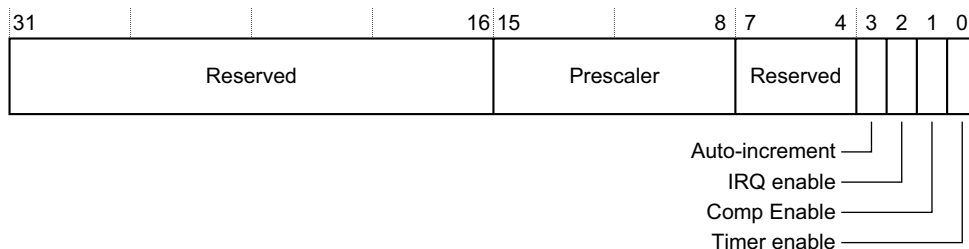


Figure 9-14 Global Timer Control Register bit assignments

Table 9-15 shows the Global Timer Control Register bit assignments.

Table 9-15 Global Timer Control Register bit assignments

Bits	Name	Description
[31:16]	Reserved	SBZ
[15:8]	Prescaler	The prescaler modifies the clock period for the incrementing event for the Counter Register. The time between updates to the Counter Register is given by $(\text{Prescaler}+1) \times \text{PERIPHCLK}$ period.
[7:4]	Reserved	SBZ
[3]	Auto-increment ^a	This bit is banked per core in the Cortex-A5 MPCore processor. b0 = single shot mode. When the counter reaches the comparator value, sets the event flag. The software is responsible for updating the comparator value to get further events. b1 = auto-increment mode. Each time the counter reaches the comparator value, the comparator register is incremented with the auto-increment register, so that further events can be set periodically without any software updates.
[2]	IRQ Enable	This bit is banked per core in the Cortex-A5 MPCore processor. If set, the interrupt ID 27 is set as pending in the Interrupt Distributor when the event flag is set in the Timer Status Register.
[1]	Comp Enable ^a	This bit is banked per core in the Cortex-A5 MPCore processor. If set, it allows the comparison between the 64-bit Timer Counter and the related 64-bit Comparator Register.
[0]	Timer Enable	Timer enable: b0 = Timer is disabled and the counter does not increment. All registers can still be read and written b1 = Timer is enabled and the counter increments normally.

a. When the Auto-increment and Comp enable bits are set, an IRQ is generated every auto-increment register value.

9.5.3 Global Timer Interrupt Status Register

This is a banked register for all cores in the Cortex-A5 MPCore processor.

The event flag is a sticky bit that is automatically set when the Counter Register reaches the Comparator Register value. If the timer interrupt is enabled, Interrupt ID 27 is set as pending in the Interrupt Distributor after the event flag is set. The event flag is cleared when written to 1. Figure 9-15 shows the Global Timer Interrupt Status Register bit assignments.

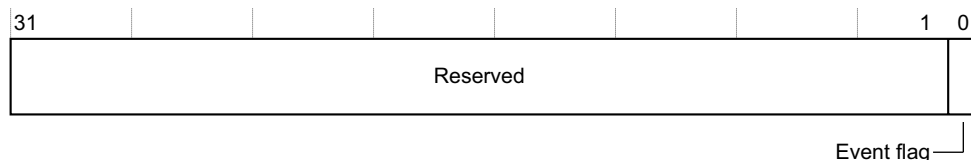


Figure 9-15 Global Timer Interrupt Status Register bit assignments

9.5.4 Comparator Value Registers

There are two 32-bit registers, the lower 32-bit comparator value register and the upper 32-bit comparator value register.

You must access these registers with 32-bit accesses. You cannot use LDM/STM or LDRD/STRD or NEON load or store instructions. There is a Comparator Value Register for each core in the Cortex-A5 MPCore processor.

To ensure that updates to this register do not set the Interrupt Status Register proceed as follows:

1. Clear the Comp Enable bit in the Timer Control Register.
2. Write the lower 32-bit Comparator Value Register.
3. Write the upper 32-bit Comparator Value Register.
4. Set the Comp Enable bit and, if necessary, the IRQ enable bit.

9.5.5 Auto-increment Register

This 32-bit register gives the increment value of the Comparator Register when the Auto-increment bit is set in the Timer Control Register. Each core in the Cortex-A5 MPCore processor has its own Auto-increment Register.

If the Comp Enable and Auto-increment bits are set when the global counter reaches the Comparator Register value, the comparator is incremented by the auto-increment value, so that a new event can be set periodically.

The global counter is not affected and continues incrementing.

Chapter 10

Interrupt Controller

This chapter describes the implementation-defined features of the Cortex-A5 MPCore Interrupt Controller. This chapter does not reproduce information already in the *ARM Generic Interrupt Controller Architecture Specification*. The chapter contains the following sections:

- *About the interrupt controller* on page 10-2
- *Interrupt distributor registers* on page 10-6
- *Processor interface registers* on page 10-18.

10.1 About the interrupt controller

The Interrupt Controller is a single functional unit that is located in a Cortex-A5 MPCore processor. There is one processor interface per core in the processor. The Interrupt Controller is used to collate and arbitrate between a number of different interrupt sources in the system.

The Interrupt Controller is memory-mapped in two regions of the memory area decoded from the base address specified by **PERIPHBASE[31:13]**:

0x1000-0x1FFF Interrupt Distributor registers shared by all the cores in the processor.

0x0100-0x01FF Core specific Interrupt interface registers.

The interrupt sources can be masked and prioritized before being distributed to the appropriate cores in the processor. The Interrupt Controller programmers model also enables interrupts to be generated directly from software.

10.1.1 Interrupt Controller clock frequency

The clock period is configured, during integration, as a multiple of the SCU clock period. This multiple, N, must be greater than or equal to two. Therefore, the minimum pulse width of signals driving external interrupt lines is N Cortex-A5 MPCore processor clock cycles. See *Clocking* on page 2-11 for a description of **PERIPHCLK** and **PERIPHCLKEN**.

The timers and watchdogs use the same clock as the interrupt controller.

10.1.2 Interrupt types and sources

This section describes interrupt types and interrupt distributor sources in:

- *Interrupt types*
- *Interrupt Distributor interrupt sources* on page 10-3.

Interrupt types

The Cortex-A5 MPCore processor has the following interrupt types:

Software Generated Interrupt (SGI)

Generated by writing to the *Software Generated Interrupt Register (ICDSGIR)*.

A maximum of 16 SGIs can be generated for each processor interface.

Private Peripheral Interrupt (PPI)

An interrupt generated by a peripheral that is specific to a single core in the processor.

There are five PPIs for each processor interface. See *Interrupt Distributor interrupt sources* on page 10-3.

Shared Peripheral Interrupt (SPI)

An interrupt generated by a peripheral that the Interrupt Controller can route to any, or all, processor interfaces.

The Interrupt Controller supports a maximum of 224 SPIs. The permitted values are 0, 32, 64, 96, 128, 160, 192, or 224. The number of SPIs available depends on the implemented configuration of the Cortex-A5 MPCore.

Lockable Shared Peripheral Interrupts (LSPI)

There are 31 LSPIs. You can configure and then lock these interrupts against further change using **CFGSDISABLE**. The LSPIs map onto the interrupt IDs used for the first 31 SPIs and are present only if the SPIs are present.

Interrupt Distributor interrupt sources

The Interrupt Distributor centralizes all interrupt sources before dispatching the highest priority ones to each individual core in the Cortex-A5 MPCore processor. Hardware ensures that an interrupt targeted at several cores in the processor can only be taken by one core at a time. See the *ARM Generic Interrupt Controller Architecture Specification*.

All interrupt sources are identified by a unique ID. All interrupt sources have their own configurable priority and list of targeted cores in the processor, that is, a list of cores that the interrupt is sent to when triggered by the interrupt distributor.

This section describes the implementation-defined features of the *Interrupt Configuration Registers (ICDICFR)*. Each bit-pair in the registers describes the interrupt configuration for an interrupt. The options for each pair depend on the interrupt type as follows:

Software Generated Interrupts (SGI)

Each core in the Cortex-A5 MPCore processor has private interrupts, ID0-ID15, that can only be triggered by software. These interrupts are aliased so that there is no requirement for a requesting core to determine its own CPU ID when it deals with SGIs. The priority of an SGI depends on the value set by the receiving core in the banked SGI priority registers, not the priority set by the core sending the request.

The bits are read-only and a bit-pair always reads as b10.

Legacy nIRQ signal, PPI[4]

In legacy IRQ mode, the external **nIRQ[3:0]** signal bypasses the interrupt distributor logic and directly drives interrupt requests into the appropriate core in the processor.

When a core uses the Interrupt Controller, rather than the legacy IRQ signal, by enabling its own processor interface, the **nIRQ[3:0]** signal is treated like other interrupt lines and uses ID31.

The bits are read-only and a bit-pair always reads as b01. Interrupt is active LOW level sensitive.

Watchdog timers, PPI[3]

Each processor has its own watchdog timers that can generate interrupts, using ID30.

The bits are read-only and a bit-pair always reads as b11. Interrupt is rising-edge sensitive.

Private timer, PPI[2]

Each processor has its own private timers that can generate interrupts, using ID29.

The bits are read-only and a bit-pair always reads as b11. Interrupt is rising-edge sensitive.

Legacy nFIQ[3:0] signal, PPI[1]

In legacy FIQ mode, the external **nFIQ[3:0]** signal bypasses the interrupt distributor logic and directly drives interrupt requests into the appropriate core in the processor.

When a core uses the Interrupt Controller, rather than the legacy FIQ signal, by enabling its own processor interface, the **nFIQ[3:0]** signal is treated like other interrupt lines and uses ID28.

The bits are read-only and a bit-pair always reads as b01. Interrupt is active LOW level sensitive.

Global timer, PPI[0]

The global timer can generate interrupts using ID27 which is common across all cores in the processor. Interrupt is rising-edge sensitive.

Shared Peripheral Interrupts (SPI)

SPIs are triggered by events generated on associated interrupt input lines. The Interrupt Controller can support up to 224 interrupt input lines corresponding to the external signal **INT[223:0]**. The interrupt input lines can be configured to be edge sensitive (posedge) or level sensitive (high level). SPIs start at ID32. The Cortex-A5 MPCore processor can be configured with a range of supported SPIs from 0 up to 224. The functionality of all registers associated with non-implemented SPIs is reserved.

The LSB of a bit-pair is read-only and is always b1. You can program the MSB of the bit-pair to alter the triggering sensitivity as follows:

- b01** interrupt is active LOW level sensitive
- b11** interrupt is active HIGH level sensitive.

10.1.3 TrustZone support

The Interrupt Controller enables all implemented interrupts to be individually defined as Secure or Non-secure. A Non-secure access to a register of a Secure interrupt behaves as *Read-As-Zero/Write-Ignore* (RAZ/WI).

Priority formats

The Cortex-A5 MPCore processor implements a five-bit version of the priority format in the *ARM Generic Interrupt Controller Architecture Specification*.

Using CFGSDISABLE

The Interrupt Controller provides the facility to prevent write accesses to critical configuration registers when you assert **CFGSDISABLE**. This signal controls the read and write behavior for the secure control registers in the distributor, processor interfaces, and the *Lockable Shared Peripheral Interrupts* (LSPIs) in the Interrupt Controller.

If you use **CFGSDISABLE**, ARM recommends that you assert **CFGSDISABLE** during the system boot process, after the software has configured the registers. Ideally, the system must only deassert **CFGSDISABLE** if a hard reset occurs.

When **CFGSDISABLE** is HIGH, the Interrupt Controller prevents write accesses to the following registers in the:

Distributor The Distributor Control Register.

Secure interrupts defined by LSPI field in the Interrupt Controller Type Register

- Interrupt Security Registers
- Enable Set Registers
- Enable Clear Registers

- Pending Set Registers
- Pending Clear Registers
- Priority Level Registers
- SPI Target Registers
- Interrupt Configuration Register.

Processor interface

The Processor Interface Control Register, except for the EnableNS bit.

10.2 Interrupt distributor registers

Table 10-1 shows the interrupt distributor registers. Registers not described in Table 10-1 are RAZ/WI. This section does not reproduce information about registers already described in the *ARM Generic Interrupt Controller Architecture Specification*.

The ICDIPR and ICDIPTR registers are byte accessible and word accessible. All other registers in Table 10-1 are word accessible.

Table 10-1 Distributor register summary

Offset from PERIPBASE [31:13]	Name	Type	Reset	Width	Description
0x1000	ICDDCR ^a	RW	0x00000000	32	<i>Distributor Control Register on page 10-7</i>
0x1004	ICDICTR	RO	Configuration dependent	32	<i>Interrupt Controller Type Register on page 10-8</i>
0x1008	ICDIIDR	RO	0x0200143B	32	<i>Distributor Implementer Identification Register on page 10-9</i>
0x100C-0x107C	-	-	-	-	Reserved
0x1080-0x109C	ICDISR	RW ^b	0x00000000	32	Interrupt security registers
0x1100-0x111C	ICDISER	RW	0x00000000 ^c	32	Enable set registers
0x1180-0x119C	ICDICER	RW	0x00000000 ^b	32	Enable clear registers
0x1200-0x121C	ICDISPR	RW	0x00000000	32	Pending set registers
0x1280-0x129C	ICDICPR	RW	0x00000000	32	Pending clear registers
0x1300-0x131C	ICDABR	RO	0x00000000	32	Active status registers
0x1380-0x13FC	-	-	-	-	Reserved
0x1400-0x14FC	ICDIPR	RW	0x00000000	32	Priority level registers
0x17FC	-	-	-	-	Reserved
0x1800-0x18FC	ICDIPTR	RW ^d	0x00000000	32	SPI Target registers
0x18FC	-	-	-	-	Reserved
0x1C00-0x1C3C	ICDICFR	RW	Configuration dependent	32	Interrupt Configuration Registers
0x1D00	ICDPPIS	-	0x00000000	32	<i>Private Peripheral Interrupt Status Register on page 10-10</i>
0x1D04-0x1D1C	ICDSPIS	RO	0x00000000	32	<i>Shared Peripheral Interrupt Status Registers on page 10-11</i>
0x1D80-0x1EFC	-	-	-	-	Reserved
0x1F00	ICDSGIR	WO	-	32	Software Generated Interrupt Register
0x1F04-0x1FCC	-	-	-	-	Reserved
0x1FD0-0x1FEC	Peripheral ID	RO	Configuration dependent	8	<i>Peripheral Identification Registers on page 10-12</i>
0x1FF0-0x1FFC	Component ID	RO	-	8	<i>Component Identification Registers on page 10-15</i>

- a. You cannot modify this register for Secure accesses if **CFGSDISABLE** is set.
- b. You must access this register in Secure state.
- c. The reset value for the registers that contain the SGI and PPI interrupts is implementation-dependent.
- d. The registers that control the SGI and PPI interrupts are read-only and the reset value is configuration-dependent.

The register map is divided into a set of regions specifying registers associated with:

- distributor control and configuration
- interrupt set and clear control
- *Private Peripheral Interrupt (PPI) status*
- *Shared Peripheral Interrupt (SPI) status*
- *Software Generated Interrupt (SGI) control.*
- It also provides a number of peripheral identification registers.

PPIs can be generated only by the internal timer and watchdog peripherals.

———— **Note** —————

The multi-field interrupt control registers, ICDISR, ICDISER, ICDICER, ICDISPR, ICDICPR, and ICDABR, all contain eight 32-bit fields reflecting the number of registers required to include the maximum number of possible interrupt IDs available to the unit. If the processor is configured with fewer interrupts, the number of registers included is reduced accordingly.

10.2.1 Distributor Control Register

The ICDDCR characteristics are:

- Purpose** Controls whether the distributor responds to external stimulus changes that occur on SPIs and PPIs.
- Usage constraints** This register is banked. The register you access depends on the type of access:
 - Non-secure access** Distributor provides access to the enable_ns Register.
 - Secure access** Distributor provides access to the enable_s Register.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 10-1 on page 10-6.

Figure 10-1 shows the ICDDCR bit assignments for Secure accesses.

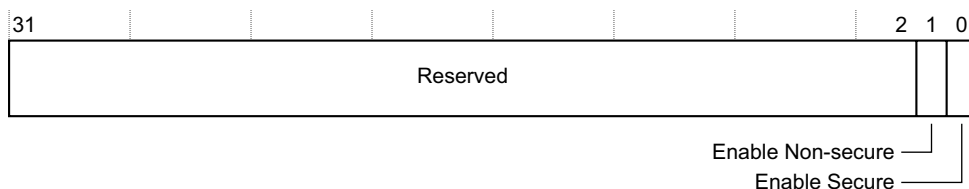


Figure 10-1 ICDDCR bit assignments for Secure accesses

Table 10-2 shows the ICDDCR bit assignments for secure accesses.

Table 10-2 ICDDCR bit assignments for secure accesses

Bits	Name	Description
[31:2]	Reserved	RAZ
[1]	Enable Non-secure	0 = disables all Non-secure interrupt control bits in the distributor from changing state because of any external stimulus change that occurs on the corresponding SPI or PPI signals. 1 = enables the distributor to update register locations for Non-secure interrupts
[0]	Enable Secure	0 = disables all Secure interrupt control bits in the distributor from changing state because of any external stimulus change that occurs on the corresponding SPI or PPI signals. 1 = enables the distributor to update register locations for Secure interrupts.

Figure 10-2 shows the ICDDCR bit assignments for Non-secure accesses.

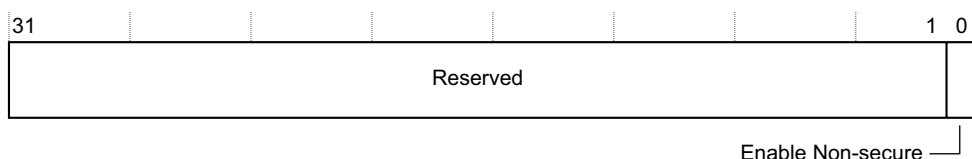


Figure 10-2 ICDDCR bit assignments for Non-secure accesses

Table 10-3 shows the ICDDCR bit assignments for Non-secure accesses.

Table 10-3 ICDDCR bit assignments for Non-secure accesses

Bits	Name	Description
[31:1]	Reserved	RAZ
[0]	Enable Non-secure	0 = disables all Non-secure interrupt control bits in the distributor from changing state because of any external stimulus change that occurs on the corresponding SPI or PPI signals. 1 = enables the distributor to update register locations for Non-secure interrupts

10.2.2 Interrupt Controller Type Register

The ICDDICR characteristics are:

- Purpose** Provides information about the configuration of the Interrupt Controller.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 10-1 on page 10-6.

Figure 10-3 shows the ICDDICR bit assignments.

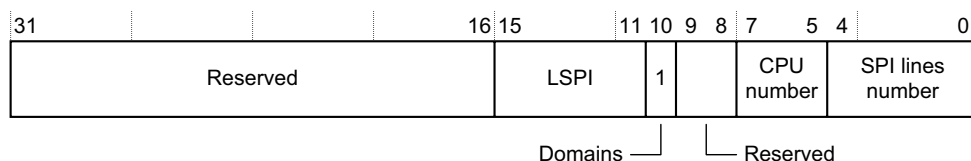


Figure 10-3 ICDDICR bit assignments

Table 10-4 shows the ICDICTR bit assignments.

Table 10-4 ICDICTR bit assignments

Bits	Name	Description
[31:16]	Reserved	RAZ
[15:11]	LSPI	Returns the number of <i>Lockable Shared Peripheral Interrupts</i> (LSPIs) that the controller contains. The encoding is: b11111 = 31 LSPIs, which are the interrupts of IDs 32-62. When CFGSDISABLE is HIGH then the interrupt controller prevents writes to any register locations that control the operating state of an LSPI.
[10]	Domains	Returns the number of security domains that the controller contains: 1 = the controller contains two security domains. This bit always returns a value of one.
[9:8]	Reserved	SBZ
[7:5]	CPU number	The encoding is: b000 = the design contains one processor. b001 = the design contains two processors. b010 = the design contains three processors. b011 = the design contains four processors. b1xx = Reserved for future extensions.
[4:0]	SPI lines number	The encoding is: b00000 = the distributor provides 32 interrupts ^a , no external interrupt lines. b00001 = the distributor provides 64 interrupts, 32 external interrupt lines. b00010 = the distributor provides 96 interrupts, 64 external interrupt lines. b00011 = the distributor provides 128 interrupts, 96 external interrupt lines. b00100 = the distributor provides 160 interrupts, 128 external interrupt lines. b00101 = the distributor provides 192 interrupts, 160 external interrupt lines. b00110 = the distributor provides 224 interrupts, 192 external interrupt lines. b00111 = the distributor provides 256 interrupts, 224 external interrupt lines. All other values are Reserved for future extensions.

a. The distributor always uses interrupts of IDs 0 to 31 to control any SGIs and PPIs that the Interrupt Controller might contain.

10.2.3 Distributor Implementer Identification Register

The ICDIIDR characteristics are:

Purpose	Provides information about the implementer and the revision of the controller.
Usage constraints	There are no usage constraints.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 10-1 on page 10-6.

Figure 10-4 on page 10-10 shows the ICDIIDR bit assignments.

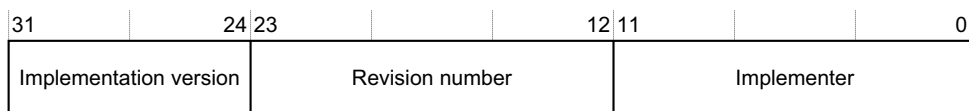


Figure 10-4 ICDIIDR bit assignments

Table 10-5 shows the ICDIIDR bit assignments.

Table 10-5 ICDIIDR bit assignments

Bits	Name	Description
[31:24]	Implementation version	Gives implementation version number.
[23:12]	Revision number	Returns the revision number of the controller.
[11:0]	Implementer	Implementer number.

10.2.4 Private Peripheral Interrupt Status Register

The ICDPPIS Register characteristics are:

- Purpose** Enables a core in the Cortex-A5 MPCore processor to access the status of the private inputs on the distributor.
- Usage constraints** A processor can only read the status of its own **PPI** and therefore cannot read the status of **PPI** for other processors.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 10-1 on page 10-6.

Figure 10-5 shows the ICDPPIS Register bit assignments.

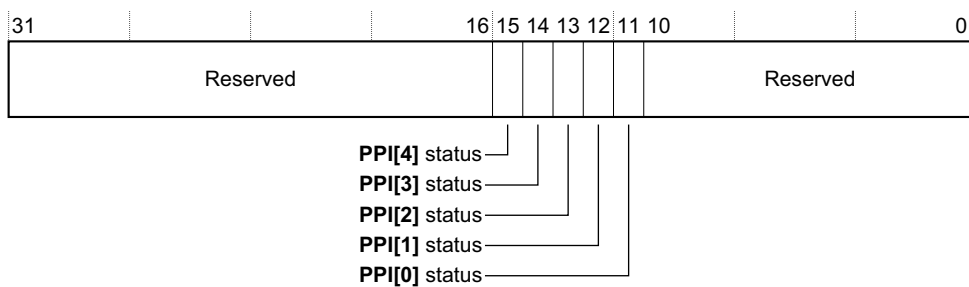


Figure 10-5 ICDPPIS Register bit assignments

Table 10-6 shows the ICDPPIS Register bit assignments.

Table 10-6 ICDPPIS Register bit assignments

Bits	Name	Description
[31:16]	Reserved	SBZ
[15:11]	PPI status	<p>Returns the status of the PPI[4:0] inputs on the distributor:</p> <ul style="list-style-type: none"> • PPI[4] is nIRQ • PPI[3] is the watchdog • PPI[2] is the private timer • PPI[1] is nFIQ • PPI[0] is the global timer. <p>PPI[1] and PPI[4] are active LOW PPI[0], PPI[2], and PPI[3] are active HIGH.</p> <p style="text-align: center;">Note</p> <p>These bits return the actual status of the internal PPI[4:0] signals. The ICDISPR and ICDICPR Registers also can provide the PPI[4:0] status but because you can write to these registers, they might not contain the actual status of the PPI[4:0] signals.</p>
[10:0]	Reserved	SBZ

10.2.5 Shared Peripheral Interrupt Status Registers

The IC DSPIS Register characteristics are:

- Purpose** Enables a Cortex-A5 processor to access the status of **INT[223:0]** inputs on the distributor.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 10-1 on page 10-6.

Figure 10-6 shows the IC DSPIS Register bit assignments.

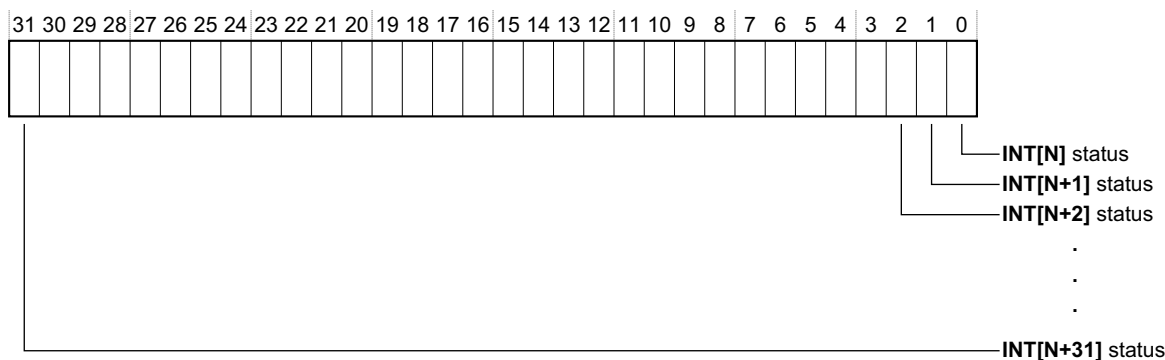


Figure 10-6 IC DSPIS Register bit assignments

Table 10-7 shows the ICDSPIS Register bit assignments.

Table 10-7 ICDSPIS Register bit assignments

Bits	Name	Description
[31:0]	INT[N+31:N]	<p>Returns the status of the INT[223:0] inputs on the distributor:</p> <p>Bit [X] = 0 INT[X] is LOW</p> <p>Bit [X] = 1 INT[X] is HIGH.</p> <p>———— Note —————</p> <p>The INT that X refers to depends on its bit position and the base address offset of the ICDSPIS Register as Table 10-7 shows.</p> <p>These bits return the actual status of the INT signals. The pending_set and pending_clr Registers can also provide the INT status but because you can write to these registers then they might not contain the actual status of the INT signals.</p>

Figure 10-7 shows the address map that the distributor provides for the SPIs.

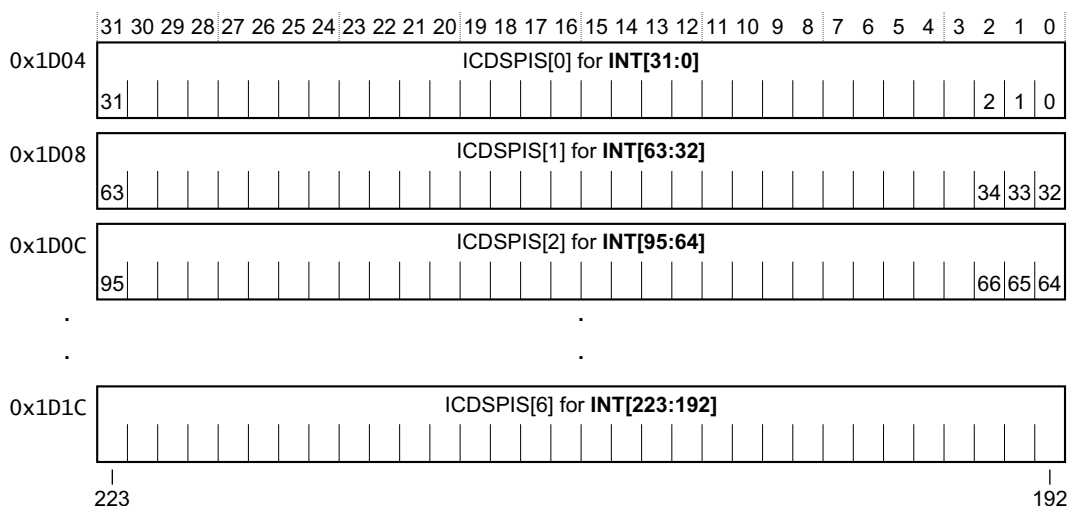


Figure 10-7 ICDSPIS Register address map

In Figure 10-7 the values for the SPIs are read-only. The distributor provides a register at address offset 0x1D04. This register contains the values for the SPIs for the corresponding processor interface. The distributor provides up to seven registers. If you configure the Interrupt Controller to use fewer than 224 SPIs, it reduces the number of registers accordingly. For locations where interrupts are not implemented then the distributor:

- ignores writes to the corresponding bits
- returns 0 when it reads from these bits.

10.2.6 Peripheral Identification Registers

The Peripheral ID Registers provide information about the configuration of the peripheral. Each register provides eight bits of data but, because some fields span across two adjacent Peripheral ID registers, the following sections describe these registers:

- *Peripheral ID [3:0] Register group* on page 10-13
- *Peripheral ID [7:4] Register group* on page 10-14.

Peripheral ID [3:0] Register group

Figure 10-8 shows the Peripheral ID [3:0] Register group bit assignments.

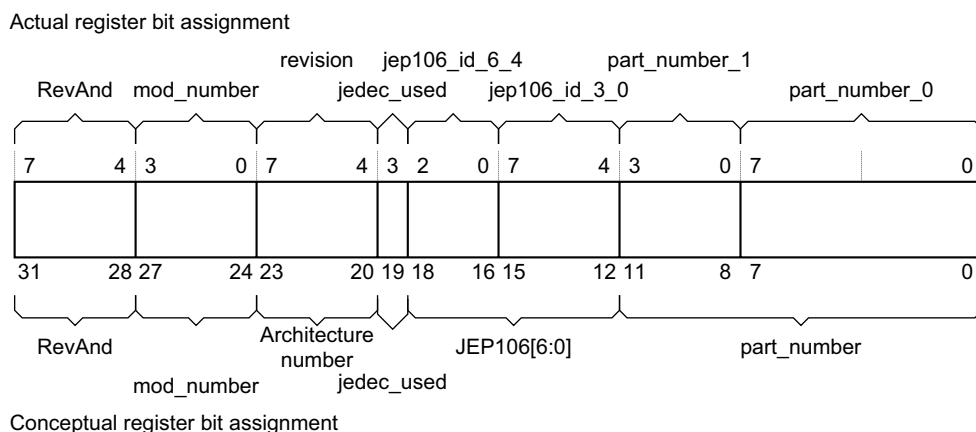


Figure 10-8 Peripheral ID [3:0] Register bit assignments

Table 10-8 shows the Peripheral ID [3:0] Register group bit assignments.

Table 10-8 Peripheral ID [3:0] Register bit assignments

Bits	Name	Description
[31:28]	RevAnd	These bits read as 0x0.
[27:24]	mod_number	Identifies data that is relevant to the ARM partner.
[23:20]	Architecture number	Identifies the major revision number, <i>rn</i> , of the peripheral. The revision number starts from 0 and is revision-dependent.
[19]	jedec_used	Identifies if the Interrupt Controller uses the JEP106 manufacturer's identity code.
[18:12]	JEP106[6:0]	Identifies the designer. This is set to b0111011, to indicate that ARM designed the peripheral.
[11:0]	part_number	Identifies the peripheral. This is set to 0x390.

The following subsections describe the Peripheral ID [3:0] registers:

- *Peripheral ID 0 Register*
- *Peripheral ID 1 Register* on page 10-14
- *Peripheral ID 2 Register* on page 10-14
- *Peripheral ID 3 Register* on page 10-14.

Peripheral ID 0 Register

The Peripheral ID 0 Register is hard-coded and the fields in the register control the reset value. Table 10-9 shows the Peripheral ID 0 Register bit assignments.

Table 10-9 Peripheral ID 0 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved
[7:0]	part_number_0	-

Peripheral ID 1 Register

The Peripheral ID 1 Register is hard-coded and the fields in the register control the reset value. Table 10-10 shows the Peripheral ID 1 Register bit assignments.

Table 10-10 Peripheral ID 1 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved.
[7:4]	jep106_id_3_0	JEP106 identity code [3:0]. See the <i>JEP106, Standard Manufacturer's Identification Code</i> .
[3:0]	part_number_1	-

Peripheral ID 2 Register

The Peripheral ID 2 Register is hard-coded and the fields in the register control the reset value. Table 10-11 shows the Peripheral ID 2 Register bit assignments.

Table 10-11 Peripheral ID 2 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved.
[7:4]	Architecture number	The architecture number of the Interrupt Controller.
[3]	jedec_used	This indicates that the IC uses a manufacturer's identity code that was allocated by JEDEC according to JEP106.
[2:0]	jep106_id_6_4	JEP106 identity code [6:4]. See the <i>JEP106, Standard Manufacturer's Identification Code</i> .

Peripheral ID 3 Register

The Peripheral ID 3 Register is hard-coded and the fields in the register control the reset value. Table 10-12 shows the Peripheral ID 3 Register bit assignments.

Table 10-12 Peripheral ID 3 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved.
[7:4]	RevAnd	-
[3:0]	mod_number	The customer can update this field if they modify the RTL of the Interrupt Controller.

Peripheral ID [7:4] Register group

Figure 10-9 on page 10-15 shows the Peripheral ID [7:4] Register group bit assignments.

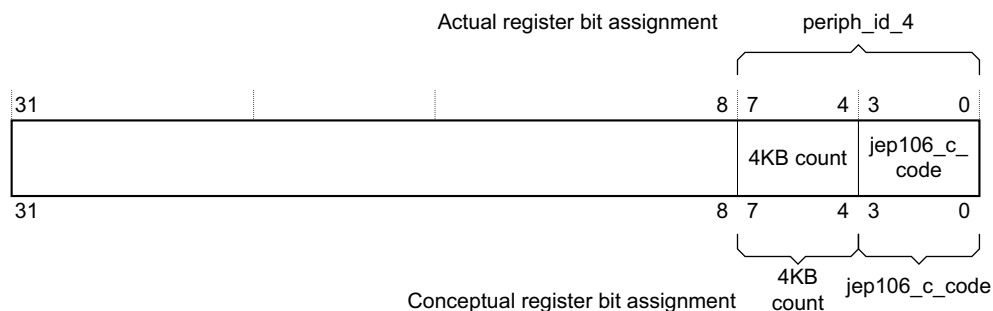


Figure 10-9 Peripheral ID [7:4] Register bit assignments

Table 10-13 shows the Peripheral ID [7:4] Register group bit assignments.

Table 10-13 Peripheral ID [7:4] Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved.
[7:4]	4KB count	Identifies the address space that the registers occupy.
[3:0]	jep106_c_code	Identifies the JEP106 continuation code.

The following subsection describes the Peripheral ID [7:4] registers:

- *Peripheral ID 4 Register.*

Peripheral ID 4 Register

The Peripheral ID 4 Register is hard-coded and the fields in the register control the reset value. Table 10-14 shows the Peripheral ID 4 Register bit assignments.

Table 10-14 Peripheral ID 4 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved.
[7:4]	4KB count	The number of 4KB address blocks you require, to access the registers, expressed in powers of 2.
[3:0]	jep106_c_code	The JEP106 continuation code value represents how many 0x7F continuation characters occur in the manufacturer's identity code. See <i>JEP106, Standard Manufacturer's Identification Code</i> .

10.2.7 Component Identification Registers

The Component ID [3:0] Registers are four eight-bit wide registers, that can conceptually be treated as a single register that holds a 32-bit Component ID value. You can use the register for automatic BIOS configuration. The Component ID Register is set to 0xB105F00D.

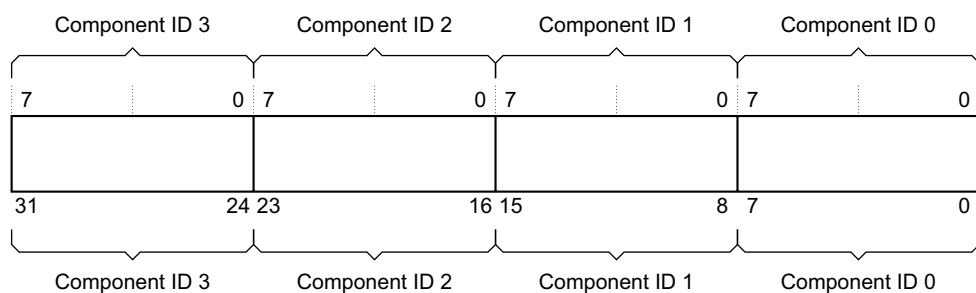
Table 10-15 shows the Component ID Register bit assignments.

Table 10-15 Component ID Register bit assignments

Bits	Reset value	Register	Bits	Description
-	-	Component ID 3	[31:8]	Reserved
[31:24]	0xB1	Component ID 3	[7:0]	-
-	-	Component ID 2	[31:8]	Reserved
[23:16]	0x05	Component ID 2	[7:0]	-
-	-	Component ID 1	[31:8]	Reserved
[15:8]	0xF0	Component ID 1	[7:0]	-
-	-	Component ID 0	[31:8]	Reserved
[7:0]	0x0D	Component ID 0	[7:0]	-

Figure 10-10 shows the Component ID Register bit assignments.

Actual register bit assignment



Conceptual register bit assignment

Figure 10-10 Component ID Register bit assignments

The following subsections describe the Component ID Registers:

- *Component Identification Register 0*
- *Component Identification Register 1* on page 10-17
- *Component Identification Register 2* on page 10-17
- *Component Identification Register 3* on page 10-17.

Component Identification Register 0

The Component ID 0 Register is hard-coded and the fields in the register control the reset value. Table 10-16 shows the Component ID 0 Register bit assignments.

Table 10-16 Component ID 0 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved
[7:0]	Component ID 0	-

Component Identification Register 1

The Component ID 1 Register is hard-coded and the fields in the register control the reset value. Table 10-17 shows the Component ID 1 Register bit assignments.

Table 10-17 Component ID 1 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved
[7:0]	Component ID 1	-

Component Identification Register 2

The Component ID 2 Register is hard-coded and the fields in the register control the reset value. Table 10-18 shows the Component ID 2 Register bit assignments.

Table 10-18 Component ID 2 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved
[7:0]	Component ID 2	-

Component Identification Register 3

The Component ID 3 Register is hard-coded and the fields in the register control the reset value. Table 10-19 shows the Component ID 3 Register bit assignments.

Table 10-19 Component ID 3 Register bit assignments

Bits	Name	Description
[31:8]	-	Reserved
[7:0]	Component ID 3	-

10.3 Processor interface registers

Table 10-20 shows the processor interface registers. These registers control the operating state and behavior of the processor interface. This section does not reproduce information about registers already described in the *ARM Generic Interrupt Controller Architecture Specification*. All the registers in Table 10-20 are word accessible only. Byte accesses made to these registers cause Unpredictable results.

Table 10-20 Cortex-A5 MPCore processor interface register summary

Base	Name	Type	Reset	Width	Description
0x100	ICPICR	RW	0x0	32	Processor Interface Control Register
0x104	ICCIPMR	RW	0x0	32	Priority Mask Register
0x108	ICCBPR	RW	0x2	32	Binary Point Register
0x10C	ICCIAR	RO	0x3FF	32	Interrupt Acknowledge Register
0x110	ICCEOIR	WO	-	32	End Of Interrupt Register
0x114	ICCRPR	RO	0xFF	32	Running Priority Register
0x118	ICCHPIR	RO	0x3FF	32	Highest Pending Interrupt Register
0x11C ^a	ICCABPR	RW	0x3	32	Aliased Non-secure Binary Point Register
0x1FC	ICCIIDR	RO	0x3901143B	32	<i>Processor Interface Implementer Identification Register</i>

a. This address location is only accessible when the core in the Cortex-A5 MPCore processor performs a Secure access.

10.3.1 Processor Interface Implementer Identification Register

The ICCIIDR characteristics are:

Purpose Provides information about the implementer and the revision of the controller.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 10-20.

Figure 10-11 shows the ICCIIDR bit assignments.

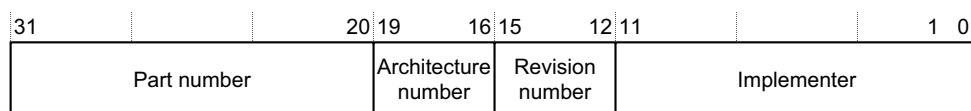


Figure 10-11 ICCIIDR bit assignments

Table 10-21 shows the ICCIHDR bit assignments.

Table 10-21 ICCIHDR bit assignments

Bits	Name	Description
[31:20]	Part number	Identifies the peripheral.
[19:16]	Architecture version	Identifies the architecture version.
[15:12]	Revision number	Returns the revision number of the Interrupt Controller. The implementer defines the format of this field.
[11:0]	Implementer	Returns the JEP106 code of the company that implemented the processor interface RTL. It uses the following construct: [11:8] the JEP106 continuation code of the implementer [7] 0 [6:0] the JEP106 code [6:0] of the implementer.

Chapter 11

Debug

This chapter describes the processor debug unit. This feature assists the development of application software, operating systems, and hardware. This chapter contains the following sections:

- *About debug* on page 11-2
- *Debugging modes* on page 11-4
- *Debug interface* on page 11-6
- *Debug register summary* on page 11-8
- *Debug register descriptions* on page 11-11
- *Management registers* on page 11-29
- *Integration test registers* on page 11-37
- *External debug interface* on page 11-41
- *Miscellaneous debug signals* on page 11-42.

11.1 About debug

The Cortex-A5 MPCore processor implements the ARMv7 debug architecture, including support for the TrustZone security extensions and CoreSight. The processor forms one component of a debug system. Figure 11-1 shows a typical system.

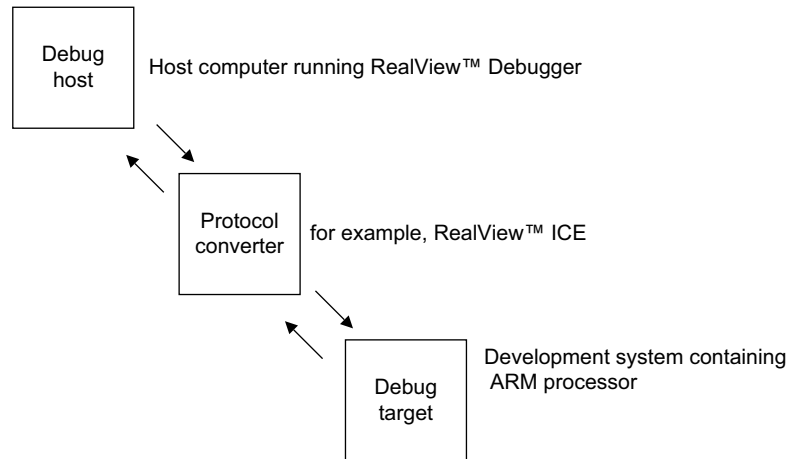


Figure 11-1 Typical debug system

This typical system has a:

- debug host
- protocol converter
- debug target.

11.1.1 Debug host

The debug host is a computer, for example a personal computer, running a software debugger such as RealView™ Debugger. The debug host enables you to issue high-level commands such as setting a breakpoint at a certain location, or examining the contents of a memory address.

11.1.2 Protocol converter

The debug host sends messages to the debug target using an interface such as Ethernet. However, the debug target typically implements a different interface protocol. A device such as RealView ICE is required to convert between the two protocols.

11.1.3 Debug target

The debug target is the lowest level of the system. An example of a debug target is a development system with a test chip or a silicon part with a processor. The debug target implements system support for the protocol converter to access the Cortex-A5 MPCore Debug Unit using the APB slave port.

11.1.4 About the debug unit

The processor debug unit assists in debugging software running on the processor. You can use the processor debug unit, in combination with a software debugger program, to debug:

- application software
- operating systems
- hardware systems based on an ARM processor.

The debug unit enables you to:

- stop program execution using breakpoints and a watchpoint
- examine and alter processor and coprocessor state
- examine and alter memory and input/output peripheral state
- restart the processor core and resume execution of the application.

You can debug software running on the processor in the following ways:

- Halting debug-mode debugging
- Monitor debug-mode debugging
- trace debugging, see *ETM interface* on page 2-9.

11.1.5 Debug configuration

The Cortex-A5 MPCore processor expands the debug capabilities to enable multiple threads to be debugged. The processor exports a *Cross Trigger Interface (CTI)*, which can be connected to a CoreSight *Cross Trigger Matrix (CTM)*. All the cores in the processor can be controlled independently through a common Debug APB interface, which is exposed at the processor boundary. Figure 11-2 shows a typical Cortex-A5 MPCore debug configuration.

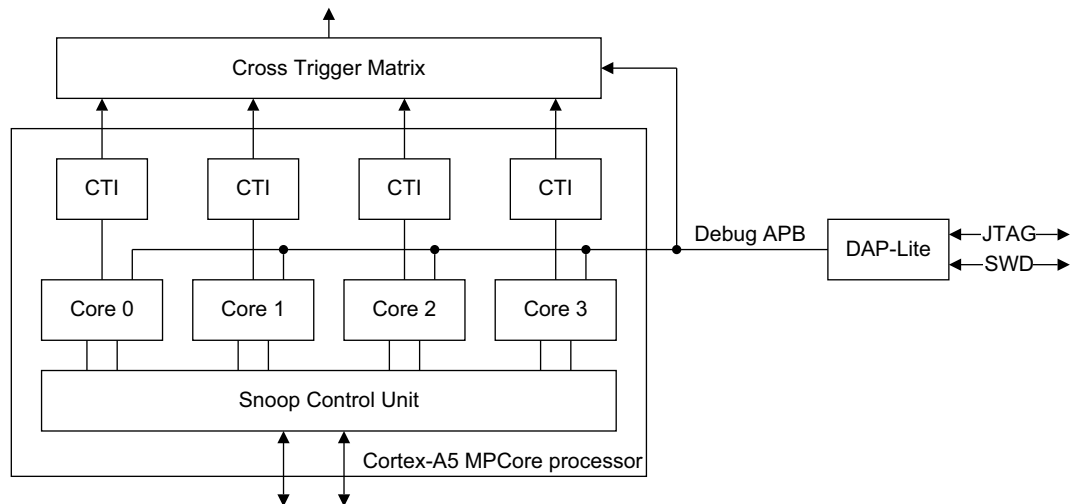


Figure 11-2 Cortex-A5 MPCore debug configuration including cross trigger support

11.2 Debugging modes

The Cortex-A5 MPCore processor implements the following types of debug:

Invasive debug

Invasive debug is defined as a debug process where you can control and observe the processor. Most debug features in this chapter are considered invasive debug because they enable you to halt the processor and modify its state.

DBGEN and **SPIDEN** control invasive debug permissions.

Non-invasive debug

Non-invasive debug is defined as a debug process where you can observe the processor but not control it. The *Embedded Trace Macrocell* (ETM) interface and the performance monitor registers are features of non-invasive debug.

See *ETM interface* on page 2-9 for information on the ETM interface.

See *System performance monitor registers* on page 4-7 for information on performance monitor registers.

NIDEN and **SPNIDEN** control non-invasive debug permissions. Non-invasive debug is always permitted when invasive debug is permitted.

The following sections describe:

- *Halting debug-mode debugging*
- *Monitor debug-mode debugging*
- *Performance monitor and events* on page 11-5
- *Security extensions and debugging* on page 11-5.

11.2.1 Halting debug-mode debugging

When the processor debug unit is in Halting debug-mode, the processor halts when a debug event, such as a breakpoint, occurs. When the processor is halted, an external debugger can examine and modify the processor state using the APB slave port. This debug mode is invasive to program execution.

11.2.2 Monitor debug-mode debugging

When the processor debug unit is in Monitor debug-mode and a debug event occurs, the processor takes a debug exception instead of halting. A special piece of software, a monitor target, can then take control to examine or alter the processor state. Monitor debug-mode is essential in real-time systems where the processor cannot be halted to collect debug information. Examples of these systems are engine controllers and servo mechanisms in hard drive controllers that cannot stop the code without physically damaging the components.

When execution of a monitor target starts, the state of the processor is preserved in the same way as all ARM exceptions. The monitor target then communicates with the debugger to access processor and coprocessor state, and to access memory contents and input/output peripherals. Monitor debug-mode requires a debug monitor program to interface between the debug hardware and the software debugger.

Debug can also be carried out using a trace-based approach with output from the external ETM interface, described in *ETM interface* on page 2-9. The Cortex-A5 MPCore processor enables access to the internal debug functionality and registers as follows:

- through a memory-mapped area on the external AMBA APBv3 slave port
- by using CP14 system coprocessor operations from software running on the processor.

11.2.3 Performance monitor and events

The Cortex-A5 MPCore processor includes logic to detect various events that can occur during runtime. These events provide useful information about the behavior of the processor that you can use when debugging or profiling code.

The events are made visible on an output bus, **EVNTBUS_n**, which forms part of the ETM interface for each core *n* in the Cortex-A5 MPCore processor, and can also be counted using registers in the *Performance Monitoring Unit* (PMU). The Cortex-A5 MPCore processor enables access to the PMU registers as follows:

- through a memory-mapped area on the external AMBA APBv3 slave port
- by using CP15 system coprocessor operations from software running on the processor.

Each core in the Cortex-A5 MPCore processor supports two general purpose counters which can be tied to any of the events, and a separate dedicated cycle counter.

See *Event Type Select Register* on page 12-12 for more information on performance events.

11.2.4 Security extensions and debugging

To prevent access to secure system software or data while still permitting Non-secure state and optionally secure User mode to be debugged, you can set debug to one of three levels:

- Non-secure state only
- Non-secure state and Secure User mode only. In this configuration, only Monitor debug-mode debugging is supported in secure User mode.
- any Secure or Non-secure state.

The **SPIDEN** and **SPNIDEN** signals, and the two bits, **SUIDEN** and **SUNIDEN**, in the Secure Debug Enable Register in the CP15 system coprocessor control the secure debug permissions.

See *Secure Debug Enable Register* on page 4-48, *Authentication signals* on page 11-43, and *Changing the authentication signals* on page 11-43 for more information.

11.3 Debug interface

The Cortex-A5 MPCore processor implements the ARMv7 debug architecture and debug events as described in the *ARM Architecture Reference Manual*.

11.3.1 Breakpoints and watchpoints

Each core in the Cortex-A5 MPCore processor supports three hardware breakpoints and two watchpoints. Two of the breakpoints match only to virtual address, the third matches against either virtual address or context ID. Similarly, either of the first two breakpoints can be linked to the third breakpoint to enable an instruction to be trapped in a given process context. The following apply to watchpoints:

- A watchpoint event is always synchronous. It has the same behavior as a synchronous data abort.
- If a translation or access permissions fault occurs on a watchpointed access, the synchronous abort takes priority over the watchpoint.
- If the abort is asynchronous and cannot be associated with the access, the exception that is taken is unpredictable.
- Cache maintenance operations do not generate watchpoint events.

11.3.2 Asynchronous aborts

The Cortex-A5 MPCore processor ensures that all possible outstanding asynchronous data aborts have been recognized prior to entry to debug state.

11.3.3 Processor interfaces

The Cortex-A5 MPCore processor has the following interfaces to the debug, performance monitor, and trace registers:

Debug registers

This interface is Baseline CP14, Extended CP14, and memory-mapped. You can access the debug register map for each core in the processor using the APB slave port. See *External debug interface* on page A-14.

Performance monitor

This interface is CP15 based and memory-mapped. You can access the performance monitor memory map for each core in the processor using the APB slave port. See Chapter 12 *Performance Monitoring Unit* for information on performance monitor registers.

Trace registers

This interface is memory-mapped. The Cortex-A5 MPCore processor implements the ETM architecture. See *ETM interface* on page 2-9.

11.3.4 Effects of resets on debug registers

nCPURESET

The **nCPURESET** signal is the main processor reset that initializes the Cortex-A5 MPCore processor logic. It has no effect on the debug logic.

nDBGRESET

The **nDBGRESET** signal is the debug logic reset signal. A power-on reset asserts **nCPURESET** and **nDBGRESET**.

On a debug reset:

- The debug state is unchanged, that is **DBGSCR.HALTED** is unchanged.
- The processor removes the pending halting debug events **DBGDRCR.HaltReq**.

11.4 Debug register summary

You can access the debug registers for each core in the Cortex-A5 MPCore processor:

- through the CP14 interface. The debug registers are mapped to coprocessor instructions run on the appropriate core.
- through a 4KB memory-mapped region on the APB interface when **PADDRDBG[14:13]** is set to access the required core in the processor, **PADDRDBG[12]** is b0 and using the relevant offset, with the following exceptions:
 - DBGRAR
 - DBGSAR
 - DBGDSCRint
 - DBGDTRTXint
 - DBGDTRRXint.

External views of DBGDSCR , DBGDTRRX, and DBGDTRTX are accessible through memory-mapped APB access.

Table 11-1 shows the debug interface registers including the CP14 instruction encoding and the address offset in the 4KB memory mapped region on the APB interface.

Table 11-1 Debug interface registers

Register number	Offset	CP14 instruction	Access	Name	Description
0	0x000	0 c0 c0 0	RO	DBGDIDR ^a	<i>Debug Identification Register on page 11-11</i> ^b
128	-	0 c1 c0 0	RO	DBGDRAR ^a	-
256	-	0 c2 c0 0	RO	DBGDSAR ^a	-
1	-	0 c0 c1 0	RO	DBGDSCRint ^{ab}	<i>Debug Status and Control Register on page 11-12</i> ^a
2-4	-	-	-	Reserved	-
5	-	0 c0 c5 0	RW	DBGDTRTXint (writes) and DBGDTRRXint (reads) ^a	-
6	0x018	0 c0 c6 0	RW	DBGWFAR	Use of DBGWFAR is deprecated in the ARMv7 architecture, because watchpoints are synchronous
7	0x01C	0 c0 c7 0	RW	DBGVCR	-
8	-	-	-	Reserved	-
9	0x024	0 c0 c9 0	RAZ/WI	DBGECR	<i>Event Catch Register on page 11-19</i>
10	0x028	0 c0 c10 0	RAZ/WI	DBGDSCCR	<i>Debug State Cache Control Register on page 11-19</i>
11	0x02C	0 c0 c11 0	RAZ/WI	DBGDSMCR	<i>Debug State MMU Control Register on page 11-19</i>
12-31	-	-	-	Reserved	-
32	0x080	0 c0 c0 2	RW	DBGDTRRXext	-

Table 11-1 Debug interface registers (continued)

Register number	Offset	CP14 instruction	Access	Name	Description
33	0x084	-	WO	DBGITR	-
33	0x084	-	RO	DBGPCSR	<i>Program Counter Sampling Register on page 11-18</i>
34	0x088	0 c0 c2 2	RW	DBGDSCRext	<i>Debug Status and Control Register on page 11-12</i>
35	0x08C	0 c0 c3 2	RW	DBGDTRTText	-
36	0x090	0 c0 c4 2	WO	DBGDRCR	<i>Debug Run Control Register on page 11-19</i>
37-39	-	-	-	Reserved	-
40	0x0A0	-	RO	DBGPCSR	<i>Program Counter Sampling Register on page 11-18</i>
41	0x0A4	-	RO	DBGCIDSr	-
42-63	-	-	-	Reserved	-
64-79	0x100-0x13C	0 c0 c0-2 4	RW	DBGBVRn	<i>Breakpoint Value Registers on page 11-20</i>
80-95	0x140-0x17C	0 c0 c0-2 5	RW	DBGBCRn	<i>Breakpoint Control Registers on page 11-21</i>
96-111	0x180-0x1BC	0 c0 c0-1 6	RW	DBGWVRn	<i>Watchpoint Value Register on page 11-24</i>
129-255, 257-191	0x1C0-0x1FC	0 c0 c0-1 7	RW	DBGWCRn	<i>Watchpoint Control Register on page 11-25</i>
128-191	-	-	-	Reserved	-
192	0x300	0 c1 c0 4	WO/WI	DBGOSLAR	<i>Operating System Lock and Save/Restore Registers on page 11-19</i>
193	0x304	0 c1 c1 4	RO/RAZ	DBGOSLSR	
194	0x308	0 c1 c2 4	RAZ/WI	DBGOSSRR	
195	-	-	-	Reserved	-
196	0x310	0 c1 c4 4	RW	DBGPRCR	<i>Device Power-down and Reset Control Register on page 11-26</i>
197	0x314	0 c1 c5 4	RO	DBGPRSR	<i>Device Power-down and Reset Status Register on page 11-27</i>
198-831	-	-	-	Reserved	-
832-895	0xD00-0xDFC	-c	RO	-	<i>Processor ID Registers on page 11-29</i>
896-957	-	-	-	Reserved	-
958	0xEF8	-	WO	DBGITMISCOUT	<i>DBGITMISCOUT Register (Miscellaneous Outputs) on page 11-38</i>
959	0xEFC	-	RO	DBGITMISCIN	<i>DBGITMISCIN Register (Miscellaneous Inputs) on page 11-39</i>
960	0xF00	-	RAZ/WI	DBGITCTRL	<i>Integration Mode Control Register on page 11-40</i>
961-999	0xF04-0xF9C	-	-	Reserved	-

Table 11-1 Debug interface registers (continued)

Register number	Offset	CP14 instruction	Access	Name	Description
1000	0xFA0	0 c7 c8 6	RW	DBGCLAIMSET	<i>Claim Tag Set Register</i> on page 11-30
1001	0xFA4	0 c7 c9 6	RW	DBGCLAIMCLR	<i>Claim Tag Clear Register</i> on page 11-31
1002-1003	-	-	-	Reserved	-
1004	0xFB0	-	WO	DBGLAR	<i>Lock Access Register</i> on page 11-31
1005	0xFB4	-	RO	DBGLSR	<i>Lock Status Register</i> on page 11-32
1006	0xFB8	0 c7 c14 6	RO	DBGAUTHSTATUS	<i>Authentication Status Register</i> on page 11-33
1007-1009	-	-	-	Reserved	-
1010	0xFC8	0 c7 c2 7	RO	DBGDEVID	-
1011	0xFCC	-	RO	DBGDEVTYPE	<i>Device Type Register</i> on page 11-34
1012-1016	0xFD0-0xFEC	-	RO	PERIPHERALID	<i>Identification Registers</i> on page 11-34
1017-1019	-	-	-	Reserved	-
1020-1023	0xFF0-0xFFC	-	RO	COMPONENTID	<i>Identification Registers</i> on page 11-34

- a. Baseline CP14 interface. This register also has an external view through the memory-mapped interface and the CP14 interface. See *Debug Status and Control Register* on page 11-12.
- b. Accessible in User mode if bit [12] of the DBGDSCR is clear. Also accessible in privileged modes.
- c. Accessed through CP15 interface.

11.5 Debug register descriptions

This section describes the debug registers.

11.5.1 Debug Identification Register

The DBGDIDR characteristics are:

- Purpose** Identifies the debug architecture version and specifies the number of debug resources that the Cortex-A5 MPCore processor implements.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-1 on page 11-8.

———— **Note** —————

All Baseline CP14 registers are accessible in User mode only if DBGDSCR.UCCDDis=0.

Figure 11-3 shows the DBGDIDR bit assignments.

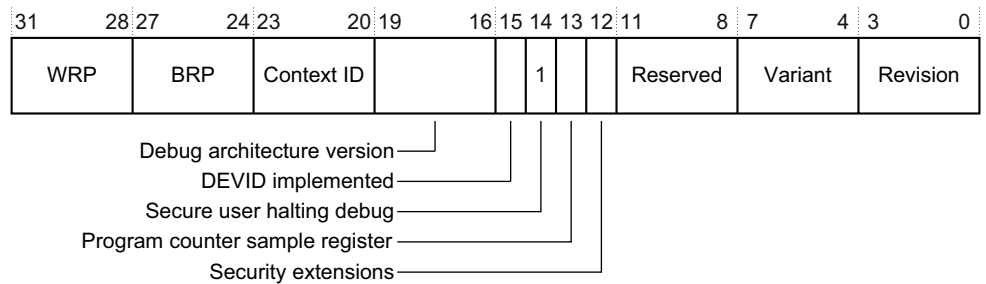


Figure 11-3 DBGDIDR bit assignments

Table 11-2 shows the DBGDIDR bit assignments.

Table 11-2 DBGDIDR bit assignments

Bits	Name	Description
[31:28]	WRP	Number of Watchpoint Register Pairs: For the Cortex-A5 MPCore processor, this field reads as b0001 to indicate two WRPs are implemented.
[27:24]	BRP	Number of Breakpoint Register Pairs: For the Cortex-A5 MPCore processor, this field reads as b0010 to indicate three BRPs are implemented.
[23:20]	Context	Number of Breakpoint Register Pairs with context ID comparison capability: For the Cortex-A5 MPCore processor, this field reads as b0000 to indicate one BRP has context ID capability.
[19:16]	Debug architecture version	Debug architecture version: b0011 = ARMv7 Debug with Extended CP14 interface implemented.
[15]	DEVID implemented	For the Cortex-A5 MPCore processor, this field reads as b1 to indicate that the Debug Device ID Register, DBGDEVID is implemented.

Table 11-2 DBGDIDR bit assignments (continued)

Bits	Name	Description
[14]	Secure User halting debug not supported	For the Cortex-A5 MPCore processor, this field reads as b1 to indicate that Secure User halting debug is not supported.
[13]	Program Counter Sampling Register	Program Counter Sample Register, DBGPCSR. For the Cortex-A5 MPCore processor, this field reads as b1 to indicate that DBGPCSR is implemented as debug register 33.
[12]	Security extensions	Security extensions bit: For the Cortex-A5 MPCore processor, this field reads as b1 to indicate that the debug security extensions are implemented.
[11:8]	Reserved	RAZ.
[7:4]	Variant	Implementation-defined variant number. This number is incremented on functional changes. The value matches bits [23:20] of the ID Code Register in CP15 c0.
[3:0]	Revision	Implementation-defined revision number. This number is incremented on bug fixes. The value matches bits [3:0] of the ID Code Register in CP15 c0.

The values of the following fields of the DBGDIDR agree with the values in CP15 c0, Main ID Register:

- DBGDIDR is the same as CP15 c0 bits
- DBGDIDR[7:4] is the same as CP15 c0 bits [23:20].

See *Main ID Register* on page 4-22 for a description of CP15 c0, Main ID Register.

To use the DBGDIDR, read CP14 c0 with:

- Opcode_1 set to 0
- CRn set to c0
- CRm set to c0
- Opcode_2 set to 0.

For example:

MRC p14, 0, <Rd>, c0, c0, 0 ; Read Debug ID Register

11.5.2 Debug Status and Control Register

The DBGDSCR characteristics are:

Purpose Contains status and control information about the debug unit.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 11-1 on page 11-8.

Figure 11-4 on page 11-13 shows the DBGDSCR bit assignments.

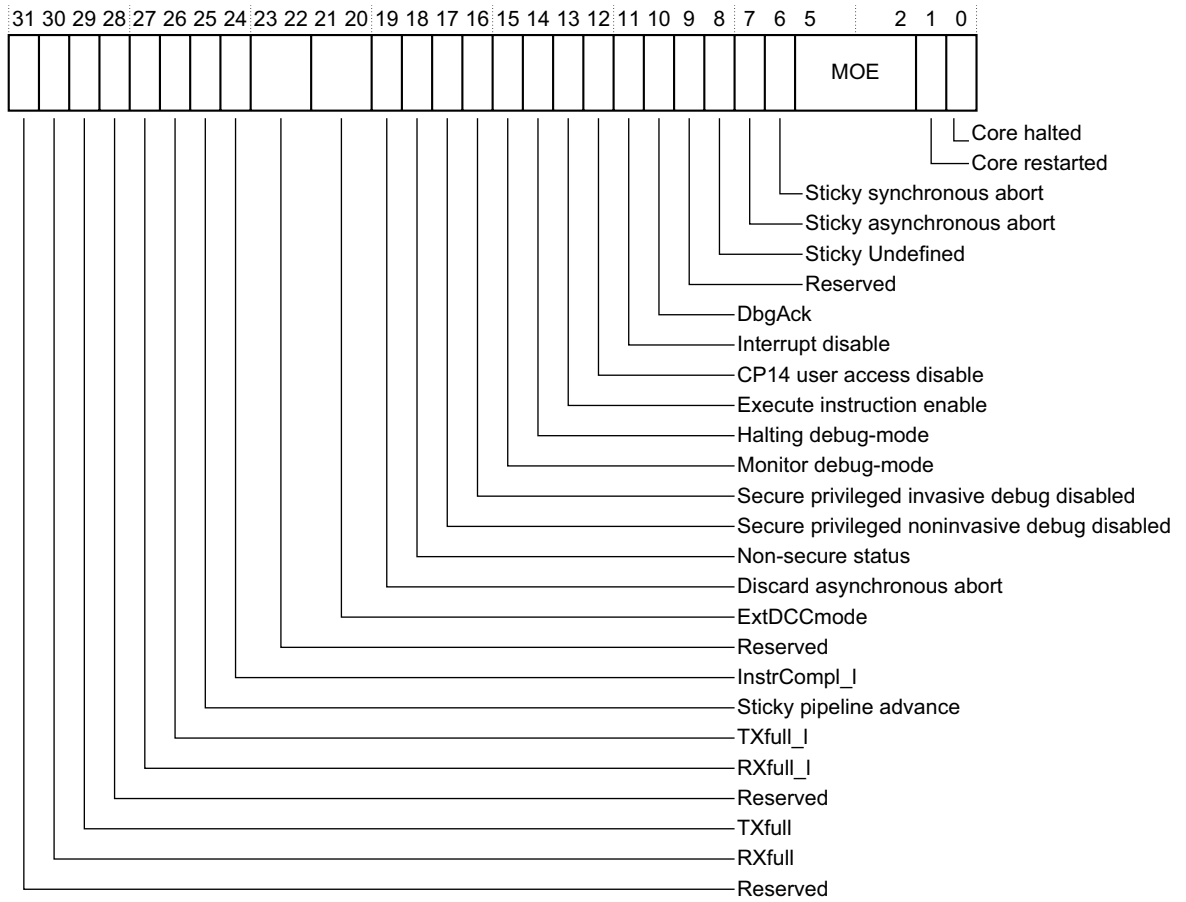


Figure 11-4 DBGDSCR bit assignments

Table 11-3 shows the DBGDSCR bit assignments.

Table 11-3 DBGDSCR bit assignments

Bits	Name	Description
[31]	Reserved	RAZ on reads, SBZP on writes.
[30]	RXfull	The DBGDTRRX Register full flag: 0 = DBGDTRRX empty, reset value 1 = DBGDTRRX full. When set, this flag indicates that there is data available in the Receive Data Transfer Register, DBGDTRRX. It is automatically set on writes to the DBGDTRRXext by the debugger, and is cleared when the processor reads the CP14 DBGDTRRXint. If the flag is not set, reads of the DBGDTRRX return an Unpredictable value.
[29]	TXfull	The DBGDTRTX Register full flag: 0 = DBGDTRTX empty, reset value 1 = DBGDTRTX full. When clear, this flag indicates that the Transmit Data Transfer Register, DBGDTRTX is ready for data write. It is automatically cleared on reads of the DBGDTRTXext by the debugger, and is set when the processor writes to the CP14 DBGDTRTXint. If this bit is set and the processor attempts to write to the DBGDTRTXint, results are Unpredictable.
[28]	Reserved	RAZ on reads, SBZP on writes.

Table 11-3 DBGDSCR bit assignments (continued)

Bits	Name	Description
[27]	RXfull_1	<p>The latched DBGDTRRX Register full flag. This flag is read in one of the following ways:</p> <ul style="list-style-type: none"> in DBGDSCRint using a CP14 instruction in DBGDSCRext using the APB interface or CP14 instruction. <p>Reads of DBGDSCRint return an Unpredictable value for this bit. Reads of DBGDSCRext return the same value as RXfull. If a write to the DBGDTRRXext address succeeds, RXfull_1 is set to 1.</p>
[26]	TXfull_1	<p>The latched DBGDTRTX Register full flag. This flag is read in one of the following ways:</p> <ul style="list-style-type: none"> in DBGDSCRint using a CP14 instruction in DBGDSCRext using the APB interface or CP14 instruction. <p>Reads of DBGDSCRint return an Unpredictable value for this bit. Reads of DBGDSCRext return the same value as TXfull. If a read to the DBGDTRTXext address succeeds, TXfull_1 is cleared.</p>
[25]	Sticky pipeline advance	<p>Sticky pipeline advance bit. This bit enables the debugger to detect whether the processor is idle. In some situations, this might mean that the system bus port is deadlocked. This bit is set to 1 every time the processor pipeline retires one instruction. A write to DBGDRCR[3] clears this bit. See <i>Debug Run Control Register</i> on page 11-19.</p> <p>0 = no instruction has completed execution since the last time this bit was cleared, reset value 1 = an instruction has completed execution since the last time this bit was cleared.</p>
[24]	InstrCompl_1	<p>The latched InstrCompl flag. This flag is read in one of the following ways:</p> <ul style="list-style-type: none"> in DBGDSCRint using CP14 instructions in DBGDSCRext using the APB interface. <p>When in Non-debug state, all reads of DBGDSCR return an Unpredictable value for this bit. Otherwise, reads through the CP14 interface return an Unpredictable value for this bit. Reads of the DBGDSCRext APB address return the same value as InstrCompl. If a write to the DBGITR APB address succeeds while in Stall or Nonblocking mode, InstrCompl_1 and InstrCompl are cleared. If a write to the DBGDTRRXext APB address or a read to the DBGDTRTXext APB address succeeds while in Fast mode, InstrCompl_1 and InstrCompl are cleared. InstrCompl is the instruction complete bit. This internal flag determines whether the processor has completed execution of an instruction issued through the APB interface. 0 = the processor is currently executing an instruction fetched from the DBGITR Register, reset value 1 = the processor is not currently executing an instruction fetched from the DBGITR Register.</p>
[23:22]	Reserved	RAZ on reads, SBZP on writes.
[21:20]	ExtDCCmode	<p>External DCC access mode. This is a read and write field. You can use this field to optimize DTR and DBGITR traffic between a debugger and the processor:</p> <p>b00 = Nonblocking mode, reset value b01 = Stall mode b10 = Fast mode b11 = reserved.</p> <p>Note</p> <ul style="list-style-type: none"> This field only affects the behavior of DBGDSCR, DTR, and DBGITR accesses through the APB port, and not through CP14 debug instructions. Nonblocking mode is the default setting. Improper use of the other modes might result in the debug access bus becoming jammed. <p>See <i>External DCC and DBGITR access mode</i> on page 11-17 for more information.</p>

Table 11-3 DBGDSCR bit assignments (continued)

Bits	Name	Description
[19]	Discard asynchronous abort	Discard asynchronous abort. This read-only bit is set while the processor is in debug state and is cleared on exit from debug state. While this bit is set, the processor does not record asynchronous Data Aborts. However, the sticky asynchronous Data Abort bit is set to 1. 0 = asynchronous Data Aborts not discarded, reset value 1 = asynchronous Data Aborts discarded.
[18] ^a	Non-secure state status	Non-secure state status bit: 0 = the processor is in Secure state or the processor is in Monitor mode 1 = the processor is in Non-secure state and is not in Monitor mode.
[17] ^a	Secure privileged noninvasive debug disabled	Secure privileged noninvasive debug disabled: 0 = ((NIDEN DBGEN) && (SPNIDEN SPIDEN)) is HIGH 1 = ((NIDEN DBGEN) && (SPNIDEN SPIDEN)) is LOW. This value is the inverse of bit [6] of the Authentication Status Register. See <i>Authentication Status Register</i> on page 11-33.
[16] ^a	Secure privileged invasive debug disabled	Secure privileged invasive debug disabled: 0 = (DBGEN && SPIDEN) is HIGH 1 = (DBGEN && SPIDEN) is LOW. This value is the inverse of bit [4] of the Authentication Status Register. See <i>Authentication Status Register</i> on page 11-33.
[15]	Monitor debug-mode	The Monitor debug-mode enable bit. This is a read and write bit. 0 = Monitor debug-mode disabled, reset value 1 = Monitor debug-mode enabled. If Halting debug-mode is enabled, bit [14] is set, then the processor is in Halting debug-mode regardless of the value of bit [15]. If the external interface input DBGEN is LOW, DBGDSCR[15] reads as 0. If DBGEN is HIGH, then the read value reverts to the programmed value.
[14]	Halting debug-mode	The Halting debug-mode enable bit. This is a read and write bit. 0 = Halting debug-mode disabled, reset value 1 = Halting debug-mode enabled. If the external interface input DBGEN is LOW, DBGDSCR[14] reads as 0. If DBGEN is HIGH, then the read value reverts to the programmed value.
[13]	Execute instruction enable	Execute ARM instruction enable bit. This is a read and write bit. 0 = disabled, reset value 1 = enabled. If this bit is set and a DBGITR write succeeds, the processor fetches an instruction from the DBGITR for execution. If this bit is set to 1 when the processor is not in debug state, the behavior of the processor is Unpredictable.
[12]	CP14 user access disable	CP14 debug user access disable control bit. This is a read and write bit. 0 = CP14 debug user access enable, reset value 1 = CP14 debug user access disable. If this bit is set and a User mode process tries to access any CP14 debug registers, the Undefined instruction exception is taken.

Table 11-3 DBGDSCR bit assignments (continued)

Bits	Name	Description
[11]	Interrupt disable	<p>Interrupts disable bit. This is a read and write bit.</p> <p>0 = interrupts enabled, reset value 1 = interrupts disabled.</p> <p>If this bit is set, the IRQ and FIQ input signals are disabled. The external debugger can set this bit before it executes code in normal state as part of the debugging process. If this bit is set to 1, an interrupt does not take control of the program flow. For example, the debugger might use this bit to execute an OS service routine to bring a page from disk into memory. It might be undesirable to service any interrupt during the routine execution.</p> <p>This bit is ignored when either:</p> <ul style="list-style-type: none"> • <code>DBGDSCR[15:14] == 0b00</code> • DBGEN is LOW.
[10]	DbgAck	<p>Debug Acknowledge bit. This is a read and write bit. If this bit is set to 1, both the DBGACK and DBGTRIGGER output signals are forced HIGH, regardless of the processor state. The external debugger can use this bit if it wants the system to behave as if the processor is in debug state. Some systems rely on DBGACK to determine whether the application or debugger generates the data accesses. The reset value is 0.</p>
[9]	Reserved	RAZ on reads, SBZP on writes.
[8]	Sticky Undefined	<p>Sticky Undefined bit:</p> <p>0 = No Undefined instruction exception occurred in debug state since the last time this bit was cleared. This is the reset value.</p> <p>1 = An Undefined instruction exception has occurred while in debug state since the last time this bit was cleared.</p> <p>This flag detects Undefined instruction exceptions generated by instructions issued to the processor through the DBGITR. This bit is set to 1 when an Undefined instruction exception occurs while the processor is in debug state. Writing a 1 to DBGDRCR[2] clears this bit. See <i>Debug Run Control Register</i> on page 11-19.</p>
[7]	Sticky asynchronous abort	<p>Sticky asynchronous Data Abort bit:</p> <p>0 = no asynchronous Aborts occurred since the last time this bit was cleared, reset value 1 = an asynchronous Abort occurred since the last time this bit was cleared.</p> <p>This flag detects asynchronous Aborts triggered by instructions issued to the processor through the DBGITR. This bit is set to 1 when an asynchronous Abort occurs while the processor is in debug state. Writing a 1 to DBGDRCR[2] clears this bit. See <i>Debug Run Control Register</i> on page 11-19.</p>
[6]	Sticky synchronous abort	<p>Sticky synchronous Data Abort bit:</p> <p>0 = no synchronous Data Abort occurred since the last time this bit was cleared, reset value 1 = a synchronous Data Abort occurred since the last time this bit was cleared.</p> <p>This flag detects synchronous Data Aborts generated by instructions issued to the processor through the DBGITR. This bit is set to 1 when a synchronous Data Abort occurs while the processor is in debug state. Writing a 1 to DBGDRCR[2] clears this bit. See <i>Debug Run Control Register</i> on page 11-19.</p> <p>When this is set, no instructions are issued through the DBGITR. Writes to DBGITR are ignored and, if ExtDCCmode is configured for Fast mode, reads of DBGDTRText and writes of DBGDTRRText are ignored.</p>

Table 11-3 DBGDSCR bit assignments (continued)

Bits	Name	Description
[5:2]	MOE	<p>MOE, Method of entry bits. This is a read and write field.</p> <p>b0000 = a DRCR[0] halting debug event occurred, reset value</p> <p>b0001 = a breakpoint occurred</p> <p>b0010 = not supported</p> <p>b0011 = a BKPT instruction occurred</p> <p>b0100 = an EDBGRQ halting debug event occurred</p> <p>b0101 = a vector catch debug event occurred</p> <p>b1010 = a synchronous watchpoint debug event occurred</p> <p>other = reserved.</p> <p>These bits are set to indicate any of:</p> <ul style="list-style-type: none"> the cause of a debug exception the cause for entering debug state. <p>A Prefetch Abort or Data Abort handler must check the value of the CP15 Fault Status Register to determine whether a debug exception occurred and then use these bits to determine the specific debug event.</p>
[1] ^a	Core restarted	<p>Core restarted bit:</p> <p>0 = The processor is exiting debug state.</p> <p>1 = The processor has exited debug state. This is the reset value.</p> <p>The debugger can poll this bit to determine when the processor responds to a request to leave debug state.</p>
[0] ^a	Core halted	<p>Core halted bit:</p> <p>0 = The processor is in normal state. This is the reset value.</p> <p>1 = The processor is in debug state.</p> <p>The debugger can poll this bit to determine when the processor has entered debug state.</p>

- a. These bits always reflect the status of the processor and, therefore they return to their reset values if the particular reset event affects the processor. For example, a core reset event such as **nDBGRESET** sets DBGDSCR[18] to a 0 and DBGDSCR[1:0] to b10.

Internal view

Access is through the Baseline CP14 interface and is read-only.

To access the DBGDSCRint, read CP14 c1 with:

MRC p14, 0, <Rd>, c0, c1, 0 ; Read Debug Status and Control Register

External view

Access is through the memory-mapped interface, offset 0x88, and through the Extended CP14 interface.

To access the DBGDSCRext through the Extended CP14 interface, read or write CP14 c2 with:

MRC p14, 0, <Rd>, c0, c2, 2 ; Read Debug Status and Control Register

MCR p14, 0, <Rd>, c0, c2, 2 ; Write Debug Status and Control Register

External DCC and DBGITR access mode

You can use the DBGDSCR.ExtDCCmode field to optimize data transfer between a debugger and the processor.

The DBGDSCR.ExtDCCmode can be one of the following:

- Nonblocking. This is the default mode

- Stall
- Fast.

In Nonblocking mode, the APB reads from the DBGDTRTXext and writes to the DBGDTRRXext and DBGITR are ignored if the appropriate latched READY flag is not in the ready state. In particular:

- writes to DBGDTRRXext are ignored if RXfull_1 is set
- writes to DBGITR are ignored if InstrCompl_1 is not set
- reads from DBGDTRTXext are ignored and return an Unpredictable value if TXfull_1 is not set.

Debuggers accessing these registers must first read DBGDSCRExt. This has the side-effect of copying RXfull and TXfull to RXfull_1 and TXfull_1, and setting InstrCompl_1. The debugger can then use the returned value to determine whether a subsequent access to these registers will be ignored.

In Stall mode, the APB accesses to DBGDTRRXext, DBGDTRTXext, and DBGITR stall under the following conditions:

- writes to DBGDTRRXext are stalled until RXfull is cleared
- writes to DBGITR are stalled until InstrCompl is set
- reads from DBGDTRTXext are stalled until TXfull is set.

In Fast mode, the processor fetches an instruction from the DBGITR when a DBGDTRRXext write or DBGDTRTXext read succeeds. In Stall mode and Nonblocking mode, the processor fetches an instruction from the DBGITR when an DBGITR write succeeds.

11.5.3 Program Counter Sampling Register

The DBGPCSR characteristics are:

- Purpose** Indicates the VA of the latest branch target plus a processor state dependent offset. The bottom two bits encode the processor state so the profiling tool can work out the VA by subtracting the offset.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-1 on page 11-8.

Figure 11-5 shows the DBGPCSR bit assignments.

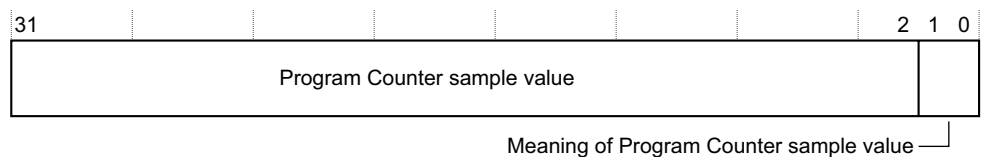


Figure 11-5 DBGPCSR bit assignments

Table 11-4 shows the DBGPCSR bit assignments.

Table 11-4 DBGPCSR bit assignments

Bits	Name	Description
[31:2]	Program Counter Sample value	The sampled value of bits [31:2] of the Program Counter.
[1:0]	Meaning of Program Counter Sample value	b00 = References an ARM state instruction. bx1 = References a Thumb or ThumbEE state instruction. b10 = Jazelle-DBX.

Reads through the Extended CP14 interface of the CP14 register that map to the DBGPCSR are Unpredictable.

11.5.4 Debug State Cache Control Register

The DBGDSCCR controls cache behavior while the processor is in debug state. The Cortex-A5 MPCore processor does not implement any of the features of the DBGDSCCR. The DBGDSCCR is read-as-zero.

11.5.5 Event Catch Register

The DBGECR configures the debug logic to generate a debug event in certain circumstances. The Cortex-A5 MPCore processor does not implement any of the features of the DBGECR. The DBGECR is read-as-zero.

11.5.6 Debug State MMU Control Register

The DBGDSMCR controls TLB behavior when the processor is in Debug state. The Cortex-A5 MPCore processor does not implement any of the features of the DBGDSMCR. The DBGDSMCR is read-as-zero.

11.5.7 Operating System Lock and Save/Restore Registers

The DBGOSLAR, DBGOSLSR, and DBGOSSRR registers are defined in the ARMv7 Debug architecture to allow access control and save/restore of operating system registers during debug. The Cortex-A5 MPCore processor does not implement any of the features of these registers. The DBGOSSRR is read-as-zero and write-ignore, DBGOSLSR is read-only and read-as-zero, and DBGOSLAR is write-only and write ignore.

11.5.8 Debug Run Control Register

The DBGDRCR characteristics are:

Purpose	Requests the processor to enter or leave debug state. It also clears the sticky exception bits present in the DBGDSCR.
Usage constraints	There are no usage constraints.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 11-1 on page 11-8.

Figure 11-6 on page 11-20 shows the DBGDRCR bit assignments.

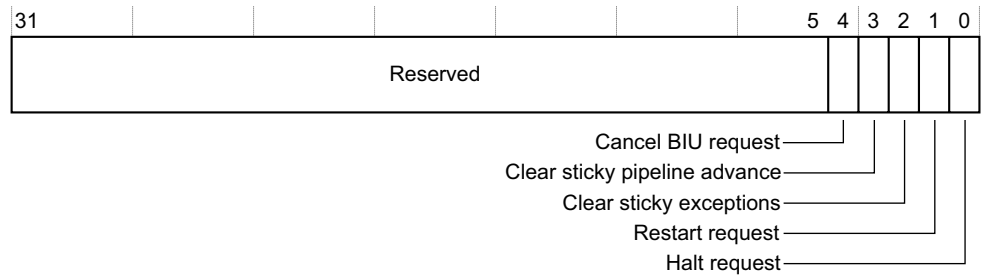


Figure 11-6 DBGDRCR bit assignments

Table 11-5 shows the DBGDRCR bit assignments.

Table 11-5 DBGDRCR bit assignments

Bits	Name	Description
[31:5]	Reserved	RAZ/SBZP.
[4]	Cancel BIU request	Implemented.
[3]	Clear sticky pipeline advance	Clear sticky pipeline advance. Writing a 1 to this bit clears DBGDSCR[25].
[2]	Clear sticky exceptions	Clear sticky exceptions. Writing a 1 to this bit clears DBGDSCR[8:6].
[1]	Restart request	Restart request. Writing a 1 to this bit requests that the processor leaves debug state. This request is held until the processor exits debug state. When the debugger makes this request, it polls DBGDSCR[1] until it reads 1. This bit always reads as zero. Writes are ignored when the processor is not in debug state.
[0]	Halt request	Halt request. Writing a 1 to this bit triggers a halting debug event, that is, a request that the processor enters debug state. This request is held until the debug state entry occurs. When the debugger makes this request, it polls DBGDSCR[0] until it reads 1. This bit always reads as zero. Writes are ignored when the processor is already in debug state.

11.5.9 Breakpoint Value Registers

The DBGBVR characteristics are:

Purpose	Contains the breakpoint value that corresponds to either an instruction address or a context ID. Breakpoints can be set on: <ul style="list-style-type: none"> an instruction address a context ID value an instruction address and context ID pair. For an instruction address and context ID pair, two BRPs must be linked. A debug event is generated when both the instruction address and the context ID pair match at the same time.
Usage constraints	There are no usage constraints.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 11-1 on page 11-8.

Each DBGBVR is associated with a *Breakpoint Control Register* (DBGBCR), as follows:

- DBGBVR0 with DBGBCR0
- DBGBVR1 with DBGBCR1

- DBGBVR2 with DBGBCR2.

A pair of breakpoint registers, DBGBVR_n and DBGBCR_n, is called a *Breakpoint Register Pair* (BRP_n).

Table 11-6 shows the DBGBVRs and corresponding DBGBCRs.

Table 11-6 DBGBVRs and corresponding DBGBCRs

Breakpoint Value Registers			Breakpoint Control Registers		
Register	Register number	Offset	Register	Register number	Offset
DBGBVR0	64	0x100	DBGBCR0	80	0x140
DBGBVR1	65	0x104	DBGBCR1	81	0x144
DBGBVR2	66	0x108	DBGBCR2	82	0x148

Table 11-7 shows the DBGBVR bit assignments.

Table 11-7 DBGBVR bit assignments

Bits	Name	Description
[31:0]	-	Breakpoint value. The reset value is Unpredictable.

Note

- Only BRP2 supports context ID comparison.
- DBGBVR0[1:0] and DBGBVR1[1:0] are SBZP on writes and RAZ on reads because these registers do not support context ID comparisons.
- The context ID value for DBGBVR2 to match with is given by the contents of the CP15 Context ID Register. See Chapter 4 *System Control* for information on the Context ID Register.

11.5.10 Breakpoint Control Registers

The DBGBCR characteristics are:

Purpose	Contains the necessary control bits for setting breakpoints and linked breakpoints.
Usage constraints	There are no usage constraints.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 11-1 on page 11-8.

Figure 11-7 on page 11-22 shows the DBGBCR bit assignments.

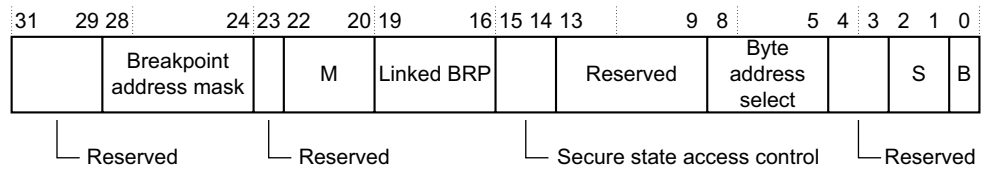


Figure 11-7 DBGBCR bit assignments

Table 11-8 shows the DBGBCR bit assignments.

Table 11-8 DBGBCR bit assignments

Bits	Name	Description
[31:29]	Reserved	RAZ on reads, SBZP on writes.
[28:24]	Breakpoint address mask	Breakpoint address mask. RAZ/WI b00000 = no mask
[23]	Reserved	RAZ on reads, SBZP on writes.
[22:20]	M	Meaning of DBGBVR: b000 = instruction virtual address match b001 = linked instruction virtual address match b010 = unlinked context ID b011 = linked context ID b100 = instruction virtual address mismatch b101 = linked instruction virtual address mismatch b11x = reserved. <p style="text-align: center;">Note</p> DBGBCR0[21] and DBGBCR1[21] are RAZ on reads because these registers do not have context ID comparison capability.
[19:16]	Linked BRP	Linked BRP number. The binary number encoded here indicates another BRP to link this one with. <p style="text-align: center;">Note</p> <ul style="list-style-type: none"> If a BRP is linked with itself, it is Unpredictable whether a breakpoint debug event is generated If this BRP is linked to another BRP that is not configured for linked context ID matching, it is Unpredictable whether a breakpoint debug event is generated.
[15:14]	Secure state access control	Secure state access control. This field enables the breakpoint to be conditional on the security state of the processor. b00 = breakpoint matches in both Secure and Non-secure state b01 = breakpoint only matches in Non-secure state b10 = breakpoint only matches in Secure state b11 = reserved.
[13:9]	Reserved	RAZ on reads, SBZP on writes.

Table 11-8 DBGBCR bit assignments (continued)

Bits	Name	Description
[8:5]	Byte address select	<p>Byte address select. For breakpoints programmed to match an instruction address, you must write a word-aligned address to the DBGBVR. You can then use this field to program the breakpoint so it hits only if you access certain byte addresses.</p> <p>If you program the BRP for instruction address match:</p> <p>b0000 = the breakpoint never hits</p> <p>b0011 = the breakpoint hits if any of the two bytes starting at address DBGBVR & 0xFFFFFFFFC +0 is accessed</p> <p>b1100 = the breakpoint hits if any of the two bytes starting at address DBGBVR & 0xFFFFFFFFC +2 is accessed</p> <p>b1111 = the breakpoint hits if any of the four bytes starting at address DBGBVR & 0xFFFFFFFFC +0 is accessed.</p> <p>If you program the BRP for instruction address mismatch, the breakpoint hits where the corresponding instruction address breakpoint does not hit, that is, the range of addresses covered by an instruction address mismatch breakpoint is the negative image of the corresponding instruction address breakpoint.</p> <p>If you program the BRP for context ID comparison, this field must be set to b1111. Otherwise, breakpoint and watchpoint debug events might not be generated as expected.</p>
[4:3]	Reserved	RAZ on reads, SBZP on writes.
[2:1]	S	<p>Supervisor access control. The breakpoint can be conditioned on the mode of the processor:</p> <p>b00 = User, System, or Supervisor</p> <p>b01 = privileged</p> <p>b10 = User</p> <p>b11 = any.</p>
[0]	B	<p>Breakpoint enable:</p> <p>0 = breakpoint disabled, reset value</p> <p>1 = breakpoint enabled.</p>

Table 11-9 Meaning of DBGBVR bits [22:20]

BVR[22:20]	Meaning
b000	The corresponding DBGBVR[31:2] is compared against the instruction address bus and the state of the processor against this DBGBCR. It generates a breakpoint debug event on a joint instruction address and state match.
b001	The corresponding DBGBVR[31:2] is compared against the instruction address bus and the state of the processor against this DBGBCR. This BRP is linked with the one indicated by DBGBCR[19:16] linked BRP field. They generate a breakpoint debug event on a joint instruction address, context ID, and state match.
b010	The corresponding DBGBVR[31:0] is compared against CP15 Context ID Register, c13 and the state of the processor against this DBGBCR. This BRP is not linked with any other one. It generates a breakpoint debug event on a joint context ID and state match. For this BRP, DBGBCR[8:5] must be set to b1111. Otherwise, it is Unpredictable whether a breakpoint debug event is generated.
b011	The corresponding DBGBVR[31:0] is compared against CP15 Context ID Register, c13. This BRP links another BRP (of the DBGBCR[21:20]=b01 type), or WRP (with DBGWCR[20]=b1). They generate a breakpoint or watchpoint debug event on a joint instruction address or data address and context ID match. For this BRP, DBGBCR[8:5] must be set to b1111, DBGBCR[15:14] must be set to b00, and DBGBCR[2:1] must be set to b11. Otherwise, it is Unpredictable whether a breakpoint debug event is generated.

Table 11-9 Meaning of DBGBVR bits [22:20] (continued)

BVR[22:20]	Meaning
b100	The corresponding DBGBVR[31:2] and DBGBCR[8:5] are compared against the instruction address bus and the state of the processor against this DBGBCR. It generates a breakpoint debug event on a joint instruction address mismatch and state match.
b101	The corresponding DBGBVR[31:2] and DBGBCR[8:5] are compared against the instruction address bus and the state of the processor against this DBGBCR. This BRP is linked with the one indicated by DBGBCR[19:16] linked BRP field. It generates a breakpoint debug event on a joint instruction address mismatch, state and context ID match.
b11x	Reserved. The behavior is Unpredictable.

11.5.11 Watchpoint Value Register

The DBGWVR characteristics are:

- Purpose** Contains the watchpoint value that corresponds to a data address and can be set either on:
 - a data address
 - a data address and context ID pair.

For a data address and context ID pair, a WRP and a BRP with context ID comparison capability must be linked. A debug event is generated when both the data address and the context ID pair match simultaneously.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-1 on page 11-8.

The DBGWVR is associated with a *Watchpoint Control Register* (DBGWCR).

Table 11-10 shows the DBGWVR and DBGWCR relationship.

Table 11-10 DBGWVR and corresponding DBGWCR

Watchpoint Value Registers			Watchpoint Control Registers		
Register	Register number	Offset	Register	Register number	Offset
DBGWVR0	96	0x180	DBGWCR0	112	0x1C0
DBGWVR1	97	0x184	DBGWCR1	113	0x1C4

A pair of watchpoint registers, DBGWVR and DBGWCR, is called a *Watchpoint Register Pair* (WRP).

Table 11-11 shows the DBGWVR bit assignments.

Table 11-11 DBGWVR bit assignments

Bits	Name	Description
[31:2]	-	Watchpoint address
[1:0]	-	RAZ on reads, SBZP on writes

11.5.12 Watchpoint Control Register

The DBGWCR characteristics are:

- Purpose** Contains the necessary control bits for setting watchpoints and linked watchpoints.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-1 on page 11-8.

Figure 11-8 shows the DBGWCR bit assignments.

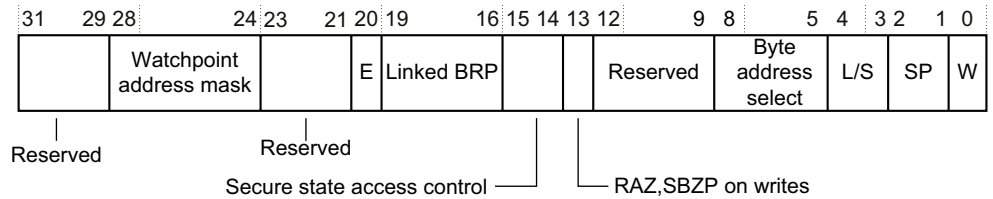


Figure 11-8 DBGWCR bit assignments

Table 11-12 shows the DBGWCR bit assignments.

Table 11-12 DBGWCR bit assignments

Bits	Name	Description
[31:29]	Reserved	RAZ on reads, SBZP on writes.
[28:24]	Watchpoint address mask	<p>This field watches a range of addresses by masking lower order address bits out of the watchpoint comparison:</p> <p>b00000 = no mask b00001 = reserved b00010 = reserved b00011 = 0x00000007 mask for data address b00100 = 0x0000000F mask for data address b00101 = 0x0000001F mask for data address . . . b11111 = 0x7FFFFFFF mask for data address.</p> <p>Note</p> <ul style="list-style-type: none"> • If bits [28:24] are not set to b00000, bits [12:5] must be set to b11111111. Otherwise the behavior is Unpredictable. • If [28:24] are not set to b00000, the corresponding DBGWVR bits that are not being included in the comparison SBZ. Otherwise the behavior is Unpredictable. <p>To watch for a write to any byte in an 8-byte aligned object of size 8 bytes, ARM recommends that a debugger sets bits [28:24] to b00111, and bits [12:5] to b11111111. This is compatible with both ARMv7 debug compliant implementations that have an 8-bit byte address select field (bits [12:5]) and with those that have a 4-bit byte address select field (bits [8:5]).</p>
[23:21]	Reserved	RAZ on reads, SBZP on writes.

Table 11-12 DBGWCR bit assignments (continued)

Bits	Name	Description
[20]	E	Enable linking bit: 0 = linking disabled 1 = linking enabled. When this bit is set, this watchpoint is linked with the context ID holding BRP selected by the linked BRP field.
[19:16]	Linked BRP	Linked BRP number. The binary number encoded here indicates a context ID holding BRP to link this WRP with. If this WRP is linked to a BRP that is not configured for linked context ID matching, it is Unpredictable whether a watchpoint debug event is generated.
[15:14]	Secure state access control	Secure state access control. This field enables the watchpoint to be conditioned on the security state of the processor. b00 = watchpoint matches in both Secure and Non-secure state b01 = watchpoint only matches in Non-secure state b10 = watchpoint only matches in Secure state b11 = reserved.
[13]	Reserved	RAZ on reads, SBZP on writes.
[12:9]	Reserved	RAZ/WI
[8:5]	Byte address select	Byte address select. The DBGWVR is programmed with word-aligned address. You can use this field to program the watchpoint so it only hits if certain byte addresses are accessed.
[4:3]	L/S	Load/store access. The watchpoint can be conditioned to the type of access being done. b00 = reserved b01 = load, load exclusive, or swap b10 = store, store exclusive or swap b11 = either. SWP and SWPB trigger a watchpoint on b01, b10, or b11. A load exclusive instruction triggers a watchpoint on b01 or b11. A store exclusive instruction triggers a watchpoint on b10 or b11 only if it passes the local monitor within the processor. ^a
[2:1]	S	Privileged access control ^b . The watchpoint can be conditioned to the privilege of the access being done: b00 = reserved b01 = privileged, match if the processor does a privileged access to memory b10 = User, match only on nonprivileged accesses b11 = either, match all accesses.
[0]	W	Watchpoint enable: 0 = watchpoint disabled, reset value 1 = watchpoint enabled.

a. A store exclusive can generate an MMU fault or cause the processor to take a data watchpoint exception regardless of the state of the local monitor.

b. For all cases, the match refers to the privilege of the access, not the mode of the processor.

11.5.13 Device Power-down and Reset Control Register

The DBGPRCR characteristics are:

Purpose Controls power-down related functionality.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 11-1 on page 11-8.

Figure 11-9 shows the DBGPRCR bit assignments.

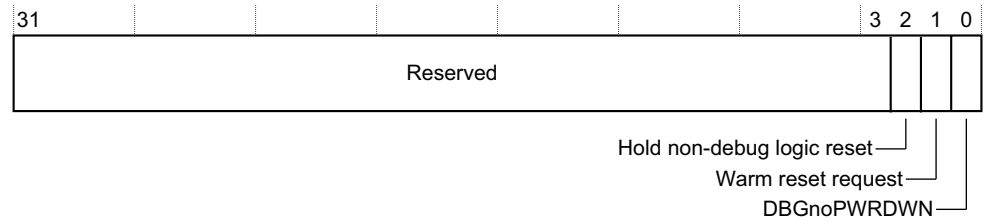


Figure 11-9 DBGPRCR bit assignments

Table 11-13 shows the DBGPRCR bit assignments.

Table 11-13 DBGPRCR bit assignments

Bits	Name	Description
[31:3]	Reserved	RAZ on reads, SBZP on writes
[2]	Hold non-debug logic reset	Hold non-debug logic reset: 0 = Do not hold the non-debug logic reset on power-up or warm reset. 1 = Hold the non-debug logic of the processor in reset on power-up or warm reset. The processor is held in this state until this flag is cleared to 0.
[1]	Warm reset request	RAZ
[0]	DBGnoPWRDWN	When set to 1, the DBGNOPWRDWN output signal is HIGH. This output is connected to the system power controller and is interpreted as a request to operate in emulate mode. In this mode, the Cortex-A5 MPCore processor and ETM are not actually powered down when requested by software or hardware handshakes. 0 = DBGNOPWRDWN is LOW. This is the reset value. 1 = DBGNOPWRDWN is HIGH.

11.5.14 Device Power-down and Reset Status Register

The DBGPRSR characteristics are:

Purpose Provides information about the reset and power-down state of the processor.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 11-1 on page 11-8.

Note

The Cortex-A5 processor does not support debug of powered down processors.

Figure 11-10 on page 11-28 shows the DBGPRSR bit assignments.

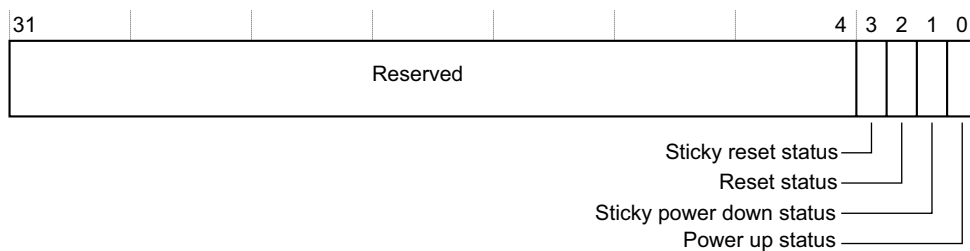


Figure 11-10 DBGPRSR bit assignments

Table 11-14 shows the DBGPRSR bit assignments.

Table 11-14 DBGPRSR bit assignments

Bits	Name	Description
[31:4]	Reserved	RAZ on reads, SBZP on writes
[3]	-	Sticky reset status
[2]	-	Reset status
[1]	-	Sticky power-down status. RAZ
[0]	-	Power up status. RAO

11.6 Management registers

The management registers define the standardized set of registers implemented by all CoreSight components. This section describes these registers.

Table 11-15 shows the contents of the management registers for the Cortex-A5 MPCore processor debug unit.

Table 11-15 Management registers

Offset	Register number	Access	Mnemonic	Description
0xD00-0xDFC	832-895	RO	-	<i>Processor ID Registers</i>
0xE00-0xEF0	854-956	-	-	RAZ
0xF00	960	RW	DBGITCTRL	<i>Integration Mode Control Register</i> on page 11-40
0xF04-0xF9C	961-999	RAZ	-	Reserved for Management Register expansion
0xFA0	1000	RW	DBGCLAIMSET	<i>Claim Tag Set Register</i> on page 11-30
0xFA4	1001	RW	DBGCLAIMCLR	<i>Claim Tag Clear Register</i> on page 11-31
0xFA8-0xFBC	1002-1003	-	-	RAZ
0xFB0	1004	WO	DBGLAR	<i>Lock Access Register</i> on page 11-31
0xFB4	1005	RO	DBGLSR	<i>Lock Status Register</i> on page 11-32
0xFB8	1006	RO	DBGAUTHSTATUS	<i>Authentication Status Register</i> on page 11-33
0xFBC-0xFC4	1007-1009	-	-	RAZ
0xFC8	1010	RO	DBGDEVID	Device Identifier.
0xFCC	1011	RO	DBGDEVTYPE	<i>Device Type Register</i> on page 11-34
0xFD0-0xFFC	1012-1023	RO	-	<i>Identification Registers</i> on page 11-34

11.6.1 Processor ID Registers

The Processor ID Registers are read-only registers that return the same values as the corresponding CP15 ID Code Register and Feature ID Register.

Table 11-16 shows the offset value, register number, mnemonic, and description that are associated with each Processor ID Register.

Table 11-16 Processor Identifier Registers

Offset (hex)	Register number	Access	Mnemonic	Reset value	Description
0xD00	832	RO	MIDR	0x410FC051	<i>Main ID Register</i> on page 4-22
0xD04	833	RO	CTR	0x83338003	<i>Cache Type Register</i> on page 4-22
0xD08	834	RAZ	-	-	-
0xD0C	835	RO	TLBTR	0x00000000	<i>TLB Type Register</i> on page 4-24
0xD10	836	-	-	-	Reserved

Table 11-16 Processor Identifier Registers (continued)

Offset (hex)	Register number	Access	Mnemonic	Reset value	Description
0xD14	837	RO	MIDR	-	<i>Multiprocessor Affinity Register</i> on page 4-24
0xD18-0xD1C	838-839	RO	-	0x410FC051	Alias of MIDR
0xD20	840	RO	ID_PFR0	0x00001231	Processor Feature Register 0
0xD24	841	RO	ID_PFR1	0x00000011	Processor Feature Register 1
0xD28	842	RO	ID_DFR0	0x02010444	Debug Feature Register 0
0xD2C	843	RAZ	ID_AFR0	-	Auxiliary Feature Register 0
0xD30	844	RO	ID_MMFR0	0x00100103	Memory Model Feature Register 0
0xD34	845	RO	ID_MMFR1	0x40000000	Memory Model Feature Register 1
0xD38	846	RO	ID_MMFR2	0x01230000	Memory Model Feature Register 2
0xD3C	847	RO	ID_MMFR3	0x00102211	Memory Model Feature Register 3
0xD40	848	RO	ID_ISAR0	0x00101111	Instruction Set Attribute Register 0
0xD44	849	RO	ID_ISAR1	0x13112111	Instruction Set Attribute Register 1
0xD48	850	RO	ID_ISAR2	0x21232041	Instruction Set Attribute Register 2
0xD4C	851	RO	ID_ISAR3	0x11112131	Instruction Set Attribute Register 3
0xD50	852	RO	ID_ISAR4	0x00011142	Instruction Set Attribute Register 4
0xD54	853	RAZ	ID_ISAR5	-	Instruction Set Attribute Register 5

11.6.2 Claim Tag Set Register

The DBGCLAIMSET Register characteristics are:

Purpose Bits in the Claim Tag Set Register do not have any specific functionality. The external debugger and debug monitor set these bits to lay claims on debug resources.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 11-15 on page 11-29.

Figure 11-11 shows the DBGCLAIMSET Register bit assignments.



Figure 11-11 DBGCLAIMSET Register bit assignments

Table 11-17 shows the DBGCLAIMSET Register bit assignments.

Table 11-17 DBGCLAIMSET Register bit assignments

Bits	Name	Description
[31:8]	Reserved	RAZ on reads, SBZP on writes.
[7:0]	Claim tags	Indicates the claim tags. Writing 1 to a bit in this register sets that particular claim. You can read the claim status at the Claim Tag Clear Register. For example, if you write 1 to bit [3] of this register, bit [3] of the Claim Tag Clear Register is read as 1. Writing 0 to a specific claim tag bit has no effect. This register always reads 0xFF, indicating that up to eight claims can be set.

11.6.3 Claim Tag Clear Register

The DBGCLAIMCLR Register characteristics are:

- Purpose** Read the claim status on debug resources.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-15 on page 11-29.

Figure 11-12 shows the DBGCLAIMCLR Register bit assignments.

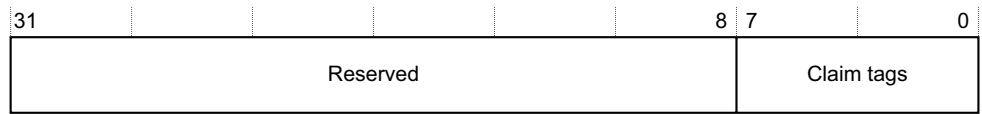


Figure 11-12 DBGCLAIMCLR Register bit assignments

Table 11-18 shows the DBGCLAIMCLR Register bit assignments.

Table 11-18 DBGCLAIMCLR Register bit assignments

Bits	Name	Description
[31:8]	Reserved	RAZ on reads, SBZP on writes.
[7:0]	Claim tags	Indicates the claim tag status. Writing 1 to a specific claim tag clear bit clears that claim tag. Reading this register returns the current claim tag value. For example, if you write 1 to bit [3] of this register, it is read as 0. The reset value is 0.

11.6.4 Lock Access Register

The DBGLAR Register characteristics are:

- Purpose** Controls writes to the debug registers. This reduces the risk of accidental corruption to the contents of the debug registers. It does not prevent all accidental or malicious damage. Because the state of the register is in the debug power domain, it is not lost when the core powers down.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-15 on page 11-29.

Figure 11-13 shows the DBGLAR Register bit assignments.

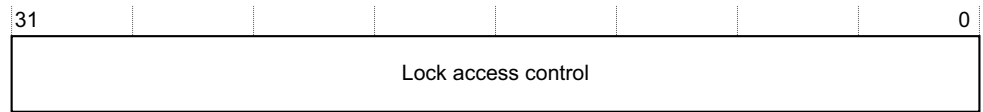


Figure 11-13 DBGLAR Register bit assignments

Table 11-19 shows the DBGLAR Register bit assignments.

Table 11-19 DBGLAR Register bit assignments

Bits	Name	Description
[31:0]	Lock access control	Lock access control. To unlock the debug registers, write a 0xC5ACCE55 key to this register. To lock the debug registers, write any other value. Accesses to locked debug registers are ignored. The reset value is 0.

When this register is written by an external debugger, APB write with **PADDRDBG31=1**, the results are Unpredictable.

11.6.5 Lock Status Register

The DBGLSR Register characteristics are:

Purpose Returns the current lock status of the debug registers.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 11-15 on page 11-29.

Figure 11-14 shows the DBGLSR Register bit assignments.

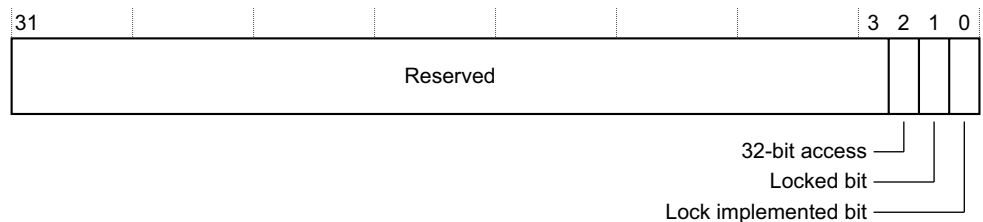


Figure 11-14 DBGLSR Register bit assignments

Table 11-20 shows the DBGLSR Register bit assignments.

Table 11-20 DBGLSR Register bit assignments

Bits	Name	Description
[31:3]	Reserved	Reserved

Table 11-20 DBGLSR Register bit assignments (continued)

Bits	Name	Description
[2]	32-bit access	Read as zero. It indicates that a 32-bit access is required to write the key to the Lock Access Register.
[1]	Locked bit	This bit indicates the status of the debug registers lock. 0 = Lock clear. Debug register writes are permitted. 1 = Lock set. Debug register writes are ignored. The Debug reset value of this bit is 1.
[0]	Lock implemented bit	Read-as-One

When this register is read by an external debugger, APB read with **PADDRDBG31=1**, the read value is 0x0.

11.6.6 Authentication Status Register

The DBGAUTHSTATUS Register characteristics are:

- Purpose** Reads the current values of the configuration inputs that determine the debug permission level.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-15 on page 11-29.

Figure 11-15 shows the DBGAUTHSTATUS Register bit assignments.

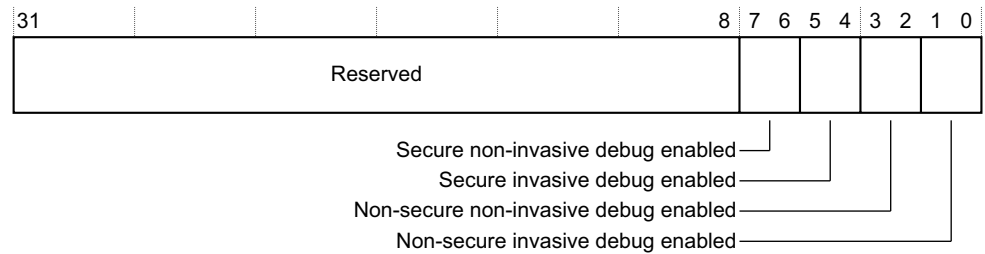


Figure 11-15 DBGAUTHSTATUS Register bit assignments

Table 11-21 shows the DBGAUTHSTATUS Register bit assignments.

Table 11-21 DBGAUTHSTATUS Register bit assignments

Bits	Name	Value	Description
[31:8]	Reserved	-	RAZ
[7]	Secure non-invasive debug enabled	b1	Secure non-invasive debug enable field
[6]	Secure invasive debug enabled	(DBGEN NIDEN) && (SPIDEN SPNIDEN)	
[5]	Non-secure non-invasive debug enabled	b1	Secure invasive debug enable field
[4]	Non-secure invasive debug enabled	DBGEN && SPIDEN	

Table 11-21 DBGAUTHSTATUS Register bit assignments (continued)

Bits	Name	Value	Description
[3]	Non-secure non-invasive debug enabled	b1	Non-secure non-invasive debug enable field
[2]		DBGEN NIDEN	
[1]	Non-secure invasive debug enabled	b1	Non-secure invasive debug enable field
[0]		DBGEN	

11.6.7 Device Type Register

The DBGDEVTYPE Register characteristics are:

- Purpose** Indicates the type of debug component.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-15 on page 11-29.

Figure 11-16 shows the DBGDEVTYPE bit assignments.



Figure 11-16 DBGDEVTYPE Register bit assignments

Table 11-22 shows the DBGDEVTYPE bit assignments.

Table 11-22 DBGDEVTYPE Register bit assignments

Bits	Name	Description
[31:8]	Reserved	RAZ.
[7:4]	Sub type	Indicates that the sub-type of the Cortex-A5 MPCore processor is <i>core</i> . This value is 0x1.
[3:0]	Main class	Indicates that the main class of the Cortex-A5 MPCore processor is <i>debug logic</i> . This value is 0x5.

11.6.8 Identification Registers

The Identification Registers are read-only registers that consist of the Peripheral Identification Registers and the Component Identification Registers. The Peripheral Identification Registers provide standard information required by all CoreSight components. Only bits [7:0] of each register are used.

The Component Identification Registers identify the processor as a CoreSight component. Only bits [7:0] of each register are used, the remaining bits Read-As-Zero. The values in these registers are fixed.

Table 11-23 shows the offset value, register number, and description that are associated with each Peripheral Identification Register.

Table 11-23 Peripheral Identification Registers

Offset (hex)	Register number	Description
0xFD0	1012	Peripheral Identification Register 4
0xFD4	1013	Reserved
0xFD8	1014	Reserved
0xFDC	1015	Reserved
0xFE0	1016	Peripheral Identification Register 0
0xFE4	1017	Peripheral Identification Register 1
0xFE8	1018	Peripheral Identification Register 2
0xFEC	1019	Peripheral Identification Register 3

Table 11-24 shows the Peripheral ID Register 0 bit assignments.

Table 11-24 Peripheral ID Register 0 bit assignments

Bits	Description
[31:8]	RAZ.
[7:0]	Indicates bits [7:0] of the part number for the Cortex-A5 processor. This value is 0x05.

Table 11-25 shows the Peripheral ID Register 1 bit assignments.

Table 11-25 Peripheral ID Register 1 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates bits of the JEDEC JEP106 Identity Code. This value is 0xB.
[3:0]	Indicates bits [11:8] of the part number for the Cortex-A5 processor. This value is 0xC.

Table 11-26 shows the Peripheral ID Register 2 bit assignments.

Table 11-26 Peripheral ID Register 2 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates the revision number for the Cortex-A5 MPCore processor. This value changes based on the product major and minor revision. This value is set to 1 indicating revision r0p1.
[3]	This field is always set to 0x1.
[2:0]	Indicates bits [6:4] of the JEDEC JEP106 Identity Code. This value is set to 0x3.

Table 11-27 shows the Peripheral ID Register 3 bit assignments.

Table 11-27 Peripheral ID Register 3 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates the manufacturer revision number. This value changes based on the manufacturer metal fixes. This value is set to 0.
[3:0]	For the Cortex-A5 MPCore processor, this value is set to 0.

Table 11-28 shows the Peripheral ID Register 4 bit assignments.

Table 11-28 Peripheral ID Register 4 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates the number of blocks occupied by the Cortex-A5 MPCore processor. This field is always set to 0.
[3:0]	Indicates the JEDEC JEP106 Continuation Code. For the Cortex-A5 MPCore processor, this value is 0x4.

Table 11-29 shows the offset value, register number, and value that are associated with each Component Identification Register.

Table 11-29 Component Identification Registers

Offset (hex)	Register number	Value	Description
0xFF0	1020	0x0D	Component Identification Register 0
0xFF4	1021	0x90	Component Identification Register 1
0xFF8	1022	0x05	Component Identification Register 2
0xFFC	1023	0xB1	Component Identification Register 3

11.7 Integration test registers

The Cortex-A5 MPCore processor contains Integration Test Registers that enable you to verify integration of the design and enable topology detection of the design using debug tools. The *Integration Mode Control Register* on page 11-40 controls the use of the Integration Test Registers.

When programming the Integration Test Registers you must enable all the changes at the same time.

For more information about the Integration Test Registers and the Integration Mode Control Register see the *ARM Architecture Reference Manual*.

11.7.1 Processor integration testing

This section describes the behavior and use of the Integration Test Registers that are in the processor. It also describes the Integration Mode Control Register that controls the use of the Integration Test Registers. For more information about the DBGITCTRL see the *ARM Architecture Reference Manual*.

If you want to access these registers you must first set bit [0] of the Integration Mode Control Register to 1.

- You can use the write-only Integration Test Registers to set the outputs of some of the processor signals. Table 11-30 shows the signals that you can write in this way.
- You can use the read-only Integration Test Registers to read the state of some of the processor inputs. Table 11-31 shows the signals that you can read in this way.

Table 11-30 Output signals that can be controlled by the Integration Test Registers

Signal	Register	Bit	Register description
DBGRESTARTED	DBGITMISCOUT	[9]	See <i>DBGITMISCOUT Register (Miscellaneous Outputs)</i> on page 11-38
PMUIRQ	DBGITMISCOUT	[4]	
DBGACK	DBGITMISCOUT	[0]	

Table 11-31 Input signals that can be read by the Integration Test Registers

Signal	Register	Bit	Register description
DBGRESTART	DBGITMISCIN	[11]	See <i>DBGITMISCIN Register (Miscellaneous Inputs)</i> on page 11-39
nIRQ	DBGITMISCIN	[2]	
nFIQ	DBGITMISCIN	[1]	
EDBGRQ	DBGITMISCIN	[0]	

This section describes:

- *Using the Integration Test Registers* on page 11-38
- *Performing integration testing* on page 11-38
- *DBGITMISCOUT Register (Miscellaneous Outputs)* on page 11-38
- *DBGITMISCIN Register (Miscellaneous Inputs)* on page 11-39
- *Integration Mode Control Register* on page 11-40.

Using the Integration Test Registers

When bit [0] of the Integration Mode Control Register (DBGITCTRL) is set to b1:

- Values written to the write-only Integration Test Registers map onto the specified outputs of the processor. For example, writing b1 to DBGITMISCOUT[0] causes the appropriate bit of **DBGACK** to be asserted HIGH for the core in the processor.
- Values read from the read-only Integration Test Registers correspond to the values of the specified inputs of the macrocell. For example, if you read DBGITMISCIN[11] you obtain the value of the **DBGRESTART** bit associated with the core in the processor.

Performing integration testing

When you perform integration testing or topology detection, ARM strongly recommends that the processor is halted while in debug state, because toggling input and output pins might have an unwanted effect on the operation of the processor. You must not set the DBGITCTRL Register until the processor has halted.

After you perform integration testing or topology detection, that is, the Integration Mode Control Register has been set, the system must be reset. This is because the signals that are toggled can have an unwanted effect on connected devices.

DBGITMISCOUT Register (Miscellaneous Outputs)

The DBGITMISCOUT Register characteristics are:

- Purpose** Sets the state of the output pins shown in Table 11-30 on page 11-37.
- Usage constraints**
- Available when bit [0] of DBGITCTRL is set to 1
 - The value of the register sets the signals on the output pins when the register is written.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-1 on page 11-8.

Figure 11-17 shows the DBGITMISCOUT Register bit assignments.

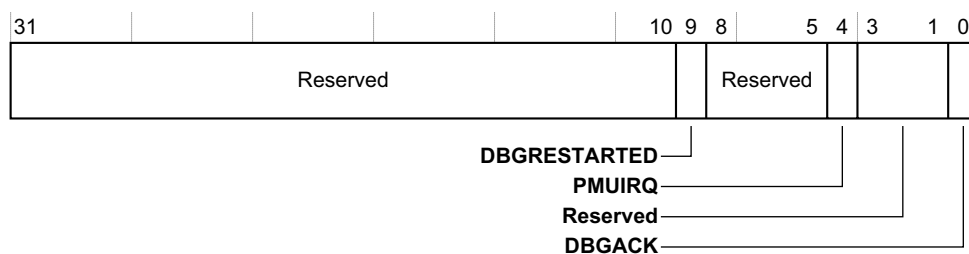


Figure 11-17 DBGITMISCOUT Register bit assignments

Table 11-32 shows the DBGITMISCOUT Register bit assignments. When this register is written the appropriate output pins take the value written.

Table 11-32 DBGITMISCOUT Register bit assignments

Bits	Name	Function
[31:10]	-	Reserved. Write as zero.
[9]	DBGRESTARTED	Set value of the DBGRESTARTED output pin.
[8:5]	-	Reserved. Write as zero.
[4]	PMUIRQ	Set value of PMUIRQ output pin.
[3:1]	-	Reserved. Write as zero.
[0]	DBGACK	Set value of the DBGACK output pin.

DBGITMISCIN Register (Miscellaneous Inputs)

The DBGITMISCIN Register characteristics are:

- Purpose** Reads the state of the input pins shown in Table 11-31 on page 11-37.
- Usage constraints**
 - Available when bit [0] of DBGITCTRL is set to 1
 - The values of the register bits depend on the signals on the input pins when the register is read.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 11-1 on page 11-8.

Figure 11-18 shows the DBGITMISCIN Register bit assignments.

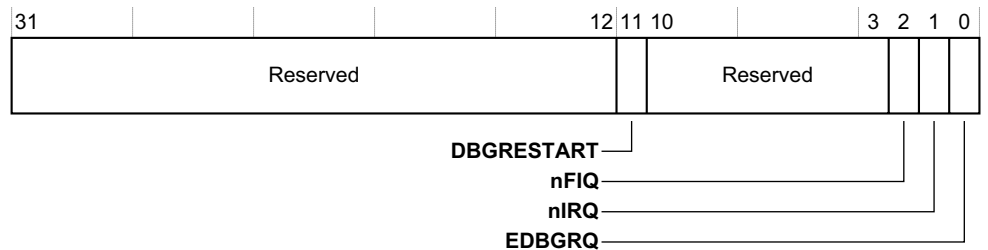


Figure 11-18 DBGITMISCIN Register bit assignments

Table 11-33 shows the DBGITMISCIN Register bit assignments.

Table 11-33 DBGITMISCIN Register bit assignments

Bits	Name	Function
[31:12]	-	Reserved. Read Undefined.
[11]	DBGRESTART	Read value of the DBGRESTART input pin.
[10:3]	-	Reserved. Read Undefined.

Table 11-33 DBGITMISCIN Register bit assignments (continued)

Bits	Name	Function
[2]	nFIQ	Read value of nFIQ input pin.
[1]	nIRQ	Read value of nIRQ input pin.
[0]	EDBGRQ	Read value of EDBGRQ input pin.

Integration Mode Control Register

The DBGITCTRL Register characteristics are:

Purpose Enables the processor to switch from a functional, default mode, into integration mode, where the inputs and outputs of the device can be directly controlled for integration testing or topology detection.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 11-1 on page 11-8.

Figure 11-19 shows the DBGITCTRL Register bit assignments.

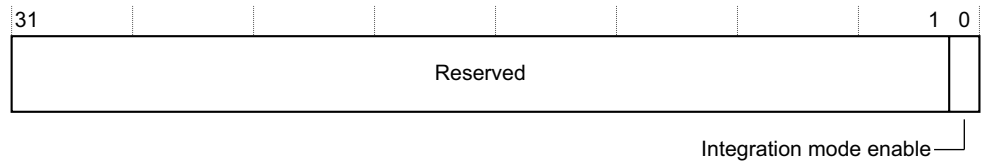
**Figure 11-19 DBGITCTRL Register bit assignments**

Table 11-34 shows the DBGITCTRL Register bit assignments.

Table 11-34 DBGITCTRL Register bit assignments

Bits	Name	Function
[31:1]	-	Reserved.
[0]	INTMODE	Controls whether the processor is in normal operating mode or integration mode: b0 = normal operation b1 = integration mode enabled.

Writing to the DBGITCTRL register controls whether the processor is in its default functional mode, or in integration mode, where the inputs and outputs of the device can be directly controlled for the purpose of integration testing or topology detection. For more information see the *ARM Architecture Reference Manual*.

11.8 External debug interface

The system can access memory-mapped debug registers through the Cortex-A5 MPCore APB slave port.

The APB interface is compliant with the AMBA 3 APB interface. This APB slave interface supports 32-bits wide data, stalls, slave-generated aborts, and thirteen address bits [14:2] mapping 2x4KB of memory for each of the 4 cores included in the Cortex-A5 MPCore processor. The individual cores are addressed using the APB address bits [14:13] as shown in Table 11-35.

Table 11-35 Address mapping used to access the debug interface for a core in the Cortex-A5 MPCore processor

PADDRDBG[14:13]	Core number in processor
b00	Core 0
b01	Core 1
b10	Core 2
b11	Core 3

Attempting to access the 4KB memory areas associated with cores which are not implemented in the configured Cortex-A5 MPCore processor results in unpredictable behavior.

The lower 4KB region is used to access the debug registers. The upper 4KB is used to access the Performance Monitor Registers, see Chapter 12 *Performance Monitoring Unit*. The **PADDRDBG31** signal indicates to the processor the source of access. See *External debug interface* on page A-14 for a complete list of the external debug signals.

Figure 11-20 shows the external debug interface signals.

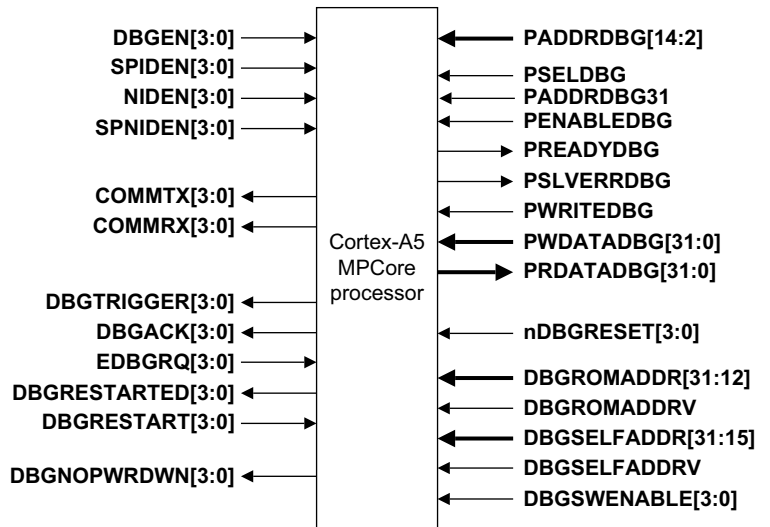


Figure 11-20 External debug interface signals

11.9 Miscellaneous debug signals

This section describes the miscellaneous debug input and output signals in more detail.

11.9.1 EDBGRRQ

This signal generates a halting debug event, that is, it requests the selected core in the processor to enter debug state. When this occurs, the DBGDSCR[5:2] method of debug entry bits are set to b0100. When **EDBGRQ** is asserted, it must be held until **DBGACK** is asserted. Failure to do so causes Unpredictable behavior.

11.9.2 DBGACK

The core in the processor asserts **DBGACK** to indicate that the system has entered debug state. It serves as a handshake for the **EDBGRQ** signal. The **DBGACK** signal is also driven HIGH when the debugger sets the DBGDSCR[10] DbgAck bit to 1. See *Debug Status and Control Register* on page 11-12.

11.9.3 COMMRX and COMMTX

The **COMMRX** and **COMMTX** output signals enable interrupt-driven communications over the DTR. By connecting these signals to an interrupt controller, software using the debug communications channel can be interrupted whenever there is new data on the channel or when the channel is clear for transmission.

COMMRX is asserted when the CP14 DTR has data for the core in the processor to read, and it is deasserted when the core in the processor reads the data. Its value is equal to DBGDSCR[30] DTRRX full flag. See *Debug Status and Control Register* on page 11-12.

COMMTX is asserted when CP14 is ready for write data, and it is deasserted when the processor writes the data. Its value equals the inverse of DBGDSCR[29] DTRTX full flag. See *Debug Status and Control Register* on page 11-12.

11.9.4 Memory mapped accesses, DBGROMADDR, and DBGSELFADDR

The Cortex-A5 MPCore processor has a memory-mapped debug interface. If the system includes a suitable route from the AXI master interface to the APB debug slave interface the processor can access the debug and PMU registers by executing load and store instructions:

- **DBGROMADDR** gives the base address for the ROM table which locates the physical addresses of the debug components.
- **DBGSELFADDR** gives the offset from the ROM table to the physical addresses of the registers owned by the processor itself.

11.9.5 Authentication signals

Table 11-36 shows a list of the valid combination of authentication signals along with their associated debug permissions. Authentication signals are used to configure the processor so its activity can only be debugged or traced in a certain subset of processor modes and security states.

Table 11-36 Authentication signal restrictions

SPIDEN	DBGEN ^a	SPNIDEN	NIDEN	Secure ^b invasive debug permitted	Non-secure invasive debug permitted	Secure non-invasive debug permitted	Non-secure non-invasive debug permitted
0	0	0	0	No	No	No	No
0	0	0	1	No	No	No	Yes
0	0	1	0	No	No	No	No
0	0	1	1	No	No	Yes	Yes
0	1	0	0	No	Yes	No	Yes
0	1	0	1	No	Yes	No	Yes
0	1	1	0	No	Yes	Yes	Yes
0	1	1	1	No	Yes	Yes	Yes
1	0	0	0	No	No	No	No
1	0	0	1	No	No	Yes	Yes
1	0	1	0	No	No	No	No
1	0	1	1	No	No	Yes	Yes
1	1	0	0	Yes	Yes	Yes	Yes
1	1	0	1	Yes	Yes	Yes	Yes
1	1	1	0	Yes	Yes	Yes	Yes
1	1	1	1	Yes	Yes	Yes	Yes

- When **DBGEN** is LOW, the processor behaves as if **DBGDSCR**[15:14] equals b00 with the exception that halting debug events are ignored when this signal is LOW.
- Invasive debug is defined as those operations that affect the behavior of the core. For example, taking a breakpoint is defined as invasive debug but performance counters and trace are noninvasive.

11.9.6 Changing the authentication signals

The **NIDEN**, **DBGEN**, **SPIDEN**, and **SPNIDEN** input signals are either tied off to some fixed value or controlled by some external device.

If software running on the Cortex-A5 MPCore processor has control over an external device that drives the authentication signals, it must make the change using a safe sequence:

- Execute an implementation-specific sequence of instructions to change the signal value. For example, this might be a single **STR** instruction that writes certain value to a control register in a system peripheral.
- If step 1 involves any memory operation, issue a **DSB**.

3. Poll **DBGDSCR** or **DBGAUTHSTATUS** to check whether the processor has already detected the changed value of these signals. This is required because the system might not issue the signal change to the processor until several cycles after the **DSB** completes.
4. Issue an **ISB**.

The software cannot perform debug or analysis operations that depend on the new value of the authentication signals until this procedure is complete. The same rules apply when the debugger has control of the processor through the **ITR** while in debug state.

The relevant combinations of the **DBGEN**, **NIDEN**, **SPIDEN**, and **SPNIDEN** values can be determined by polling **DBGDSCR**[17:16], **DBGDSCR**[15:14], or **DBGAUTHSTATUS**.

Chapter 12

Performance Monitoring Unit

This chapter describes the *Performance Monitoring Unit* (PMU) and the registers that it can use. It contains the following sections:

- *About the Performance Monitoring Unit* on page 12-2
- *Performance monitoring register descriptions* on page 12-4.

12.1 About the Performance Monitoring Unit

Each core in the Cortex-A5 MPCore processor contains a PMU which provides two counters to gather statistics on the operation of the core and memory system. Each counter can count any of the events available in the Cortex-A5 MPCore processor. It also provides a single 32-bit cycle counter with support for scaling and filtering on the processor mode and security state. See the *ARM Architecture Reference Manual, ARMv7-A and ARMv7-R edition* and *ARM Architecture Reference Manual Performance Monitors v2 Supplement* for more information about performance monitoring.

The PMU counters, and their associated control registers for each core in the processor, are accessible from the internal CP15 interface as well as through a 4KB memory mapped region on the APB interface when **PADDRDBG[12]** is b1. The core in the Cortex-A5 MPCore processor is selected using **PADDRDBG[14:13]**. Table 12-1 shows the mappings of the PMU registers for each core.

Table 12-1 Performance monitoring instructions and APB mapping

APB interface mapping	CP15 instruction	Access	Reset	Name	Description
0x1000	0 c9 c13 2	RW	-	PMXEVNTR0	PM0 Counter Register
0x1004	0 c9 c13 2	RW	-	PMXEVNTR1	PM1 Counter Register
0x107C	0 c9 c13 0	RW	-	PMCCNTR	Cycle Count Register
0x1400	0 c9 c13 1	RW	-	PMXEVTYPER0	PM0 Event Type Register
0x1404	0 c9 c13 1	RW	-	PMXEVTYPER1	PM0 Event Type Register
0x147C	0 c9 c13 1	RW	-	PMCCFILTR	Cycle Count Filter Control Register
0x1C00	0 c9 c12 1	RW	0x00000000	PMCNTENSET	Count Enable Set Register
0x1C20	0 c9 c12 2	RW	0x00000000	PMCNTENCLR	Count Enable Clear Register
0x1C40	0 c9 c14 1	RW	0x00000000	PMINTENSET	Interrupt Enable Set Register
0x1C60	0 c9 c14 2	RW	0x00000000	PMINTENCLR	Interrupt Enable Clear Register
0x1C80	0 c9 c12 3	RW	-	PMOVSr	Overflow Flag Status Register
0x1CA0	0 c9 c12 4	WO	-	PMSWINC	Software Increment Register
0x1E00	-	RO	0x0009DF02	PMCFGR	Configuration Register
0x1E04	0 c9 c12 0	RW	0x41052000	PMCR	Control Register
0x1E08	0 c9 c14 0	RW ^a	0x00000000	PMUSERENR	User Enable Register
0x1E20	0 c9 c12 6	RO	0x003FFFFFF	PMCEID0	Common Event Identification Register 0
0x1E24	0 c9 c12 7	RO	0x00000000	PMCEID1	Common Event Identification Register 1
0x1FB0	-	WO	-	PMLAR	Lock Access Register
0x1FB4	-	RO	-	PMLSR	Lock Status Register
0x1FB8	-	RO	-	PMAUTHSTATUS	Authentication Status Register

Table 12-1 Performance monitoring instructions and APB mapping (continued)

APB interface mapping	CP15 instruction	Access	Reset	Name	Description
0x1FCC	-	RO	-	PMDEVTYPE	Device Type Register
0x1FD0-0x1FEC	-	RO	-	PMPERIPHERALID	Identification Registers
0x1FF0-0x1FFC	-	RO	-	PMCOMPONENTID	Identification Registers

a. Read only in user mode.

12.2 Performance monitoring register descriptions

This section describes the performance monitoring registers:

- *Performance Monitor Control Register*
- *Count Enable Set Register* on page 12-5
- *Count Enable Clear Register* on page 12-6
- *Overflow Flag Status Register* on page 12-7
- *Software Increment Register* on page 12-8
- *Event Counter Selection Register* on page 12-9
- *Common Event Identification Registers* on page 12-10
- *Cycle Count Register* on page 12-11
- *Event Type Select Register* on page 12-12
- *Cycle Count Filter Control Register* on page 12-14
- *Event Count Registers* on page 12-15
- *User Enable Register* on page 12-16
- *Interrupt Enable Set Register* on page 12-17
- *Interrupt Enable Clear Register* on page 12-18
- *Configuration Register* on page 12-18
- *Lock Access Register* on page 12-19
- *Lock Status Register* on page 12-20
- *Authentication Status Register* on page 12-21
- *Device Type Register* on page 12-21
- *Identification Registers* on page 12-22.

12.2.1 Performance Monitor Control Register

The PMCR characteristics are:

- Purpose** Controls operation of the:
- Performance Monitor Count Registers
 - Cycle Counter Register.
- Usage constraints** The PMCR is:
- accessible as determined by the *User Enable Register* on page 12-16
 - common to Secure and Non-secure states.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-17 on page 4-19.

Figure 12-1 shows the PMCR bit assignments.

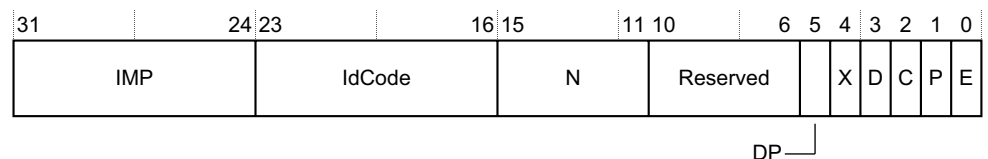


Figure 12-1 PMCR bit assignments

Table 12-2 shows the PMCR bit assignments.

Table 12-2 PMCR bit assignments

Bits	Name	Description
[31:24]	IMP	Specifies the implementor code: 0x41 = ARM. This field is read-only and write ignored.
[23:16]	IdCode	Specifies the identification code: 0x5 This field is read-only and write ignored.
[15:11]	N	Specifies the number of counters implemented: 0x2 = two counters implemented. This field is read-only and write ignored.
[10:6]	Reserved	RAZ/SBZP
[5]	DP	Disables cycle counter, PMCCNTR, when prohibited: 0 = count is enabled in prohibited regions. This is the reset value. 1 = count is disabled in prohibited regions.
[4]	X	Enables export of the events from the event bus to an external monitoring block, such as an ETM: 0 = export disabled. This is the reset value. 1 = export enabled.
[3]	D	Cycle count divider: 0 = count every clock cycle when enabled. This is the reset value. 1 = count every 64th clock cycle when enabled.
[2]	C	Cycle counter reset, write only bit, RAZ: 0 = no action 1 = reset cycle counter, PMCCNTR, to zero.
[1]	P	Performance counter reset, write only bit, RAZ: 0 = no action 1 = reset all performance counters to zero, not including PMCCNTR.
[0]	E	Enable bit: 0 = disable all counters, including PMCCNTR. This is the reset value. 1 = enable all counters including PMCCNTR.

The PMCR is always accessible in privileged modes.

To access the PMCR, use:

```
MRC p15, 0, <Rd>, c9, c12, 0 ; Read PMCR Register
MCR p15, 0, <Rd>, c9, c12, 0 ; Write PMCR Register
```

12.2.2 Count Enable Set Register

The PMCNTENSET characteristics are:

Purpose The PMCNTENSET Register:

- enables the PMCCNTR Register
- indicates which counters are enabled.

Figure 12-3 shows the PMCNTENCLR Register bit assignments.

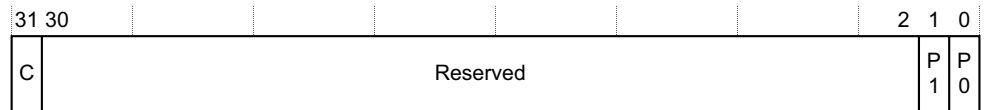


Figure 12-3 PMCNTENCLR Register bit assignments

Table 12-4 shows the PMCNTENCLR Register bit assignments.

Table 12-4 PMCNTENCLR Register bit assignments

Bits	Name	Description
[31]	C	Cycle counter enable clear: 0 = disable 1 = enable.
[30:2]	Reserved	RAZ/WI
[1]	P1	Counter 1 enable
[0]	P0	Counter 0 enable

To access the PMCNTENCLR Register, use:

MRC p15, 0, <Rd>, c9, c12, 2 ; Read PMCNTENCLR Register

MCR p15, 0, <Rd>, c9, c12, 2 ; Write PMCNTENCLR Register

When reading this register, any enable that reads as 0 indicates the counter is disabled. An enable that reads as 1 disables the counter.

When writing this register, any enable written with a value of 0 is ignored, that is, not updated. An enable written with a value of 1 clears the counter enable.

You can use the enable, EN, bit [0] of the PMCR to disable all performance counters including PMCCNTR. The PMCNTENCLR Register retains its value when the enable bit of the PMCR is clear, even though its settings are ignored.

12.2.4 Overflow Flag Status Register

The PMSOVSR characteristics are:

Purpose Holds the state of the overflow flags for:

- the Cycle Count Register.
- each of the implemented event counters.

Usage constraints The PMSOVSR is:

- accessible as determined by the *User Enable Register* on page 12-16
- common to Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-17 on page 4-19.

Figure 12-4 on page 12-8 shows the PMSOVSR bit assignments.

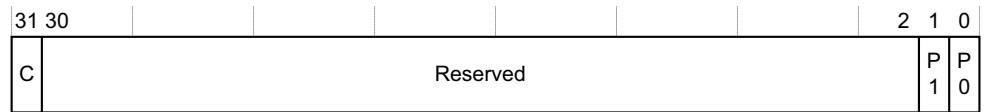


Figure 12-4 PMSOVSr bit assignments

Table 12-5 shows the PMSOVSr bit assignments.

Table 12-5 PMSOVSr Register bit assignments

Bits	Name	Description
[31]	C	Cycle counter overflow flag: 0 = disable 1 = enable.
[30:2]	Reserved	RAZ/WI
[1]	P1	Counter 1 overflow flag
[0]	P0	Counter 0 overflow flag

To access the PMSOVSr, use:

MRC p15, 0, <Rd>, c9, c12, 3 ; Read PMSOVSr Register
MCR p15, 0, <Rd>, c9, c12, 3 ; Write PMSOVSr Register

When reading this register, any overflow flag that reads as 0 indicates the counter has not overflowed. An overflow flag that reads as 1 indicates the counter has overflowed.

When writing this register, any overflow flag written with a value of 0 is ignored, that is, no change. An overflow flag written with a value of 1 clears the counter overflow flag.

12.2.5 Software Increment Register

The PMSWINC Register characteristics are:

Purpose Increments the count of a performance monitor count register.

Usage constraints The PMSWINC Register is:

- accessible as determined by the *User Enable Register* on page 12-16
- common to Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-17 on page 4-19.

Figure 12-5 shows the PMSWINC Register bit assignments.

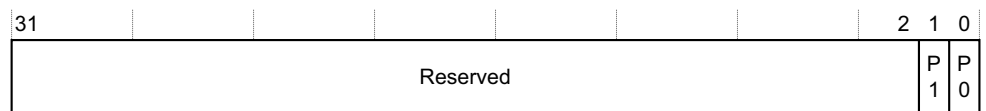


Figure 12-5 PMSWINC Register bit assignments

Values programmed in the PMSELR other than those specified in Table 12-7 on page 12-9 are Unpredictable.

To access the PMSELR, use:

MRC p15, 0, <Rd>, c9, c12, 5; Read PMSELR
MCR p15, 0, <Rd>, c9, c12, 5; Write PMSELR

12.2.7 Common Event Identification Registers

The PMCEID0 and PMCEID1 Register characteristics are:

Purpose	Define which common architectural and common micro-architectural feature events are implemented.
Usage constraints	The PMCEID0 and PMCEID1 Registers are: <ul style="list-style-type: none"> • accessible as determined by the <i>User Enable Register</i> on page 12-16 • common to Secure and Non-secure states.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-17 on page 4-19.

Table 12-8 shows the PMCEID0 Register bit assignments and which features are implemented in the Cortex-A5 MPCore processor.

Table 12-8 PMCEID0 Register bit assignments

Bit	Number	Description	Implemented?
[31:30]	0x1F-0x1E	Reserved, UNK.	-
[29]	0x1D	Bus cycle	No
[28]	0x1C	Write to translation table base	No
[27]	0x1B	Instruction speculatively executed	No
[26]	0x1A	Local memory error	No
[25]	0x19	Bus access	No
[24]	0x18	Level 2 data cache write-back	No
[23]	0x17	Level 2 data cache refill	No
[22]	0x16	Level 2 data cache access	No
[21]	0x15	Level 1 data cache write-back	Yes
[20]	0x14	Level 1 instruction cache access	Yes
[19]	0x13	Data memory access	Yes
[18]	0x12	Predictable branch speculatively executed	Yes
[17]	0x11	Cycle	Yes
[16]	0x10	Mispredicted or not predicted branch speculatively executed	Yes
[15]	0x0F	Unaligned load or store	Yes
[14]	0x0E	Procedure return	Yes
[13]	0x0D	Immediate branch	Yes

Table 12-8 PMCEID0 Register bit assignments (continued)

Bit	Number	Description	Implemented?
[12]	0x0C	Software change of the PC	Yes
[11]	0x0B	Write to CONTEXTIDR	Yes
[10]	0x0A	Exception return	Yes
[9]	0x09	Exception taken	Yes
[8]	0x08	Instruction architecturally executed	Yes
[7]	0x07	Store	Yes
[6]	0x06	Load	Yes
[5]	0x05	Level 1 data TLB refill	Yes
[4]	0x04	Level 1 data cache access	Yes
[3]	0x03	Level 1 data cache refill	Yes
[2]	0x02	Level 1 instruction TLB refill	Yes
[1]	0x01	Level 1 instruction cache refill	Yes
[0]	0x00	Software increment	Yes

The PMCEID1 Register is reserved in the architecture, and is RAZ/WI.

To access the PMCEID0 Register, use:

MRC p15, 0, <Rd>, c9, c12, 6; Read PMCEID0

To access the PMCEID1 Register, use:

MRC p15, 0, <Rd>, c9, c12, 7; Read PMCEID1

12.2.8 Cycle Count Register

The PMCCNTR characteristics are:

Purpose Counts processor clock cycles.

Usage constraints The PMCCNTR is:

- accessible as determined by the *User Enable Register* on page 12-16
- common to Secure and Non-secure states.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-17 on page 4-19.

To access the PMCCNTR, use:

MRC p15, 0, <Rd>, c9, c13, 0 ; Read PMCCNTR
MCR p15, 0, <Rd>, c9, c13, 0 ; Write PMCCNTR

The PMCCNTR must be disabled before software can write to it. Any attempt by software to write to this register when enabled is Unpredictable.

12.2.9 Event Type Select Register

The PMXEVTYPER characteristics are:

- Purpose** Selects the events that you want a Performance Monitor Count Register to count.
- Usage constraints** The PMXEVTYPER is:
- accessible as determined by the *User Enable Register* on page 12-16
 - common to Secure and Non-secure states.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-17 on page 4-19.

Figure 12-7 shows the PMXEVTYPER bit assignments.



Figure 12-7 PMXEVTYPER bit assignments

Table 12-9 shows the PMXEVTYPER bit assignments.

Table 12-9 PMXEVTYPER bit assignments

Bits	Name	Description
[31:8]	-	RAZ/SBZP
[7:0]	SEL	Specifies the event selected as described in the <i>ARM Architecture Reference Manual</i> .

To access the PMXEVTYPER, use:

MRC p15, 0, <Rd>, c9, c13, 1 ; Read PMXEVTYPER
MCR p15, 0, <Rd>, c9, c13, 1 ; Write PMXEVTYPER

Table 12-10 shows the events that are generated, with the bit position of each event on the event bus, and the numbers that the PMU uses to refer the events. Event reference numbers that are not listed are reserved. The *ARM Architecture Reference Manual* shows the range of values for predefined events that you can monitor using the PMXEVTYPER.

Table 12-10 Performance monitor events

Event	EVNTBUS bit position	Description
0x00	-	Software increment. The register is incremented only on writes to the Software Increment Register. See <i>Software Increment Register</i> on page 12-8.
0x01	[0]	Instruction fetch that causes a refill at (at least) the lowest level of instruction or unified cache. Includes the speculative linefills in the count.
0x02	[1]	Instruction fetch that causes a TLB refill at (at least) the lowest level of TLB. Includes the speculative requests in the count.
0x03	[2]	Data read or write operation that causes a refill at (at least) the lowest level of data or unified cache. Counts the number of allocations performed in the Data Cache because of a read or a write.

Table 12-10 Performance monitor events (continued)

Event	EVNTBUS bit position	Description
0x04	[3]	Data read or write operation that causes a cache access at (at least) the lowest level of data or unified cache. This includes speculative reads.
0x05	[4]	Data read or write operation that causes a TLB refill at (at least) the lowest level of TLB. This does not include micro TLB misses because of PLD, PLI, CP15 Cache operation by MVA and CP15 VA to PA operations.
0x06	[5]	Data read architecturally executed. Counts the number of data read instructions accepted by the Load Store Unit. This includes counting the speculative and aborted LDR/LDM, and the reads because of the SWP instructions.
0x07	[6]	Data write architecturally executed. Counts the number of data write instructions accepted by the Load Store Unit. This includes counting the speculative and aborted STR/STM, and the writes because of the SWP instructions.
0x08	[7]	Instruction architecturally executed.
0x09	[8]	Exception taken. Counts the number of exceptions architecturally taken.
0x0A	[9]	Exception return architecturally executed. The following instructions are reported on this event: <ul style="list-style-type: none"> • LDM {..., pc}^ • RFE • DP S pc
0x0B	[10]	Change to ContextID retired. Counts the number of instructions architecturally executed writing into the ContextID Register.
0x0C	[11]	Software change of PC.
0x0D	[12]	Immediate branch architecturally executed (taken or not taken). This includes the branches which are flushed due to a previous load/store which aborts late.
0x0E	[13]	Procedure return (other than exception returns) architecturally executed.
0x0F	[14]	Unaligned load-store.
0x10	[15]	Branch mispredicted/not predicted. Counts the number of mispredicted or not-predicted branches executed. This includes the branches which are flushed because of a previous load/store which aborts late.
0x11	-	Cycle counter.
0x12	[16]	Branches or other change in program flow that could have been predicted by the branch prediction resources of the processor. This includes the branches which are flushed because of a previous load/store which aborts late.
0x13	[17]	Data memory access.
0x14	[18]	Instruction Cache access.
0x15	[19]	Data cache eviction.
0x86	[20]	IRQ exception taken.
0x87	[21]	FIQ exception taken.
0xC0	[22]	External memory request.
0xC1	[23]	Non-cacheable external memory request.
0xC2	[24]	Linefill because of prefetch.

Table 12-10 Performance monitor events (continued)

Event	EVNTBUS bit position	Description
0xC3	[25]	Prefetch linefill dropped.
0xC4	[26]	Entering read allocate mode.
0xC5	[27]	Read allocate mode.
0xC6	[28]	Reserved.
0xC7	-	ETM Ext Out[0].
0xC8	-	ETM Ext Out[1].
0xC9	[29]	Data Write operation that stalls the pipeline because the store buffer is full.

If this unit generates an interrupt, the processor asserts the bit of the **PMUIRQ** signal associated with the core. You can route this signal to an external interrupt controller for prioritization and masking.

The absolute counts recorded might vary because of pipeline effects. This has negligible effect except in cases where the counters are enabled for a very short time.

12.2.10 Cycle Count Filter Control Register

The PMCCFILTR characteristics are:

Purpose Configures which modes and states the Performance Monitor Count Register counts in.

Usage constraints The PMCCFILTR is:

- accessible as determined by the *Event Counter Selection Register* on page 12-9
- common to Secure and Non-secure states

Configurations Available in all configurations.

Attributes See the register summary in Table 4-17 on page 4-19.

Figure 12-8 shows the PMCCFILTR bit assignments.

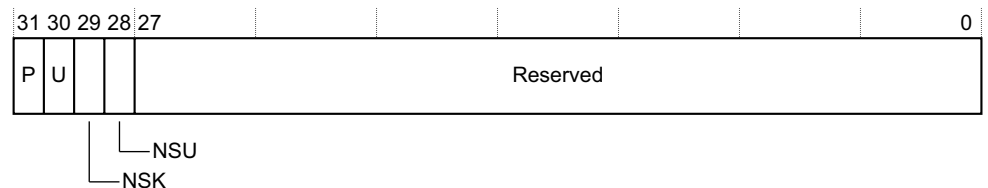


Figure 12-8 PMCCFILTR bit assignments

Table 12-11 shows the PMCCFILTR bit assignments.

Table 12-11 PMCCFILTR bit assignments

Bits	Name	Description
[31]	P	Configures the modes and states as described in the <i>ARM Architecture Reference Manual Performance Monitors v2 Supplement</i>
[30]	U	
[29]	NSK	
[28]	NSU	
[27:0]	-	UNK/SBZP

To access the PMCCFILTR, use:

MRC p15, 0, <Rd>, c9, c13, 1 ; Read PMCCFILTR
MCR p15, 0, <Rd>, c9, c13, 1 ; Write PMCCFILTR

12.2.11 Event Count Registers

The PMXEVNTR characteristics are:

Purpose Count instances of an event selected by PMXEVTPER. The bits of each PMXEVNTR contain an event count.

Usage constraints The PMXEVNTR are:

- accessible as determined by the *User Enable Register* on page 12-16
- common to Secure and Non-secure states.

Configurations There are two PMXEVNTR.

Attributes See the register summary in Table 4-17 on page 4-19.

To access the PMXEVNTR, use:

MRC p15, 0, <Rd>, c9, c13, 2 ; Read PMXEVNTR0-PMXEVNTR1 Registers
MCR p15, 0, <Rd>, c9, c13, 2 ; Write PMXEVNTR0-PMXEVNTR1 Registers

Table 12-12 shows what signal settings are required and the Secure or Non-secure state and mode that you can enable the counters.

Table 12-12 Signal settings for the PMXEVNTR

DBGEN	SPIDEN		Secure state	User mode	PMCR[5]	Performance counters enabled	PMCCNTR enabled
NIDEN	SPNIDEN	SDER.SUNIDEN					
0	-	-	-	-	b0	No	Yes
0	-	-	-	-	b1	No	No
1	-	-	No	-	-	Yes	Yes
1	1	-	Yes	-	-	Yes	Yes
1	0	-	Yes	No	b0	No	Yes
1	0	-	Yes	No	b1	No	No

Table 12-12 Signal settings for the PMXEVCNTR (continued)

DBGEN	SPIDEN		Secure state	User mode	PMCR[5]	Performance counters enabled	PMCCNTR enabled
NIDEN	SPNIDEN	SDER.SUNIDEN					
1	0	0	Yes	Yes	b0	No	Yes
1	0	0	Yes	Yes	b1	No	No
1	0	1	Yes	Yes	-	Yes	Yes

12.2.12 User Enable Register

The PMUSERENR characteristics are:

Purpose Enables user mode to have access to the Performance Monitor Registers.

Usage constraints The PMUSERENR is:

- writable only in privileged modes and readable in any processor mode.
- common to Secure and Non-secure states.

———— **Note** ————

The PMUSERENR does not provide access to the registers that control interrupt generation.

Configurations Available in all configurations.

Attributes See the register summary in Table 4-17 on page 4-19.

Figure 12-9 shows the PMUSERENR bit assignments.

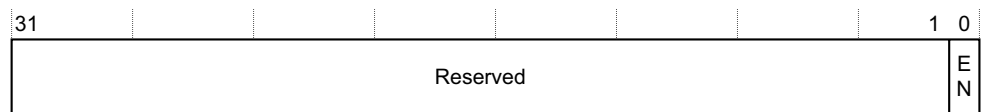


Figure 12-9 PMUSERENR bit assignments

Table 12-13 shows the PMUSERENR bit assignments.

Table 12-13 PMUSERENR bit assignments

Bits	Name	Description
[31:1]	Reserved	RAZ/SBZP
[0]	EN	User mode enable. 0 is the reset value

To access the PMUSERENR, use:

MRC p15, 0, <Rd>, c9, c14, 0 ; Read PMUSERENR
MCR p15, 0, <Rd>, c9, c14, 0 ; Write PMUSERENR

12.2.13 Interrupt Enable Set Register

The PMINTENSET characteristics are:

- Purpose** Determines if the PMCR or PMCCNTR generate an interrupt request on overflow. Interrupt requests are signaled by the Cortex-A5 MPCore processor using the **PMUIRQ** signal. See *Performance monitoring signals* on page A-14.
- Usage constraints** The PMINTENSET Register is:
- only accessible in privileged modes
 - common to Secure and Non-secure states.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 4-17 on page 4-19.

Figure 12-10 shows the PMINTENSET Register bit assignments.

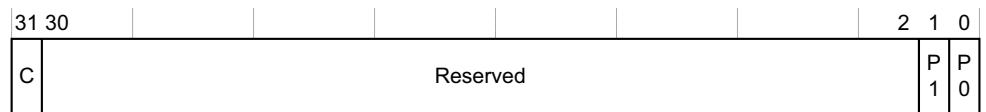


Figure 12-10 PMINTENSET Register bit assignments

Table 12-14 shows the PMINTENSET Register bit assignments.

Table 12-14 PMINTENSET Register bit assignments

Bits	Name	Description
[31]	C	PMCCNTR overflow interrupt request enable. When reading this register: 0 = interrupt request disabled 1 = interrupt request enabled. When writing to this register: 0 = no action 1 = interrupt request enabled.
[30:2]	Reserved	RAZ/WI.
[1]	P1	PMC1 overflow interrupt request enable.
[0]	P0	PMC0 overflow interrupt request enable.

To access the PMINTENSET Register, use:

MRC p15, 0, <Rd>, c9, c14, 1 ; Read PMINTENSET Register
MCR p15, 0, <Rd>, c9, c14, 1 ; Write PMINTENSET Register

Reading this register returns the current setting. Writing to this register can enable interrupts. You can disable interrupts only by writing to the INTENC Register. See *Interrupt Enable Clear Register* on page 12-18.

12.2.14 Interrupt Enable Clear Register

The PMINTENCLR Register characteristics are:

Purpose	Disables the generation of interrupt requests on overflows from the PMCR or PMCCNTR.
Usage constraints	The PMINTENCLR Register is: <ul style="list-style-type: none"> • only accessible in privileged modes • common to Secure and Non-secure state.
Configurations	Available in all configurations.
Attributes	See the register summary in Table 4-17 on page 4-19.

Figure 12-11 shows the PMINTENCLR Register bit assignments.

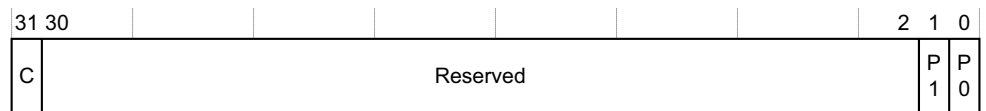


Figure 12-11 PMINTENCLR Register bit assignments

Table 12-15 shows the PMINTENCLR Register bit assignments.

Table 12-15 PMINTENCLR Register bit assignments

Bits	Name	Description
[31]	C	PMCCNTR overflow interrupt clear bit. When reading this register: 0 = interrupt request disabled 1 = interrupt request enabled. When writing to this register: 0 = no action 1 = interrupt request cleared.
[30:2]	Reserved	RAZ/WI.
[1]	P1	Clear interrupt request on PMC1 overflow.
[0]	P0	Clear interrupt request on PMC0 overflow.

To access the PMINTENCLR Register, use:

MRC p15, 0, <Rd>, c9, c14, 2 ; Read PMINTENCLR Register
MCR p15, 0, <Rd>, c9, c14, 2 ; Write PMINTENCLR Register

12.2.15 Configuration Register

The PMCFGR characteristics are:

Purpose	Contains performance monitor specific configuration data.
Usage constraints	There are no usage constraints
Configurations	Available in all configurations
Attributes	See the register summary in Table 12-1 on page 12-2.

Figure 12-12 shows the PMCFGR bit assignments.

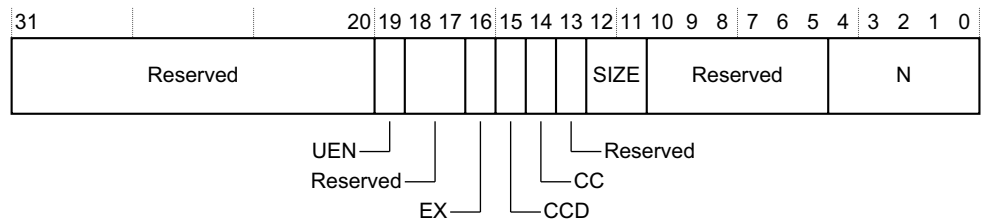


Figure 12-12 PMCFGR bit assignments

Table 12-16 shows the PMCFGR bit assignments.

Table 12-16 PMCFGR bit assignments

Bits	Name	Value	Description
[31:20]	-	RAZ	Reserved
[19]	UEN	0b1	User mode enable supported (using PMUSERENR)
[18:17]	-	RAZ	Reserved
[16]	EX	0b1	Event export supported
[15]	CCD	0b1	Cycle counter pre-scale supported
[14]	CC	0b1	Cycle counter implemented
[13]	-	RAZ	Reserved
[12:11]	SIZE	0b11	32-bit counters implemented
[10:8]	-	RAO	Reserved
[7:5]	-	RAZ	Reserved
[4:0]	N	0x02	2 event counters implemented

12.2.16 Lock Access Register

The PMLAR characteristics are:

Purpose Controls writes to the performance monitor registers. This reduces the risk of accidental corruption to the contents of the performance monitor registers. It does not prevent all accidental or malicious damage. Because the state of the register is in the debug power domain, it is not lost when the core powers down.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 12-1 on page 12-2.

Figure 12-13 on page 12-20 shows the PMLAR bit assignments.

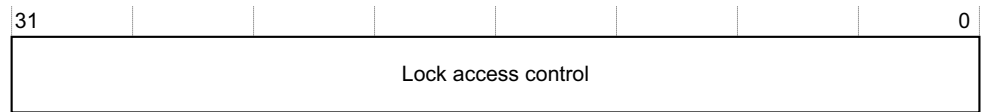


Figure 12-13 PMLAR bit assignments

Table 12-17 shows the PMLAR bit assignments.

Table 12-17 PMLAR bit assignments

Bits	Name	Description
[31:0]	Lock access control	Lock access control. To unlock the performance monitor registers, write a 0xC5ACCE55 key to this register. To lock the performance monitor registers, write any other value. Accesses to locked performance monitor registers are ignored. The reset value is 0.

When this register is written by an external debugger, APB read with **PADDRDBG31=1**, the results are Unpredictable.

12.2.17 Lock Status Register

The PMLSR characteristics are:

Purpose Returns the current lock status of the performance monitor registers.

Usage constraints There are no usage constraints.

Configurations Available in all configurations.

Attributes See the register summary in Table 12-1 on page 12-2.

Figure 12-14 shows the PMLSR bit assignments.

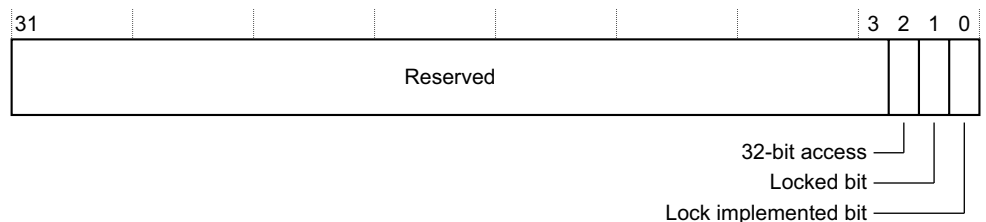


Figure 12-14 PMLSR bit assignments

Table 12-18 shows the PMLSR bit assignments.

Table 12-18 PMLSR bit assignments

Bits	Name	Description
[31:3]	Reserved	Reserved
[2]	32-bit access	Read as zero. It indicates that a 32-bit access is required to write the key to the Lock Access Register.
[1]	Locked bit	This bit indicates the status of the performance monitor registers lock. 0 = Lock clear. Performance monitor register writes are permitted. 1 = Lock set. Performance monitor register writes are ignored. The Debug reset value of this bit is 1.
[0]	Lock implemented bit	Read-as-One

When this register is read by an external debugger, APB read with **PADDRDBG31=1**, the read value is **0x0**.

12.2.18 Authentication Status Register

The PMAUTHSTATUS Register characteristics are:

- Purpose** Reads the current values of the configuration inputs that determine the performance monitor permission level.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 12-1 on page 12-2.

Figure 12-15 shows the PMAUTHSTATUS Register bit assignments.

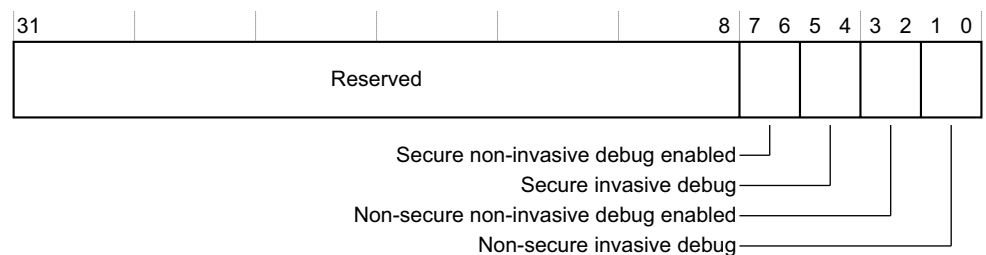


Figure 12-15 PMAUTHSTATUS Register bit assignments

Table 12-19 shows the PMAUTHSTATUS bit assignments.

Table 12-19 PMAUTHSTATUS Register bit assignments

Bits	Name	Value	Description
[31:8]	Reserved	-	RAZ
[7]	Secure noninvasive debug enabled	b1	Secure noninvasive debug enable field
[6]		(DBGEN NIDEN) && (SPIDEN SPNIDEN)	
[5:4]	Secure invasive debug	RAZ	Secure invasive debug features not implemented
[3]	Non-secure noninvasive debug enabled	b1	Non-secure noninvasive debug enable field
[2]		DBGEN NIDEN	
[1:0]	Non-secure invasive debug	RAZ	Non-secure invasive debug features not implemented

12.2.19 Device Type Register

The PMDEVTYPE Register characteristics are:

- Purpose** Indicates the type of performance monitor component.
- Usage constraints** There are no usage constraints.
- Configurations** Available in all configurations.
- Attributes** See the register summary in Table 12-1 on page 12-2.

Figure 12-16 shows the PMDEVTYPE Register bit assignments.



Figure 12-16 PMDEVTYPE Register bit assignments

Table 12-20 shows the PMDEVTYPE Register bit assignments.

Table 12-20 PMDEVTYPE Register bit assignments

Bits	Name	Description
[31:8]	Reserved	RAZ.
[7:4]	Sub type	Indicates that the sub-type of the Cortex-A5 MPCore processor is <i>core</i> . This value is 0x1.
[3:0]	Main class	Indicates that the main class of the Cortex-A5 MPCore processor is <i>performance monitor</i> . This value is 0x6.

12.2.20 Identification Registers

The Identification Registers are read-only registers that consist of the Peripheral Identification Registers and the Component Identification Registers. The Peripheral Identification Registers provide standard information required by all CoreSight components. Only bits [7:0] of each register are used.

The Component Identification Registers identify the processor as a CoreSight component. Only bits [7:0] of each register are used, the remaining bits Read-As-Zero. The values in these registers are fixed.

Table 12-21 shows the offset value, register number, and description that are associated with each Peripheral Identification Register.

Table 12-21 Peripheral Identification Registers

Offset (hex)	Register number	Description
0x1FD0	1012	Peripheral Identification Register 4
0x1FD4	1013	Reserved
0x1FD8	1014	Reserved
0x1FDC	1015	Reserved
0x1FE0	1016	Peripheral Identification Register 0
0x1FE4	1017	Peripheral Identification Register 1
0x1FE8	1018	Peripheral Identification Register 2
0x1FEC	1019	Peripheral Identification Register 3

Table 12-22 shows the Peripheral ID Register 0 bit assignments.

Table 12-22 Peripheral ID Register 0 bit assignments

Bits	Description
[31:8]	RAZ.
[7:0]	Indicates bits [7:0] of the part number for the Cortex-A5 processor. This value is 0xA5.

Table 12-23 shows the Peripheral ID Register 1 bit assignments.

Table 12-23 Peripheral ID Register 1 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates bits of the JEDEC JEP106 Identity Code. This value is 0x8.
[3:0]	Indicates bits [11:8] of the part number for the Cortex-A5 processor. This value is 0x9.

Table 12-24 shows the Peripheral ID Register 2 bit assignments.

Table 12-24 Peripheral ID Register 2 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates the revision number for the Cortex-A5 processor. This value changes based on the product major and minor revision. This value is set to 1 indicating revision r0p1.
[3]	This field is always set to 0x1.
[2:0]	Indicates bits [6:4] of the JEDEC JEP106 Identity Code. This value is set to 0x3.

Table 12-25 shows the Peripheral ID Register 3 bit assignments.

Table 12-25 Peripheral ID Register 3 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates the manufacturer revision number. This value changes based on the manufacturer metal fixes. This value is set to 0.
[3:0]	For the Cortex-A5 processor, this value is set to 0.

Table 12-26 shows the Peripheral ID Register 4 bit assignments.

Table 12-26 Peripheral ID Register 4 bit assignments

Bits	Description
[31:8]	RAZ.
[7:4]	Indicates the number of blocks occupied by the Cortex-A5 processor. This field is always set to 0.
[3:0]	Indicates the JEDEC JEP106 Continuation Code. For the Cortex-A5 processor, this value is 0x4.

Table 12-27 shows the offset value, register number, and value that are associated with each Component Identification Register.

Table 12-27 Component Identification Registers

Offset (hex)	Register number	Value	Description
0x1FF0	1020	0x0D	Component Identification Register 0
0x1FF4	1021	0x90	Component Identification Register 1
0x1FF8	1022	0x05	Component Identification Register 2
0x1FFC	1023	0xB1	Component Identification Register 3

Appendix A

Signal Descriptions

This appendix describes the Cortex-A5 MPCore signals. It contains the following section:

- *Signal descriptions* on page A-2.

A.1 Signal descriptions

The following sections describe the Cortex-A5 MPCore signals:

- *Clock and reset signals*
- *Interrupt signals* on page A-3
- *Configuration signals* on page A-3
- *Standby and wait for event signals* on page A-4
- *Power management signals* on page A-5
- *AXI master interfaces* on page A-5
- *ACP interface* on page A-10
- *Performance monitoring signals* on page A-14
- *MBIST interface* on page A-14
- *Scan test signals* on page A-14
- *External debug interface* on page A-14
- *Trace interface signals* on page A-17.

Many of the Cortex-A5 MPCore signals include a 4-bit field, [3:0], to encode up to four cores in the processor. For these signals, bit [0] represents core 0, bit [1] represents core 1, bit [2] represents core 2, and bit [3] represents core 3.

The external interface contains all the signals required for the maximum Cortex-A5 MPCore configuration, that is, four cores, 224 interrupts, two AXI master ports and, an ACP slave interface. Signals representing features which are not configured are unused.

A.1.1 Clock and reset signals

Table A-1 shows the clock and reset signals.

Table A-1 Clock and reset signals

Name	Type	Description
CLKIN	Input	Global clock.
nCPURESET[3:0]	Input	Processor reset per core. Resets can be asserted independently on each core. To avoid potential data corruption, the core's software must correctly clean the core before and invalidate after reset..
nDBGRESET[3:0]	Input	Processor debug logic reset per core.
L1RSTDISABLE[3:0]	Input	Disable invalidate entire data cache, instruction cache, and TLB at reset per core.
PERIPHCLK	Input	Clock for timer and Interrupt Controller.
PERIPHCLKEN	Input	Clock enable for timer and Interrupt Controller.
nPERIPHRESET	Input	Timer and interrupt controller.
nSCURESET	Input	<i>Snoop Control Unit</i> (SCU) global reset. This can only be held if reset is held on all the cores in the processor and all ACP masters have no outstanding transactions, or are being reset themselves.
WDRESETREQ[3:0]	Output	Watchdog reset request per core.
nWDRESET[3:0]	Input	Individual watchdog resets per core.

See *Clocking and resets* on page 2-11.

A.1.2 Interrupt signals

Table A-2 shows the interrupt signals.

Table A-2 Interrupt signals

Name	Type	Description
INT[223:0]	Input	Interrupt distributor interrupt lines.
nFIQ[3:0]	Input	Active-LOW fast interrupt request: 0 = activate fast interrupt 1 = do not activate fast interrupt. The processor treats the nFIQ input as level sensitive.
nIRQ[3:0]	Input	Active-LOW interrupt request: 0 = activate interrupt 1 = do not activate interrupt. The processor treats the nIRQ input as level sensitive.
nIRQOUT[3:0]	Output	Internal interrupt controller nIRQ output for each core in the processor.
nFIQOUT[3:0]	Output	Internal interrupt controller nFIQ output for each core in the processor.

A.1.3 Configuration signals

Table A-3 shows the configuration signals.

Table A-3 Configuration signals

Name	Type	Description
CFGDISABLE	Input	Disables write access to some secure Interrupt Controller registers.
CFGEND[3:0]	Input	Controls the state of EE bit in the SCTLR: 0 = EE bit is LOW 1 = EE bit is HIGH. This signal is only sampled during reset of the processor.
CLUSTERID[3:0]	Input	Value read in CPU ID field, bits [11:8], of the <i>Multiprocessor Affinity Register</i> (MPIDR)
CP15SDISABLE[3:0]	Input	Disables write access to some system control processor registers: 0 = not enabled 1 = enabled. See Table 4-1 on page 4-4.
FILTEREN	Input	For use with configurations with two master ports. Enables filtering of address ranges. This is sampled just after reset and is the startup value of the Filtering enable bit in the <i>SCU Control Register</i> on page 9-7. Changing the value after it has been sampled has no effect.
FILTEREND[31:20]	Input	Specifies the end address for address filtering. This is sampled just after reset and is the startup value of the Filtering enable bit in the <i>SCU Control Register</i> on page 9-7. Changing the value after it has been sampled has no effect. If the end address is a lower value than the start address, no memory transactions are routed to the secondary AXI master interface.
FILTERSTART[31:20]	Input	Specifies the start address for address filtering. This is sampled just after reset and is the startup value of the Filtering enable bit in the <i>SCU Control Register</i> on page 9-7. Changing the value after it has been sampled has no effect. If the end address is a lower value than the start address, no memory transactions are routed to the secondary AXI master interface.

Table A-3 Configuration signals (continued)

Name	Type	Description
PERIPHBASE[31:13]	Input	Specifies the base address for Timers, Watchdogs, Interrupt Controller, and SCU registers. This must not change unless reset is LOW. Changing the value of the signal at other times results in unpredictable behavior in the processor.
L2CPRESENT	Input	Indicates the presence of a PL310 L2 cache controller connected to the processor. The value of this signal is shown in the <i>SCU Configuration Register</i> on page 9-8.
SMPnAMP[3:0]	Output	Signals <i>Symmetric MultiProcessing</i> (SMP) mode or <i>Asymmetric MultiProcessing</i> (AMP) for each core in the processor.
TEINIT[3:0]	Input	Default exception handling state per core: 0 = ARM 1 = Thumb. It sets the SCTL.R.TE bit. This signal is only sampled during reset of the processor.
VINITHI[3:0]	Input	Controls the location of the exception vectors per core: 0 = start exception vectors at address 0x00000000 1 = start exception vectors at address 0xFFFF0000. It sets the SCTL.R.V bit. This signal is only sampled during reset of the processor.

A.1.4 Standby and wait for event signals

Table A-4 shows the standby and wait for event signals.

Table A-4 Standby and wait for event signals

Name	Type	Description
EVENTI	Input	Event input for processor wake-up from WFE state. The EVENTI signal must remain high for one CLKIN clock cycle to be visible to the cores inside the processor. See <i>Accelerator Coherency Port</i> on page 9-3 for information on how this signal is used.
EVENTO	Output	Event output. This signal is set high for one CLKIN clock cycle when the SEV instruction is executed by one of the cores in the processor. See <i>Accelerator Coherency Port</i> on page 9-3 for information on how this signal is used.
STANDBYWFI[3:0]	Output	Indicates if a core in the processor is in WFI mode: 0 = core not in standby mode 1 = core in standby mode. This is a pulse signal. An external master must latch the signal if it cannot deal with it immediately. See <i>Individual Cortex-A5 core power management</i> on page 2-13 for information on how this signal is used.
STANDBYWFE[3:0]	Output	Indicates if a core in the processor is in WFE mode: 0 = core not in wait for event mode 1 = core in wait for event mode. This is a pulse signal. An external master must latch the signal if it cannot deal with it immediately. See <i>Individual Cortex-A5 core power management</i> on page 2-13 for information on how this signal is used.

See *Communication to the Power Management Controller* on page 2-17.

A.1.5 Power management signals

Table A-5 shows the power management signals.

Table A-5 Power management signals

Name	Type	Description
SCUIDLE	Output	Indicates that the SCU is in IDLE state. This signal can be used to control clock or power-gating control signals of the modules connected to the SCU. In the case of the PL310 L2 Cache Controller, the SCUIDLE output of the Cortex-A5 MPCore processor can be connected to the STOPCLK input of the PL310 L2 Cache Controller.
CPURAMCLAMP[3:0]	Input	Enable the RAM interface clamps for each core in the processor: 0 = clamps not active 1 = clamps active.
PERIPHCLAMP[3:0]	Input	Enable the SCU, interrupt, and peripheral interface clamps for each core in the processor.
SCURAMCLAMP	Input	SCU clamp control.
PWRCTLI0[1:0]	Input	Reset value for core 0 status register [1:0].
PWRCTLI1[1:0]	Input	Reset value for core 1 status register [3:2].
PWRCTLI2[1:0]	Input	Reset value for core 2 status register [5:4].
PWRCTLI3[1:0]	Input	Reset value for core 3 status register [7:6].
PWRCTLO0[1:0]	Output	b00 = core 0 is powered on b01 = reserved b10 = core 0 can enter dormant mode b11 = core 0 can enter powered-off mode.
PWRCTLO1[1:0]	Output	Only applicable if core 1 is present. b00 = core 1 can be powered on b01 = reserved b10 = core 1 can enter dormant mode b11 = core 1 can enter powered-off mode.
PWRCTLO2[1:0]	Output	Only applicable if core 2 is present. b00 = core 2 can be powered on b01 = reserved b10 = core 2 can enter dormant mode b11 = core 2 can enter powered-off mode.
PWRCTLO3[1:0]	Output	Only applicable if core 3 is present. b00 = core 3 can be powered on b01 = reserved b10 = core 3 can enter dormant mode b11 = core 3 can enter powered-off mode.

See *Communication to the Power Management Controller* on page 2-17.

A.1.6 AXI master interfaces

The following sections describe the AXI master interface signals:

- *Write address channel signals* on page A-6
- *Write data response channel signals* on page A-8

- *Read address channel signals* on page A-8
- *Read data channel signals* on page A-9.

The Cortex-A5 MPCore processor can include one or two AXI master interfaces. *x* in the signal name represents either master 0, which is the primary AXI master, or master 1, which is the secondary AXI master.

Write address channel signals

Table A-6 shows the AXI master write address channel signals.

Table A-6 AXI master write address channel signals

Name	Type	Description
AWADDRMx[31:0]	Output	Address.
AWBURSTMx[1:0]	Output	Burst type: b00 = FIXED address burst (only from ACP) b01 = INCR incrementing burst b10 = WRAP wrapping burst b11 = Reserved.
AWCACHEMx[3:0]	Output	Cache type giving additional information about outer cacheable characteristics: b0000 = Strongly-ordered b0001 = Device b0011 = Normal, Non-Cacheable b0110 = Normal, Write-Through, no Write-Allocate b0111 = Normal, Write-Back, no Write-Allocate b1111 = Normal, Write-Back, Write-Allocate,
AWIDMx[4:0]	Output	Request ID. The ID encodes the source of the memory transaction. If AWIDMx[4:3] = 11, the source is ACP and AWIDMx[2:0] are the ACP ID. Otherwise, AWIDMx[1:0] is the core number in the processor and AWIDMx[4:2] encode the reason for the transaction: b000 = Normal, Strongly-ordered, and Device STREX operations, and the write part of Normal, Strongly-ordered, and Device SWP operations b001 = Non-shared cacheable evictions and the result of noncoherent CP15 clean operations. b010 = Strongly-ordered and Device writes that are not SWP or STREX operations. b011 = Shareable cacheable evictions b100 = writes as a result of coherent CP15 clean operations. All other values are unused. If a core in the processor is not present, or is powered off, its AXI ID is not used.
AWLENMx[3:0]	Output	Number of data transfers that can occur in each burst. Each burst can be 1-16 transfers long: b0000 = 1 data transfer b0001 = 2 data transfers b0010 = 3 data transfers b0011 = 4 data transfers . . . b1111 = 16 data transfers.

Table A-6 AXI master write address channel signals (continued)

Name	Type	Description
AWLOCKMx[1:0]	Output	Lock type: b00 = normal access b01 = exclusive access b1x = not used.
AWPROTMx[2:0]	Output	Protection type.
AWREADYMx	Input	Address ready.
AWSIZEMx[2:0]	Output	Burst size: b000 = 8-bit transfer b001 = 16-bit transfer b010 = 32-bit transfer b011 = 64-bit transfer.
AWUSERMx[6:0]	Output	[6:5] Exclusive mode: b00 = Not an eviction b01 = An eviction with dirty data b10 = Not used b11 = An eviction but the data is clean [4:0] Inner attributes: b00001 = Strongly-ordered b00010 = Device, non-shareable b00011 = Device, shareable b00110 = Non-cacheable, non-shareable b00111 = Non-cacheable, shareable b11110 = Writeback cacheable, read and write allocate, non-shareable b11111 = Writeback cacheable, read and write allocate, shareable
AWVALIDMx	Output	Address valid.

Write data channel signals

Table A-7 shows the AXI master write data channel signals.

Table A-7 AXI master write data channel signals

Name	Type	Description
WDATAMx[63:0]	Output	Write data.
WIDMx[4:0]	Output	Write ID.
WLASTMx	Output	Write last indication.
WREADYMx	Input	Write ready.
WSTRBMx[7:0]	Output	Write byte lane strobe.
WVALIDMx	Output	Write valid.

Write data response channel signals

Table A-8 shows the AXI master write data response channel signals.

Table A-8 AXI master write data response channel signals

Name	Type	Description
BIDM_x[4:0]	Input	Response ID.
BREADYM_x	Output	Response ready.
BRESPM_x[1:0]	Input	Write response.
BVALIDM_x	Input	Response valid.

Read address channel signals

Table A-9 shows the AXI master read address channel signals.

Table A-9 AXI master read address channel signals

Name	Type	Description
ARADDRM_x[31:0]	Output	Address.
ARBURSTM_x[1:0]	Output	Burst type: b00 = FIXED address burst (only from ACP) b01 = INCR incrementing burst b10 = WRAP wrapping burst b11 = Reserved.
ARCACHEM_x[3:0]	Output	Cache type giving additional information about outer cacheable characteristics: b0000 = Strongly-ordered b0001 = Device b0011 = Normal, Non-Cacheable b0110 = Normal, Write-Through, no Write-Allocate b0111 = Normal, Write-Back, no Write-Allocate b1111 = Normal, Write-Back, Write-Allocate.
ARIDM_x[4:0]	Output	Request ID. If ARIDM_x[4:3] = 11, this is an ACP access and ARIDM_x[2:0] are the received ID from ACP. Otherwise, ARIDM_x[1:0] is the core number in the processor and ARIDM_x[4:2] encode the reason for the transaction : b000 = Normal, Strongly-ordered, and Device reads b001 = pagewalk reads b010-b011 = data linefills b100 = instruction fetches (linefills or non-cacheable).
ARLENM_x[3:0]	Output	Number of data transfers that can occur in each burst. Each burst can be 1-16 transfers long: b0000 = 1 data transfer b0001 = 2 data transfers b0010 = 3 data transfers b0011 = 4 data transfers . . . b1111 = 16 data transfers.

Table A-9 AXI master read address channel signals (continued)

Name	Type	Description
ARLOCKMx[1:0]	Output	Lock type: b00 = normal access b01 = exclusive access b10 = locked access.
ARPROTMx[2:0]	Output	Protection type.
ARREADYMx	Input	Address ready.
ARSIZEMx[2:0]	Output	Burst size: b000 = 8-bit transfer b001 = 16-bit transfer b010 = 32-bit transfer b011 = 64-bit transfer.
ARUSERMx[4:0]	Output	Inner attributes: b00001 = Strongly-ordered b00010 = Device, non-shareable b00011 = Device, shareable b00110 = Non-cacheable, non-shareable b00111 = Non-cacheable, shareable b11110 = Writeback cacheable, read and write allocate, non-shareable b11111 = Writeback cacheable, read and write allocate, shareable
ARVALIDMx	Output	Address valid.

Read data channel signals

Table A-10 shows the AXI master read data signals.

Table A-10 AXI master read data signals

Name	Type	Description
RVALIDMx	Input	Read valid.
RDATAMx[63:0]	Input	Read data.
RRESPMx[1:0]	Input	Read response.
RLASTMx	Input	Read last.
RIDMx[4:0]	Input	Read ID.
RREADYMx	Output	Read ready.

AXI master clock enable signals

Table A-11 shows the AXI master clock enable signals.

Table A-11 AXI master clock enable signals

Name	Type	Description
ACLKENM0	Input	Primary master AXI bus clock enable.
ACLKENM1	Input	Secondary master AXI bus clock enable.

See *Clocking* on page 2-11.

A.1.7 ACP interface

The *Accelerator Coherency Port* (ACP) is defined as an AXI slave port. The following sections describe the ACP interface signals:

- *Write address channel signals*
- *Write data channel signals* on page A-11
- *Write data response channel signals* on page A-12
- *Read address channel signals* on page A-12
- *Read data channel signals* on page A-13
- *AXI slave clock enable signal* on page A-13.

Write address channel signals

Table A-12 shows the AXI slave write address channel signals.

Table A-12 AXI slave write address channel signals

Name	Type	Description
AWADDRS[31:0]	Input	Address.
AWBURSTS[1:0]	Input	Burst type: b00 = FIXED address burst b01 = INCR incrementing burst b10 = WRAP wrapping burst b11 = Reserved.
AWCACHES[3:0]	Input	Cache type giving additional information about cacheable characteristics.
AWIDS[2:0]	Input	Request ID.
AWLENS[3:0]	Input	Number of data transfers that can occur in each burst. Each burst can be 1-16 transfers long: b0000 = 1 data transfer b0001 = 2 data transfers b0010 = 3 data transfers b0011 = 4 data transfers . . . b1111 = 16 data transfers.

Table A-12 AXI slave write address channel signals (continued)

Name	Type	Description
AWLOCKS[1:0]	Input	Lock type: b00 = normal access b01 = exclusive access Bit [1] is unused. Tie off LOW.
AWPROTS[2:0]	Input	Protection Type.
AWREADYS	Output	Address ready.
AWSIZES[2:0]	Input	Burst size: b000 = 8-bit transfer b001 = 16-bit transfer b010 = 32-bit transfer b011 = 64-bit transfer.
AWUSERS[4:0]	Input	[4:1] inner attributes: b0000 = Strongly-ordered b0001 = Device b0011 = Normal Memory Non-Cacheable b0110 = Write-Through b0111 = Write-Back no Write Allocate b1111 = Write-Back Write Allocate [0] shared transaction.
AWVALIDS	Input	Address valid.

Write data channel signals

Table A-13 shows the AXI slave write data channel signals.

Table A-13 AXI slave write data channel signals

Name	Type	Description
WDATAS[63:0]	Input	Write data.
WIDS[2:0]	Input	Write ID.
WLASTS	Input	Write last indication.
WREADYS	Output	Write ready.
WSTRBS[7:0]	Input	Write byte lane strobe.
WVALIDS	Input	Write valid.

Write data response channel signals

Table A-14 shows the AXI slave write data response channel signals.

Table A-14 AXI slave write data response channel signals

Name	Type	Description
BIDS[2:0]	Output	Response ID.
BREADYS	Input	Response ready.
BRESPS[1:0]	Output	Write response.
BVALIDS	Output	Response valid.

Read address channel signals

Table A-15 shows the AXI slave read address channel signals.

Table A-15 AXI slave read address channel signals

Name	Type	Description
ARADDRS[31:0]	Input	Address.
ARBURSTS[1:0]	Input	Burst type: b00 = FIXED address burst b01 = INCR incrementing burst b10 = WRAP wrapping burst b11 = Reserved.
ARCACHES[3:0]	Input	Cache type giving additional information about cacheable characteristics.
ARIDS[2:0]	Input	Request ID
ARLENS[3:0]	Input	Number of data transfers that can occur in each burst. Each burst can be 1-16 transfers long: b0000 = 1 data transfer b0001 = 2 data transfers b0010 = 3 data transfers b0011 = 4 data transfers . . . b1111 = 16 data transfers.
ARLOCKS[1:0]	Input	Lock type: b00 = normal access b01 = exclusive access b10 = locked access.
ARPROTS[2:0]	Input	Protection Type.
ARREADYS	Output	Address ready.

Table A-15 AXI slave read address channel signals (continued)

Name	Type	Description
ARSIZES[2:0]	Input	Burst size: b000 = 8-bit transfer b001 = 16-bit transfer b010 = 32-bit transfer b011 = 64-bit transfer.
ARUSERS[4:0]	Input	[4:1] inner attributes: b0000 = Strongly-ordered b0001 = Device b0011 = Normal Memory Non-Cacheable b0110 = Write-Through b0111 = Write-Back no Write Allocate b1111 = Write-Back Write Allocate [0] shared transaction.
ARVALIDS	Input	Address valid.

Read data channel signals

Table A-16 shows the AXI slave read data signals.

Table A-16 AXI slave read data signals

Name	Type	Description
RVALIDS	Output	Read valid.
RDATAS[63:0]	Output	Read data.
RRESPS[1:0]	Output	Read response.
RLASTS	Output	Read last.
RIDS[2:0]	Output	Read ID.
RREADYS	Input	Read ready.

AXI slave clock enable signal

Table A-17 shows the AXI slave clock enable signal.

Table A-17 AXI slave clock enable signal

Name	Type	Description
ACLKENS	Input	ACP slave AXI bus clock enable.

See *Clocking* on page 2-11.

A.1.8 Performance monitoring signals

Table A-18 shows the performance monitoring signal.

Table A-18 Performance monitoring signals

Name	Type	Description
PMUIRQ[3:0]	Output	Performance Monitoring Unit interrupt signal.

A.1.9 MBIST interface

Table A-19 shows the MBIST interface signals.

Table A-19 MBIST interface signals

Name	Type	Description
MBISTADDR[11:0]	Input	MBIST address bus.
MBISTARRAY[8:0]	Input	MBIST arrays used for testing RAMs.
MBISTREQ	Input	MBIST test request.
MBISTWRITEEN	Input	Global write enable.
MBISTREADEN	Input	Global read enable.
MBISTBE[24:0]	Input	MBIST fine-grain write enable.
MBISTINDATA[71:0]	Input	MBIST data in.
MBISTACK	Output	MBIST test acknowledge.
MBISTOUTDATA[71:0]	Output	MBIST data out.

A.1.10 Scan test signals

Table A-20 shows the scan test signals.

Table A-20 Scan test signals

Signal	Type	Description
DFTSE	Input	Scan enable: 0 = not enabled 1 = enabled.
DFTRSTDISABLE	Input	Disable pipelined reset.

A.1.11 External debug interface

The following sections describe the external debug interface signals:

- *Authentication interface signals* on page A-15
- *APB interface signals* on page A-15
- *CTI signals* on page A-16
- *Miscellaneous debug interface signals* on page A-16.

Authentication interface signals

Table A-21 shows the authentication interface signals.

Table A-21 Authentication interface signals

Name	Type	Description
DBGEN[3:0]	Input	Invasive debug enable: 0 = not enabled 1 = enabled.
NIDEN[3:0]	Input	Noninvasive debug enable: 0 = not enabled 1 = enabled.
SPIDEN[3:0]	Input	Secure privileged invasive debug enable: 0 = not enabled 1 = enabled.
SPNIDEN[3:0]	Input	Secure privileged noninvasive debug enable: 0 = not enabled 1 = enabled.

APB interface signals

Table A-22 shows the APB interface signals.

Table A-22 APB interface signals

Name	Type	Description
PADDRDBG[14:2]	Input	Programming address. Use PADDRDBG[14:13] to select the core in the processor to access Use PADDRDBG[12] = b0 to access the debug registers, see Chapter 11 <i>Debug</i> . Use PADDRDBG[12] = b1 to access the Performance Monitoring registers, see Chapter 12 <i>Performance Monitoring Unit</i> .
PADDRDBG31	Input	APB address bus bit [31]: 0 = not an external debugger access 1 = external debugger access.
PCLKENDBG	Input	Clock enable for PCLKDBG .
PENABLEDBG	Input	Second and subsequent cycle of transfer.
PRDATADB[31:0]	Output	APB read data bus.
PREADYDBG	Output	APB slave ready. An APB slave can assert PREADY to extend a transfer.
PSELDBG	Input	Debug/performance monitoring registers select: 0 = registers not selected 1 = registers selected.
PSLVERRDBG	Output	APB slave error signal.
PWDATADB[31:0]	Input	APB write data.
PWRITEDBG	Input	APB read/write signal.

CTI signals

Table A-23 shows the CTI signals.

Table A-23 CTI signals

Name	Type	Description
DBGACK[3:0]	Output	Debug acknowledge signal.
DBGRESTART[3:0]	Input	Causes the core in the processor to exit from Debug state. It must be held HIGH until DBGRESTARTED is deasserted. 0 = not enabled 1 = enabled.
DBGRESTARTED[3:0]	Output	Used with DBGRESTART to move between Debug state and Normal state. 0 = not enabled 1 = enabled.
DBGTRIGGER[3:0]	Output	Indicates that the processor is committed to entering debug state. Active HIGH.
EDBGRQ[3:0]	Input	External debug request: 0 = no external debug request 1 = external debug request. The processor treats the EDBGRQ input as level-sensitive. The EDBGRQ input must be asserted until the processor asserts DBGACK .

Miscellaneous debug interface signals

Table A-24 shows the miscellaneous debug interface signals.

Table A-24 Miscellaneous debug signals

Name	Type	Description
COMMRX[3:0]	Output	Communications channel receive. Receive portion of Data Transfer Register full flag: 0 = empty 1 = full.
COMMTX[3:0]	Output	Communications channel transmit. Transmit portion of Data Transfer Register empty flag: 0 = full 1 = empty.
DBGNOPWRDWN[3:0]	Output	Debugger has requested the core in the processor is not powered down.
DBGSWENABLE[3:0]	Input	When HIGH only the external debug agent can modify debug registers. 0 = not enabled. This is the default. 1 = enabled.
DBGROMADDR[31:12]	Input	Specifies bits [31:12] of the ROM table physical address. If the address cannot be determined tie this signal off to zero.

Table A-24 Miscellaneous debug signals (continued)

Name	Type	Description
DBGROMADDRV	Input	Valid signal for DBGROMADDR . If the address cannot be determined tie this signal LOW.
DBGSELFADDR[31:15]	Input	Specifies bits [31:15] of the two's complement signed offset from the ROM table physical address to the physical address where the debug registers are memory-mapped. If the offset cannot be determined tie this signal off to zero.
DBGSELFADDRV	Input	Valid signal for DBGSELFADDR . If the offset cannot be determined tie this signal LOW.

See Chapter 11 *Debug*.

A.1.12 Trace interface signals

Table A-25 shows the trace interface signals. In the Type column:

- Input indicates an input from the trace interface to the processor
- Output indicates an output from the processor to the trace interface.

All these signals are in the processor clock domain, **CLKIN**. *x* in the signal name represents core 0, 1, 2, or 3 in the Cortex-A5 MPCore processor.

Table A-25 Trace interface signals

Name	Type	Description
ETMCTLx[19:0]	Output	ETM instruction control bus.
ETMIAx[31:0]	Output	ETM instruction address.
ETMDCTLx[10:0]	Output	ETM data control bus.
ETMDAx[31:0]	Output	ETM data address.
ETMDDx[31:0]	Output	ETM data write data value.
ETMCIDx[31:0]	Output	Current Context ID.
ETMWXPENDINGx	Output	Core is attempting to enter WFI state.
EVENTBUSx[29:0]	Output	Performance monitor unit output.
ETMPWUPx	Input	Power up core ETM interface.
ETMEXTOUTx[1:0]	Input	ETM external event to be monitored.

See *ETM interface* on page 2-9.

Appendix B

Revisions

This appendix describes the technical changes between released issues of this book.

Table B-1 Issue A

Change	Location	Affects
No changes, first release	-	-

Table B-2 Differences between issue A and issue B

Change	Location	Affects
Description of SCU clock gating added	<i>Processor debug and power saving modes</i> on page 2-15	r0p1
Invalidate TLB entry by VA added	<i>Invalidate TLB entry by VA</i> on page 4-10	All
Invalidate TLB entries by VA all ASID description updated	<i>Invalidate TLB entries by VA all ASID</i> on page 4-10	All
Main ID Register reset value updated	Table 4-9 on page 4-15 Table 11-16 on page 11-29	r0p1
Auxiliary Control Register reset value updated	Table 4-10 on page 4-16	All
Configuration Base Address Register description updated	<i>Configuration Base Address Register</i> on page 4-68	All
Supported AXI transfers updated	<i>Supported AXI transfers</i> on page 8-3	All
AXI user bits description updated	<i>AXI user bits</i> on page 8-4	All
AXI privilege information description updated	<i>AXI privilege information</i> on page 8-6	All

Table B-2 Differences between issue A and issue B (continued)

Change	Location	Affects
SCU Control Register updated	<i>SCU Control Register</i> on page 9-7	r0p1
Distributor Implementer Identification Register reset value updated	Table 10-1 on page 10-6	r0p1
Processor Interface Implementer Identification Register reset value updated	Table 10-20 on page 10-18	r0p1
Reset values updated for: <ul style="list-style-type: none"> • Cache Type Register • Memory Model Feature Register 3 	Table 11-16 on page 11-29	All
Peripheral ID Register 2 [7:4] description updated	Table 11-26 on page 11-35	r0p1
Peripheral ID Register 2 [7:4] description updated	Table 12-24 on page 12-23	r0p1
DFTRSTDISABLE moved to scan test signals	Table A-20 on page A-14	All

Glossary

This glossary describes some of the terms used in ARM manuals. Where terms can have several meanings, the meaning presented here is intended.

- Abort** A mechanism that indicates to a core that the value associated with a memory access is invalid. An abort can be caused by the external or internal memory system as a result of attempting to access invalid instruction or data memory. An abort is classified as either a Prefetch or Data Abort, and an internal or External Abort.
- See also* Data Abort, External Abort and Prefetch Abort.
- Abort model** An abort model is the defined behavior of an ARM processor in response to a Data Abort exception. Different abort models behave differently with regard to load and store instructions that specify base register write-back.
- Addressing modes** A mechanism, shared by many different instructions, for generating values used by the instructions. For four of the ARM addressing modes, the values generated are memory addresses (the traditional role of an addressing mode). A fifth addressing mode generates values to be used as operands by data-processing instructions.
- Advanced eXtensible Interface (AXI)** A bus protocol that supports separate address/control and data phases, unaligned data transfers using byte strobes, burst-based transactions with only start address issued, separate read and write data channels to enable low-cost DMA, ability to issue multiple outstanding addresses, out-of-order transaction completion, and easy addition of register stages to provide timing closure. The AXI protocol also includes optional extensions to cover signaling for low-power operation.
- AXI is targeted at high performance, high clock frequency system designs and includes a number of features that make it very suitable for high speed sub-micron interconnect.

Advanced High-performance Bus (AHB)

A bus protocol with a fixed pipeline between address/control and data phases. It only supports a subset of the functionality provided by the AMBA AXI protocol. The full AMBA AHB protocol specification includes a number of features that are not commonly required for master and slave IP developments and ARM Limited recommends only a subset of the protocol is usually used. This subset is defined as the AMBA AHB-Lite protocol.

See also Advanced Microcontroller Bus Architecture and AHB-Lite.

Advanced Microcontroller Bus Architecture (AMBA)

A family of protocol specifications that describe a strategy for the interconnect. AMBA is the ARM open standard for on-chip buses. It is an on-chip bus specification that describes a strategy for the interconnection and management of functional blocks that make up a *System-on-Chip* (SoC). It aids in the development of embedded processors with one or more CPUs or signal processors and multiple peripherals. AMBA complements a reusable design methodology by defining a common backbone for SoC modules.

Advanced Peripheral Bus (APB)

A simpler bus protocol than AXI and AHB. It is designed for use with ancillary or general-purpose peripherals such as timers, interrupt controllers, UARTs, and I/O ports. Connection to the main system bus is through a system-to-peripheral bus bridge that helps to reduce system power consumption.

AHB

See Advanced High-performance Bus.

AHB Access Port (AHB-AP)

An optional component of the DAP that provides an AHB interface to a SoC.

AHB-AP

See AHB Access Port.

AHB-Lite

A subset of the full AMBA AHB protocol specification. It provides all of the basic functions required by the majority of AMBA AHB slave and master designs, particularly when used with a multi-layer AMBA interconnect. In most cases, the extra facilities provided by a full AMBA AHB interface are implemented more efficiently by using an AMBA AXI protocol interface.

Aligned

A data item stored at an address that is divisible by the number of bytes that defines the data size is said to be aligned. Aligned words and halfwords have addresses that are divisible by four and two respectively. The terms word-aligned and halfword-aligned therefore stipulate addresses that are divisible by four and two respectively.

AMBA

See Advanced Microcontroller Bus Architecture.

Advanced Trace Bus (ATB)

A bus used by trace devices to share CoreSight capture resources.

APB

See Advanced Peripheral Bus.

Architecture

The organization of hardware and/or software that characterizes a processor and its attached components, and enables devices with similar characteristics to be grouped together when describing their behavior, for example, Harvard architecture, instruction set architecture, ARMv6 architecture.

ARM instruction

A word that specifies an operation for an ARM processor to perform. ARM instructions must be word-aligned.

ARM state

A processor that is executing ARM (32-bit) word-aligned instructions is operating in ARM state.

ATB

See Advanced Trace Bus.

ATB bridge

A synchronous ATB bridge provides a register slice to facilitate timing closure through the addition of a pipeline stage. It also provides a unidirectional link between two synchronous ATB domains.

An asynchronous ATB bridge provides a unidirectional link between two ATB domains with asynchronous clocks. It is intended to support connection of components with ATB ports residing in different clock domains.

ATPG

See Automatic Test Pattern Generation.

Automatic Test Pattern Generation (ATPG)

The process of automatically generating manufacturing test vectors for an ASIC design, using a specialized software tool.

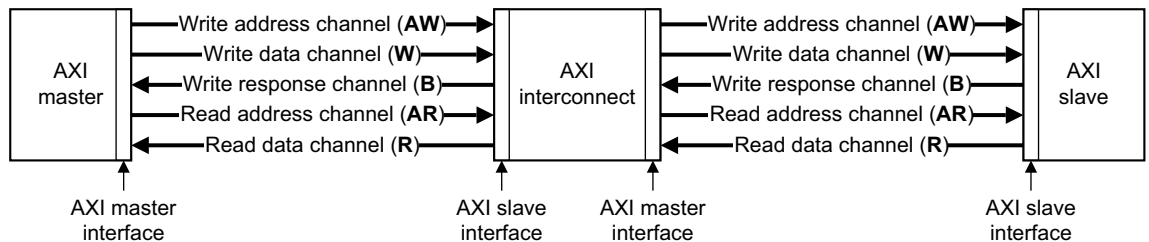
AXI

See Advanced eXtensible Interface.

AXI channel order and interfaces

The block diagram shows:

- the order that AXI channel signals are described in
- the master and slave interface conventions for AXI components.

**AXI terminology**

The following AXI terms are general. They apply to both masters and slaves:

Active read transaction

A transaction where the read address has transferred, but the last read data has not yet transferred.

Active transfer

A transfer where the **xVALID**¹ handshake has asserted, but **xREADY** has not yet asserted.

Active write transaction

A transaction where the write address or leading write data has transferred, but the write response has not yet transferred.

Completed transfer

A transfer where the **xVALID/xREADY** handshake is complete.

Payload

The non-handshake signals in a transfer.

Transaction An entire burst of transfers, comprising an address, one or more data transfers and a response transfer (writes only).

1. The letter **x** in the signal name denotes an AXI channel as follows:

AW	Write address channel.
W	Write data channel.
B	Write response channel.
AR	Read address channel.
R	Read data channel.

Transmit	An initiator driving the payload and asserting the relevant xVALID signal.
Transfer	A single exchange of information. That is, with one xVALID/xREADY handshake.

The following AXI terms are master interface attributes. To obtain optimum performance, they must be specified for all components with an AXI master interface:

Combined issuing capability

The maximum number of active transactions that a master interface can generate. This is specified instead of write or read issuing capability for master interfaces that use a combined storage for active write and read transactions.

Read ID capability

The maximum number of different **ARID** values that a master interface can generate for all active read transactions at any one time.

Read ID width

The number of bits in the **ARID** bus.

Read issuing capability

The maximum number of active read transactions that a master interface can generate.

Write ID capability

The maximum number of different **AWID** values that a master interface can generate for all active write transactions at any one time.

Write ID width

The number of bits in the **AWID** and **WID** buses.

Write interleave capability

The number of active write transactions that the master interface is capable of transmitting data for. This is counted from the earliest transaction.

Write issuing capability

The maximum number of active write transactions that a master interface can generate.

The following AXI terms are slave interface attributes. To obtain optimum performance, they must be specified for all components with an AXI slave interface

Combined acceptance capability

The maximum number of active transactions that a slave interface can accept. This is specified instead of write or read acceptance capability for slave interfaces that use a combined storage for active write and read transactions.

Read acceptance capability

The maximum number of active read transactions that a slave interface can accept.

Read data reordering depth

The number of active read transactions that a slave interface can transmit data for. This is counted from the earliest transaction.

Write acceptance capability	The maximum number of active write transactions that a slave interface can accept.
Write interleave depth	The number of active write transactions that the slave interface can receive data for. This is counted from the earliest transaction.
Banked registers	Those physical registers whose use is defined by the current processor mode. The banked registers are r8 to r14.
Base register	A register specified by a load or store instruction that is used to hold the base value for the instruction's address calculation. Depending on the instruction and its addressing mode, an offset can be added to or subtracted from the base register value to form the virtual address that is sent to memory.
Base register write-back	Updating the contents of the base register used in an instruction target address calculation so that the modified address is changed to the next higher or lower sequential address in memory. This means that it is not necessary to fetch the target address for successive instruction transfers and enables faster burst accesses to sequential memory.
Beat	Alternative word for an individual transfer within a burst. For example, an INCR4 burst comprises four beats. <i>See also</i> Burst.
BE-8	Big-endian view of memory in a byte-invariant system. <i>See also</i> BE-32, LE, Byte-invariant and Word-invariant.
BE-32	Big-endian view of memory in a word-invariant system. <i>See also</i> BE-8, LE, Byte-invariant and Word-invariant.
Big-endian	Byte ordering scheme where bytes of decreasing significance in a data word are stored at increasing addresses in memory. <i>See also</i> Little-endian and Endianness.
Big-endian memory	Memory where: <ul style="list-style-type: none"> • a byte or halfword at a word-aligned address is the most significant byte or halfword within the word at that address • a byte at a halfword-aligned address is the most significant byte within the halfword at that address. <i>See also</i> Little-endian memory.
Block address	An address that comprises a tag, an index, and a word field. The tag bits identify the way that contains the matching cache entry for a cache hit. The index bits identify the set being addressed. The word field contains the word address that can be used to identify specific words, halfwords, or bytes within the cache entry. <i>See also</i> Cache terminology diagram on the last page of this glossary.
Boundary scan chain	A boundary scan chain is made up of serially-connected devices that implement boundary scan technology using a standard JTAG TAP interface. Each device contains at least one TAP controller containing shift registers that form the chain connected between TDI and TDO , through which test data is shifted. Processors can contain several shift registers to enable you to access selected parts of the device.

Branch prediction	The process of predicting if conditional branches are to be taken or not in pipelined processors. Successfully predicting if branches are to be taken enables the processor to prefetch the instructions following a branch before the condition is fully resolved. Branch prediction can be done in software or by using custom hardware. Branch prediction techniques are categorized as static, where the prediction decision is decided before run time, and dynamic, where the prediction decision can change during program execution.
Breakpoint	A breakpoint is a mechanism provided by debuggers to identify an instruction that program execution is to be halted at. Breakpoints are inserted by the programmer to enable inspection of register contents, memory locations, variable values at fixed points in the program execution to test that the program is operating correctly. Breakpoints are removed after the program is successfully tested. <i>See also</i> Watchpoint.
Burst	A group of transfers to consecutive addresses. Because the addresses are consecutive, there is no requirement to supply an address for any of the transfers after the first one. This increases the speed that the group of transfers can occur at. Bursts over AHB buses are controlled using the HBURST signals to specify if transfers are single, four-beat, eight-beat, or 16-beat bursts, and to specify how the addresses are incremented. <i>See also</i> Beat.
Byte	An 8-bit data item.
Byte-invariant	In a byte-invariant system, the address of each byte of memory remains unchanged when switching between little-endian and big-endian operation. When a data item larger than a byte is loaded from or stored to memory, the bytes making up that data item are arranged into the correct order depending on the endianness of the memory access. The ARM architecture supports byte-invariant systems in ARMv6 and later versions. When byte-invariant support is selected, unaligned halfword and word memory accesses are also supported. Multi-word accesses are expected to be word-aligned. <i>See also</i> Word-invariant.
Byte lane strobe	An AHB signal, HBSTRB , that is used for unaligned or mixed-endian data accesses to determine the byte lanes that are active in a transfer. One bit of HBSTRB corresponds to eight bits of the data bus.
Cache	A block of on-chip or off-chip fast access memory locations, situated between the processor and main memory, used for storing and retrieving copies of often used instructions and/or data. This is done to greatly reduce the average speed of memory accesses and so to increase processor performance. <i>See also</i> Cache terminology diagram on the last page of this glossary.
Cache contention	When the number of frequently-used memory cache lines that use a particular cache set exceeds the set-associativity of the cache. In this case, main memory activity increases and performance decreases.
Cache hit	A memory access that can be processed at high speed because the instruction or data that it addresses is already held in the cache.
Cache line	The basic unit of storage in a cache. It is always a power of two words in size (usually four or eight words), and is required to be aligned to a suitable memory boundary. <i>See also</i> Cache terminology diagram on the last page of this glossary.

Cache line index	<p>The number associated with each cache line in a cache way. Within each cache way, the cache lines are numbered from 0 to (set associativity) -1.</p> <p><i>See also</i> Cache terminology diagram on the last page of this glossary.</p>
Cache lockdown	<p>To fix a line in cache memory so that it cannot be overwritten. Enables critical instructions and/or data to be loaded into the cache so that the cache lines containing them are not subsequently reallocated. This ensures that all subsequent accesses to the instructions/data concerned are cache hits, and therefore complete as quickly as possible.</p>
Cache miss	<p>A memory access that cannot be processed at high speed because the instruction/data it addresses is not in the cache and a main memory access is required.</p>
Cache set	<p>A cache set is a group of cache lines (or blocks). A set contains all the ways that can be addressed with the same index. The number of cache sets is always a power of two.</p> <p><i>See also</i> Cache terminology diagram on the last page of this glossary.</p>
Cache way	<p>A group of cache lines (or blocks). It is 2 to the power of the number of index bits in size.</p> <p><i>See also</i> Cache terminology diagram on the last page of this glossary.</p>
Clean	<p>A cache line that has not been modified while it is in the cache is said to be clean. To clean a cache is to write dirty cache entries into main memory. If a cache line is clean, it is not written on a cache miss because the next level of memory contains the same data as the cache.</p> <p><i>See also</i> Dirty.</p>
Clocks Per Instruction (CPI)	<p><i>See</i> Cycles Per Instruction (CPI).</p>
Coherency	<p><i>See</i> Memory coherency.</p>
Cold reset	<p>Also known as power-on reset. Starting the processor by turning power on. Turning power off and then back on again clears main memory and many internal settings. Some program failures can lock up the processor and require a cold reset to enable the system to be used again. In other cases, only a warm reset is required.</p> <p><i>See also</i> Warm reset.</p>
Communications channel	<p>The hardware used for communicating between the software running on the processor, and an external host, using the debug interface. When this communication is for debug purposes, it is called the Debug Comms Channel. In an ARMv7 compliant core, the communications channel includes the Data Transfer Register, some bits of the Data Status and Control Register, and the external debug interface controller, such as the DBGTAP controller in the case of the JTAG interface.</p>
Condition field	<p>A four-bit field in an instruction that specifies a condition under which the instruction can execute.</p>
Conditional execution	<p>If the condition code flags indicate that the corresponding condition is true when the instruction starts executing, it executes normally. Otherwise, the instruction does nothing.</p>
Context	<p>The environment that each process operates in for a multitasking operating system. In ARM processors, this is limited to mean the Physical Address range that it can access in memory and the associated memory access permissions.</p>
Control bits	<p>The bottom eight bits of a Program Status Register (PSR). The control bits change when an exception arises and can be altered by software only when the processor is in privileged modes.</p>

Coprocessor	A processor that supplements the main processor. It carries out additional functions that the main processor cannot perform. Usually used for floating-point math calculations, signal processing, or memory management.
Core reset	<i>See</i> Warm reset.
CPI	<i>See</i> Cycles per instruction.
CPSR	<i>See</i> Current Program Status Register
Current Program Status Register (CPSR)	The register that holds the current operating processor status.
Cycles Per instruction (CPI)	Cycles per instruction (or clocks per instruction) is a measure of the number of computer instructions that can be performed in one clock cycle. This figure of merit can be used to compare the performance of different CPUs that implement the same instruction set against each other. The lower the value, the better the performance.
Data Abort	An indication from a memory system to a core that it must halt execution of an attempted illegal memory access. A Data Abort is attempting to access invalid data memory. <i>See also</i> Abort, External Abort, and Prefetch Abort.
Data cache	A block of on-chip fast access memory locations, situated between the processor and main memory, used for storing and retrieving copies of often used data. This is done to greatly reduce the average speed of memory accesses and so to increase processor performance.
Debug Access Port (DAP)	A TAP block that acts as an AMBA (AHB or AHB-Lite) master for access to a system bus. The DAP is the term used to encompass a set of modular blocks that support system wide debug. The DAP is a modular component, intended to be extendable to support optional access to multiple systems such as memory mapped AHB and CoreSight APB through a single debug interface.
Debugger	A debugging system that includes a program, used to detect, locate, and correct software faults, together with custom hardware that supports software debugging.
Direct-mapped cache	A one-way set-associative cache. Each cache set consists of a single cache line, so cache lookup selects and checks a single cache line.
Dirty	A cache line in a write-back cache that has been modified while it is in the cache is said to be dirty. A cache line is marked as dirty by setting the dirty bit. If a cache line is dirty, it must be written to memory on a cache miss because the next level of memory contains data that has not been updated. The process of writing dirty data to main memory is called cache cleaning. <i>See also</i> Clean.
Doubleword	A 64-bit data item. The contents are taken as being an unsigned integer unless otherwise stated.
Doubleword-aligned	A data item having a memory address that is divisible by eight.
EmbeddedICE logic	An on-chip logic block that provides TAP-based debug support for ARM processor cores. It is accessed through the TAP controller on the ARM core using the JTAG interface.
EmbeddedICE-RT	The JTAG-based hardware provided by debuggable ARM processors to aid debugging in real-time.
Endianness	Byte ordering. The scheme that determines the order that successive bytes of a data word are stored in, in memory. An aspect of the system's memory mapping. <i>See also</i> Little-endian and Big-endian

Exception	A fault or error event that is considered serious enough to require that program execution is interrupted. Examples include attempting to perform an invalid memory access, external interrupts, and undefined instructions. When an exception occurs, normal program flow is interrupted and execution is resumed at the corresponding exception vector. This contains the first instruction of the interrupt handler to deal with the exception.
Exception service routine	<i>See</i> Interrupt handler.
Exception vector	<i>See</i> Interrupt vector.
Exponent	The component of a floating-point number that normally signifies the integer power to which two is raised in determining the value of the represented number.
External Abort	An indication from an external memory system to a core that it must halt execution of an attempted illegal memory access. An External Abort is caused by the external memory system as a result of attempting to access invalid memory. <i>See also</i> Abort, Data Abort and Prefetch Abort.
Flat address mapping	A system of organizing memory where each Physical Address contained within the memory space is the same as its corresponding Virtual Address.
Front of queue pointer	Pointer to the next entry to be written to in the write buffer.
Fully-associative cache	A cache that has only one cache set that consists of the entire cache. The number of cache entries is the same as the number of cache ways. <i>See also</i> Direct-mapped cache.
Halfword	A 16-bit data item.
Halting debug-mode	One of two mutually exclusive debug modes. In Halting debug-mode a <i>debug event</i> , such as a breakpoint or watchpoint, causes the processor to enter a special Debug state. In Debug state the processor is controlled through the external debug interface. This interface also provides access to all processor state, coprocessor state, memory and input/output locations. <i>See also</i> Monitor debug-mode.
High vectors	Alternative locations for exception vectors. The high vector address range is near the top of the address space, rather than at the bottom.
Host	A computer that provides data and other services to another computer. Especially, a computer providing debugging services to a target being debugged.
IEEE 754 standard	<i>IEEE Standard for Binary Floating-Point Arithmetic, ANSI/IEEE Std. 754-2008.</i> The standard that defines data types, correct operation, exception types and handling, and error bounds for floating-point systems. Most processors are built in compliance with the standard in either hardware or a combination of hardware and software.
IEM	<i>See</i> Intelligent Energy Manager.
IGN	<i>See</i> Ignore.
Ignore (IGN)	Must ignore memory writes.
Illegal instruction	An instruction that is architecturally Undefined.
Implementation-defined	Means that the behavior is not architecturally defined, but must be defined and documented by individual implementations.

Implementation-specific	Means that the behavior is not architecturally defined, and does not have to be documented by individual implementations. Used when there are a number of implementation options available and the option chosen does not affect software compatibility.
Index	<i>See</i> Cache index.
Index register	A register specified in some load or store instructions. The value of this register is used as an offset to be added to or subtracted from the base register value to form the virtual address, which is sent to memory. Some addressing modes optionally enable the index register value to be shifted prior to the addition or subtraction.
Instruction cache	A block of on-chip fast access memory locations, situated between the processor and main memory, used for storing and retrieving copies of often used instructions. This is done to greatly reduce the average speed of memory accesses and so to increase processor performance.
Instruction cycle count	The number of cycles that an instruction occupies the Execute stage of the pipeline for.
Intelligent Energy Manager (IEM)	A technology that enables dynamic voltage scaling and clock frequency variation to be used to reduce power consumption in a device.
Internal scan chain	A series of registers connected together to form a path through a device, used during production testing to import test patterns into internal nodes of the device and export the resulting values.
Interrupt handler	A program that control of the processor is passed to when an interrupt occurs.
Interrupt vector	One of a number of fixed addresses in low memory, or in high memory if high vectors are configured, that contains the first instruction of the corresponding interrupt handler.
Invalidate	To mark a cache line as being not valid by clearing the valid bit. This must be done whenever the line does not contain a valid cache entry. For example, after a cache flush all lines are invalid.
Joint Test Action Group (JTAG)	The name of the organization that developed standard IEEE 1149.1. This standard defines a boundary-scan architecture used for in-circuit testing of integrated circuit devices. It is commonly known by the initials JTAG.
JTAG	<i>See</i> Joint Test Action Group.
LE	Little-endian view of memory in both byte-invariant and word-invariant systems. <i>See also</i> Byte-invariant, Word-invariant.
Line	<i>See</i> Cache line.
Little-endian	Byte ordering scheme where bytes of increasing significance in a data word are stored at increasing addresses in memory. <i>See also</i> Big-endian and Endianness.
Little-endian memory	Memory where: <ul style="list-style-type: none"> • a byte or halfword at a word-aligned address is the least significant byte or halfword within the word at that address • a byte at a halfword-aligned address is the least significant byte within the halfword at that address. <i>See also</i> Big-endian memory.

Load/store architecture	A processor architecture where data-processing operations only operate on register contents, not directly on memory contents.
Load Store Unit (LSU)	The part of a processor that handles load and store transfers.
LSU	See Load Store Unit.
Macrocell	A complex logic block with a defined interface and behavior. A typical VLSI system comprises several macrocells (such as a processor, an ETM, and a memory block) plus application-specific logic.
Memory bank	One of two or more parallel divisions of interleaved memory, usually one word wide, that enable reads and writes of multiple words at a time, rather than single words. All memory banks are addressed simultaneously and a bank enable or chip select signal determines the bank that is accessed for each transfer. Accesses to sequential word addresses cause accesses to sequential banks. This enables the delays associated with accessing a bank to occur during the access to its adjacent bank, speeding up memory transfers.
Memory coherency	A memory is coherent if the value read by a data read or instruction fetch is the value that was most recently written to that location. Memory coherency is made difficult when there are multiple possible physical locations that are involved, such as a system that has main memory, a write buffer and a cache.
Memory Management Unit (MMU)	Hardware that controls caches and access permissions to blocks of memory, and translates virtual addresses to physical addresses.
Microprocessor	See Processor.
Miss	See Cache miss.
MMU	See Memory Management Unit.
Monitor debug-mode	One of two mutually exclusive debug modes. In Monitor debug-mode the processor enables a software abort handler provided by the debug monitor or operating system debug task. When a breakpoint or watchpoint is encountered, this enables vital system interrupts to continue to be serviced while normal program execution is suspended. See also Halt mode.
PA	See Physical Address.
Power-on reset	See Cold reset.
Prefetching	In pipelined processors, the process of fetching instructions from memory to fill up the pipeline before the preceding instructions have finished executing. Prefetching an instruction does not mean that the instruction must be executed.
Prefetch Abort	An indication from a memory system to a core that it must halt execution of an attempted illegal memory access. A Prefetch Abort can be caused by the external or internal memory system as a result of attempting to access invalid instruction memory. See also Data Abort, External Abort and Abort.
Processor	A processor is the circuitry in a computer system required to process data using the computer instructions. It is an abbreviation of microprocessor. A clock source, power supplies, and main memory are also required to create a minimum complete working computer system.
Physical Address (PA)	The MMU performs a translation on <i>Modified Virtual Addresses</i> (VA) to produce the <i>Physical Address</i> (PA) that is given to AXI to perform an external access. The PA is also stored in the data cache to avoid the necessity for address translation when data is cast out of the cache.

Read	Reads are defined as memory operations that have the semantics of a load. That is, the ARM instructions LDM, LDRD, LDC, LDR, LDRT, LDRSH, LDRH, LDRSB, LDRB, LDRBT, LDREX, RFE, STREX, SWP, and SWPB, and the Thumb instructions LDM, LDR, LDRSH, LDRH, LDRSB, LDRB, and POP. Java bytecodes that are accelerated by hardware can cause a number of reads to occur, according to the state of the Java stack and the implementation of the Java hardware acceleration.
RealView ICE	A system for debugging embedded processor cores using a JTAG interface.
Region	A partition of instruction or data memory space.
Remapping	Changing the address of physical memory or devices after the application has started executing. This is typically done to enable RAM to replace ROM when the initialization has been completed.
Reserved	A field in a control register or instruction format is reserved if the field is to be defined by the implementation, or produces Unpredictable results if the contents of the field are not zero. These fields are reserved for use in future extensions of the architecture or are implementation-specific. All reserved bits not used by the implementation must be written as 0 and read as 0.
Saved Program Status Register (SPSR)	The register that holds the CPSR of the task immediately before the exception occurred that caused the switch to the current mode.
SBO	<i>See</i> Should Be One.
SBZ	<i>See</i> Should Be Zero.
SBZP	<i>See</i> Should Be Zero or Preserved.
Scan chain	A scan chain is made up of serially-connected devices that implement boundary scan technology using a standard JTAG TAP interface. Each device contains at least one TAP controller containing shift registers that form the chain connected between TDI and TDO , through which test data is shifted. Processors can contain several shift registers to enable you to access selected parts of the device.
SCREG	The currently selected scan chain number in an ARM TAP controller.
Set	<i>See</i> Cache set.
Set-associative cache	In a set-associative cache, lines can only be placed in the cache in locations that correspond to the modulo division of the memory address by the number of sets. If there are n ways in a cache, the cache is termed n -way set-associative. The set-associativity can be any number greater than or equal to 1 and is not restricted to being a power of two.
Should Be One (SBO)	Should be written as 1 (or all 1s for bit fields) by software. Writing a 0 produces Unpredictable results.
Should Be Zero (SBZ)	Should be written as 0 (or all 0s for bit fields) by software. Writing a 1 produces Unpredictable results.
Should Be Zero or Preserved (SBZP)	Should be written as 0 (or all 0s for bit fields) by software, or preserved by writing the same value back that has been previously read from the same field on the same processor.
SPSR	<i>See</i> Saved Program Status Register
Standard Delay Format (SDF)	The format of a file that contains timing information to the level of individual bits of buses and is used in SDF back-annotation. An SDF file can be generated in a number of ways, but most commonly from a delay calculator.

Synchronization primitive

The memory synchronization primitive instructions are those instructions that are used to ensure memory synchronization. That is, the LDREX, STREX, SWP, and SWPB instructions.

Tag

The upper portion of a block address used to identify a cache line within a cache. The block address from the CPU is compared with each tag in a set in parallel to determine if the corresponding line is in the cache. If it is, it is said to be a cache hit and the line can be fetched from cache. If the block address does not correspond to any of the tags, it is said to be a cache miss and the line must be fetched from the next level of memory.

See also Cache terminology diagram on the last page of this glossary.

TAP

See Test access port.

Test Access Port (TAP)

The collection of four mandatory and one optional terminals that form the input/output and control interface to a JTAG boundary-scan architecture. The mandatory terminals are **TDI**, **TDO**, **TMS**, and **TCK**. The optional terminal is **TRST**. This signal is required in ARM cores because it is used to reset the debug logic.

Thumb instruction

A halfword that specifies an operation for an ARM processor in Thumb state to perform. Thumb instructions must be halfword-aligned.

Thumb state

A processor that is executing Thumb (16-bit) halfword aligned instructions is operating in Thumb state.

TLB

See Translation Lookaside Buffer.

Translation Lookaside Buffer (TLB)

A cache of recently used page table entries that avoid the overhead of translation table walking on every memory access. Part of the Memory Management Unit.

Translation table

A table, held in memory, that contains data that defines the properties of memory areas of various fixed sizes.

Translation table walk

The process of doing a full translation table lookup. It is performed automatically by hardware.

Trap

An exceptional condition in a VFP coprocessor that has the respective exception enable bit set in the FPSCR register. The user trap handler is executed.

Undefined

Indicates an instruction that generates an Undefined instruction trap. *See the ARM Architecture Reference Manual* for more details on ARM exceptions.

UNP

See Unpredictable.

Unpredictable

For reads, the data returned when reading from this location is unpredictable. It can have any value. For writes, writing to this location causes unpredictable behavior, or an unpredictable change in device configuration. Unpredictable instructions must not halt or hang the processor, or any part of the system.

Unsupported values

Specific data values that are not processed by the VFP coprocessor hardware but bounced to the support code for completion. These data can include infinities, NaNs, subnormal values, and zeros. An implementation is free to select which of these values is supported in hardware fully or partially, or requires assistance from support code to complete the operation. Any exception resulting from processing unsupported data is trapped to user code if the corresponding exception enable bit for the exception is set.

VA

See Virtual Address.

Victim

A cache line, selected to be discarded to make room for a replacement cache line that is required as a result of a cache miss. The method used to select the victim for eviction is processor-specific. A victim is also known as a cast out.

Virtual Address (VA)	<p>The MMU uses its translation tables to translate a Virtual Address into a Physical Address. The processor executes code at the Virtual Address, possibly located elsewhere in physical memory.</p> <p><i>See also</i> Physical Address.</p>
Warm reset	<p>Also known as a core reset. Initializes the majority of the processor excluding the debug controller and debug logic. This type of reset is useful if you are using the debugging features of a processor.</p>
Watchpoint	<p>A watchpoint is a mechanism provided by debuggers to halt program execution when the data contained by a particular memory address is changed. Watchpoints are inserted by the programmer to enable inspection of register contents, memory locations, and variable values when memory is written to test that the program is operating correctly. Watchpoints are removed after the program is successfully tested.</p> <p><i>See also</i> Breakpoint.</p>
Way	<i>See</i> Cache way.
WB	<i>See</i> Write-back.
Word	A 32-bit data item.
Word-invariant	<p>In a word-invariant system, the address of each byte of memory changes when switching between little-endian and big-endian operation, in such a way that the byte with address A in one endianness has address A EOR 3 in the other endianness. As a result, each aligned word of memory always consists of the same four bytes of memory in the same order, regardless of endianness. The change of endianness occurs because of the change to the byte addresses, not because the bytes are rearranged. The ARM architecture supports word-invariant systems in ARMv3 and later versions. When word-invariant support is selected, the behavior of load or store instructions that are given unaligned addresses is instruction-specific, and is in general not the expected behavior for an unaligned access. It is recommended that word-invariant systems use the endianness that produces the required byte addresses at all times, apart possibly from very early in their reset handlers before they have set up the endianness, and that this early part of the reset handler use only aligned word memory accesses.</p> <p><i>See also</i> Byte-invariant.</p>
Write	<p>Writes are defined as operations that have the semantics of a store. That is, the ARM instructions SRS, STM, STRD, STC, STRT, STRH, STRB, STRBT, STREX, SWP, and SWPB, and the Thumb instructions STM, STR, STRH, STRB, and PUSH. Java bytecodes that are accelerated by hardware can cause a number of writes to occur, according to the state of the Java stack and the implementation of the Java hardware acceleration.</p>
Write-back (WB)	<p>In a write-back cache, data is only written to main memory when it is forced out of the cache on line replacement following a cache miss. Otherwise, writes by the processor only update the cache. Also known as copyback.</p>
Write buffer	<p>A block of high-speed memory, arranged as a FIFO buffer, between the data cache and main memory, whose purpose is to optimize stores to main memory.</p>
Write completion	<p>The memory system indicates to the processor that a write has been completed at a point in the transaction where the memory system is able to guarantee that the effect of the write is visible to all processors in the system. This is not the case if the write is associated with a memory synchronization primitive, or is to a Device or Strongly-ordered region. In these cases the memory system might only indicate completion of the write when the access has affected the state of the target, unless it is impossible to distinguish between having the effect of the write visible and having the state of target updated.</p>

This stricter requirement for some types of memory ensures that any side-effects of the memory access can be guaranteed by the processor to have taken place. You can use this to prevent the starting of a subsequent operation in the program order until the side-effects are visible.

Write-through (WT)

In a write-through cache, data is written to main memory at the same time as the cache is updated.

WT

See Write-through.

Cache terminology diagram

The diagram illustrates the following cache terminology:

- block address
- cache line
- cache set
- cache way
- index
- tag.

